Coplanar Waveguide Circuits, Components, and Systems

RAINEE N. SIMONS
NASA Glenn Research Center
Cleveland, Ohio
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To
Joy,
Renita, and
Rona
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Preface

This book is intended to provide a comprehensive coverage of the analysis and applications of coplanar waveguides to microwave circuits and antennas for graduate students in electrical engineering and for practicing engineers.

Coplanar waveguides are a type of planar transmission line used in microwave integrated circuits (MICs) as well as in monolithic microwave integrated circuits (MMICs). The unique feature of this transmission line is that it is uniplanar in construction, which implies that all of the conductors are on the same side of the substrate. This attribute simplifies manufacturing and allows fast and inexpensive characterization using on-wafer techniques.

The first few chapters of the book are devoted to the determination of the propagation parameters of conventional coplanar waveguides and their variants. The remaining chapters are devoted to discontinuities and circuit elements, transitions to other transmission media, directional couplers, hybrids and magic-T, microelectromechanical systems (MEMS) based switches and phase shifters, high-$T_c$ superconducting circuits, tunable devices using ferroelectric materials, photonic bandgap structures, and printed circuit antennas. The author includes several valuable details such as the derivation of the fundamental equations, physical explanations, and numerical examples.

The book is an outgrowth of 15 years of research conducted by the author as a member of the Communications Technology Division (CTD) at the National Aeronautics and Space Administration (NASA), Glenn Research Center (GRC) in Cleveland, Ohio. Over the past few years, interest among engineers in coplanar waveguides has increased tremendously, with some of the concepts being extensively pursued by NASA for future space programs and missions. Numerous articles exist, but there is no collective publication. Thus the decision to publish a book on coplanar waveguides appears to be appropriate.

In the course of writing this book, several persons have assisted the author and offered support. The author first expresses his appreciation to the management of CTD at GRC for providing the environment in which he worked on
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RAINEE N. SIMONS
NASA GRC
Cleveland, Ohio
A coplanar waveguide (CPW) fabricated on a dielectric substrate was first demonstrated by C. P. Wen [1] in 1969. Since that time, tremendous progress has been made in CPW based microwave integrated circuits (MICs) as well as monolithic microwave integrated circuits (MMICs) [2] to [5].

1.1 ADVANTAGES OF COPLANAR WAVEGUIDE CIRCUITS

1.1.1 Design

A conventional CPW on a dielectric substrate consists of a center strip conductor with semi-infinite ground planes on either side as shown in Figure 1.1. This structure supports a quasi-TEM mode of propagation. The CPW offers several advantages over conventional microstrip line: First, it simplifies fabrication; second, it facilitates easy shunt as well as series surface mounting of active and passive devices [6] to [10]; third, it eliminates the need for wraparound and via holes [6] and [11], and fourth, it reduces radiation loss [6]. Furthermore, the characteristic impedance is determined by the ratio of $a/b$, so size reduction is possible without limit, the only penalty being higher losses [12]. In addition, a ground plane exists between any two adjacent lines, hence cross talk effects between adjacent lines are very week [6]. As a result, CPW circuits can be made denser than conventional microstrip circuits. These, as well as several other advantages, make CPW ideally suited for MIC as well as MMIC applications.

1.1.2 Manufacturing

Major advantages gained in manufacturing are, first, CPW lends itself to the use of automatic pick-and-place and bond assembly equipments for surface-mount component placement and interconnection of components, respectively
1.1.3 Performance

The quasi-TEM mode of propagation on a CPW has low dispersion and hence offers the potential to construct wide band circuits and components. In CPW amplifier circuits, by eliminating via holes and its associated parasitic source inductance, the gain can be enhanced [15].

1.2 TYPES OF COPLANAR WAVEGUIDES

Coplanar waveguides can be broadly classified as follows:

- Conventional CPW
- Conductor backed CPW
- Micromachined CPW

In a conventional CPW, the ground planes are of semi-infinite extent on either side. However, in a practical circuit the ground planes are made of finite extent. The conductor-backed CPW has an additional ground plane at the bottom surface of the substrate. This lower ground plane not only provides mechanical support to the substrate but also acts as a heat sink for circuits with active devices. A conductor backed CPW is shown in Figure 1.2. The micromachined CPWs are of two types, namely, the microshield line [16] and the CPW suspended by a silicon dioxide membrane above a micromachined groove [17].
These lines are illustrated in Figures 1.3 and 1.4, respectively. The advantages of the microshield line are its extremely wide bandwidth, minimal dispersion and zero dielectric loss. The advantage of the later CPW is that it is compatible with commercial CMOS foundry process and hence, is capable of monolithically integrating CMOS devices and circuits.

1.3 SOFTWARE TOOLS FOR COPLANAR WAVEGUIDE CIRCUIT SIMULATION

Recently accurate models for CPW discontinuities, such as open circuits and short circuits, lumped elements, such as inductors and capacitors, and three- and four-port junctions, such as, tee- and crossjunctions, have become com-
FIGURE 1.4 Cross section of a coplanar waveguide suspended by a silicon dioxide membrane over a micromachined substrate. (From Reference [17], © IEEE 1997.)

mercially available [5], [18] to [21]. In addition electromagnetic simulation software for 2-D and 3-D structures have also become commercially available [21] to [25].

1.4 TYPICAL APPLICATIONS OF COPLANAR WAVEGUIDES

1.4.1 Amplifiers, Active Combiners, Frequency Doublers, Mixers, and Switches

The CPW amplifier circuits include millimeter-wave amplifiers [26], [27], distributed amplifiers [28], [29], cryogenically cooled amplifiers [30], cascode amplifiers [31], transimpedance amplifiers [32], dual gate HEMT amplifiers [33], and low-noise amplifiers [34]. The CPW active combiners and frequency doublers are described in [35] and [36], respectively. The CPW mixer circuits include ultra-small drop in mixers [37], beam lead diode double-balanced mixers [38], harmonic mixers [39], MMIC double-balanced mixers [40], [41] and double-balanced image rejection, MESFET mixers [42]. The CPW PIN diode SPDT switches are described in [43] and [44].

1.4.2 Microelectromechanical Systems (MEMS) Metal Membrane Capacitive Switches

The rapid progress made in the area of semiconductor wafer processing has led to the successful development of MEMS based microwave circuits. In a CPW
the conductors are located on the top surface of a substrate which makes it ideally suited for fabricating metal membrane, capacitive, shunt-type switches [45]. CPW MEMS shunt switches with good insertion loss characteristics, reasonable switching voltages, fast switching speed, and excellent linearity have recently been demonstrated [45]. These switches offer the potential to build new generation of low-loss high-linearity microwave circuits for phased array antennas and communication systems.

1.4.3 Thin Film High-Temperature Superconducting /Ferroelectric Tunable Circuits and Components

Recent advances made in the area of thin film deposition techniques, such as sputtering, laser ablation and chemical vapor deposition, and etching technologies, have resulted in the application of high temperature superconducting (HTS) materials to microwave circuits [46]. The HTS circuits have low microwave surface resistance over a wide range of frequencies. As a result signal propagation takes place along these transmission lines with negligible amount of attenuation. Furthermore the advantage of using CPW is that only one surface of the substrate needs to be coated with HTS material before patterning. Recently HTS low-pass and band-stop CPW filters have been demonstrated in [47] and [48], respectively.

In addition by incorporating ferroelectric materials such as, SrTiO₃ with HTS materials such as, YBa₂Cu₃O₇₋ₓ, low-loss, voltage-tunable MMICs with reduced length scales can be constructed [49] and [50]. These MMICs have potential applications in phased array antenna systems and frequency agile communications systems. Recently voltage tunable CPW YBa₂Cu₃O₇₋ₓ/SrTiO₃ phaseshifters, mixers and filters have been demonstrated [50].

1.4.4 Photonic Bandgap Structures

When an electromagnetic wave propagates along a conductor backed CPW considerable amount of energy leakage takes place. The energy that leaks, propagates along the transverse directions away from the line, and excites a parallel plate mode between the CPW top and bottom ground planes. The parasitic parallel plate mode is the leading cause for crosstalk between adjacent circuits. The cross talk can be suppressed by constructing a photonic bandgap lattice on the CPW top ground planes as demonstrated in [51].

1.4.5 Printed Antennas

A radiating element is constructed from a conventional CPW by widening the center strip conductor to form a rectangular or square patch [52]. This patch produces a single-lobe, linearly polarized pattern directed normal to the plane of the conductors. The advantage gained over conventional microstrip patch antenna is lower crosspolarized radiation from the feed [52]. In [53] a
conductor backed CPW with a series gap in the center strip conductor is used to couple power to a patch through an aperture in the common ground plane. This design offers the flexibility of inserting semiconductor devices in the series gap of the feed for controlling the coupling.

1.5 ORGANIZATION OF THIS BOOK

This book is organized to serve as a text for a graduate course in MICs and MMICs, as well as a reference volume for scientists and engineers in industry. Chapter 1 gives an overview of the advantages, types, and typical applications of CPW.

Chapters 2 through 5 are devoted to the basic structures such as conventional CPW, conductor backed CPW, CPW with finite-width ground planes, elevated CPW, and CPW suspended inside a conducting enclosure. Analytical expressions to compute, the effective dielectric constant and characteristic impedance of the lines are provided.

Chapter 6 discusses coplanar stripline (CPS) and its variants. Analytical expressions to compute, the effective dielectric constant and the characteristic impedance are provided.

Coupled CPWs have several applications in the design of microwave components such as, directional couplers and filters. In Chapter 7 the even-mode and odd-mode characteristics of both edge coupled as well as broadside coupled CPWs are presented.

When an electromagnetic wave propagates along a CPW it suffers attenuation due to conductor and dielectric losses. In Chapter 8 the attenuation characteristics of conventional, micromachined, and superconducting CPWs are discussed.

Discontinuities such as, open circuits and circuit elements, such as air-bridges, are an integral part of practical CPW circuits. A good understanding of their characteristics is essential for design success. Hence Chapter 9 is devoted to CPW discontinuities.

Transitions between CPW and other transmission media are essential for integrating various components and subsystems into a complete system. Chapter 10 presents transitions between CPW and the following transmission lines: microstrip, slotline, coplanar stripline, balanced stripline, and rectangular waveguide.

Coupling of power from one line to another takes place when the lines are placed in close proximity to each other. In Chapter 11 the design and construction of directional couplers are presented. These couplers can be realized using either edge coupled CPW or broadside coupled CPW. In addition the construction and design of hybrid couplers and magic-Ts are also discussed.

Finally, Chapter 12 presents several emerging applications of CPW. These applications include microelectromechanical systems (MEMS) based switches.
and phase shifters, high-temperature superconducting circuits, tunable components based on ferroelectric materials, photonic bandgap structures and printed circuit antennas.

REFERENCES


CHAPTER 2

Conventional Coplanar Waveguide

2.1 INTRODUCTION

The coplanar waveguide (CPW) proposed by C. P. Wen in 1969 consisted of a dielectric substrate with conductors on the top surface [1]. The conductors formed a center strip separated by a narrow gap from two ground planes on either side. The dimensions of the center strip, the gap, the thickness and permittivity of the dielectric substrate determined the effective dielectric constant ($\varepsilon_{\text{eff}}$), characteristic impedance ($Z_0$) and the attenuation ($\alpha$) of the line. This basic structure has become known as the conventional CPW.

In Section 2.2 closed form expressions for $\varepsilon_{\text{eff}}$ and $Z_0$ for CPW variants are presented. These expressions are derived using conformal mapping techniques. The conformal mapping technique assumes a quasi-static TEM mode of propagation along the line. Section 2.3 briefly explains iterative techniques to determine quasi-static $\varepsilon_{\text{eff}}$ and $Z_0$. The iterative methods considered are the relaxation method and the hybrid method. Section 2.4 presents a detailed analysis of CPW using the spectral domain method. In this method the frequency dependence ignored in the conformal mapping technique is taken into consideration. This section is supported by Appendixes 2A and 2B which present the steps involved in deriving the dyadic Green’s function and the time average power flow.

Sections 2.5 and 2.6 present an empirical formula for dispersion and synthesis formulas for dispersion and characteristic impedance respectively. Section 2.7 presents the characteristics of CPW with elevated or buried center strip conductor. Using these CPW structures very high $Z_0$ can be achieved. Section 2.8 presents the characteristics of CPW with ground plane or center strip conductor underpasses. Using these CPW structures very low $Z_0$ can be achieved. Section 2.9 presents the field components of conventional CPW.
Section 2.10 presents closed form expressions for $\varepsilon_{\text{eff}}$ and $Z_0$ for CPW on cylindrical surfaces. Finally, Section 2.11 presents the effect of metal thickness on $\varepsilon_{\text{eff}}$ and $Z_0$ of conventional CPW.

2.2 CONVENTIONAL COPLANAR WAVEGUIDE ON A MULTILAYER DIELECTRIC SUBSTRATE

2.2.1 Analytical Expressions Based on Quasi-static Conformal Mapping Techniques to Determine Effective Dielectric Constant and Characteristic Impedance

The cross-sectional view of a two coplanar waveguide (CPW) structures on multilayer dielectric substrates are shown in Figures 2.1(a) and (b). These two CPW structures are designated as sandwiched CPW and CPW on a double-layer substrate respectively. In these figures the CPW center strip conductor width $S$ is equal to $2a$ and the distance of separation between the two semi-infinite ground planes is $2b$. Consequently the slot width $W$ is equal to $b - a$. The two dielectric substrate thicknesses are designated as $h_1$, $h_2$ and as $h_3$, $h_4 - h_2$ in the case of sandwiched CPW and CPW on a double-layer substrate, respectively. The corresponding relative permittivities are designated as $\varepsilon_{r1}$ and $\varepsilon_{r2}$, respectively. Two metal covers that act as a shield are placed at a distance of $h_3$ and $h_4$ from the CPW conductors. The thickness of the CPW conductors is $t$.

In the analysis that follows, the CPW conductors and the dielectric substrates are assumed to have perfect conductivity and relative permittivity, respectively. Hence the structure is considered to be loss less. Further the dielectric substrate materials are considered to be isotropic.

In this section expressions for determining $\varepsilon_{\text{eff}}$ and $Z_0$ using conformal mapping techniques are presented. The assumptions made are that the conductor thickness $t$ is zero and magnetic walls are present along all the dielectric boundaries including the CPW slots. The CPW is then divided into several partial regions and the electric field is assumed to exist only in that partial region. In this manner the capacitance of each partial region is determined separately. The total capacitance is then the sum of the partial capacitances [2]. Expressions for the partial capacitances of the sandwiched CPW will be derived first and later extended to the case of CPW on a double-layer dielectric.

The total capacitance $C_{\text{cpw}}$ of the sandwiched CPW is the sum of the partial capacitances $C_1$, $C_2$, and $C_{\text{air}}$ of the three partial regions shown in Figures 2.2(a) to (c). That is,

$$C_{\text{cpw}} = C_1 + C_2 + C_{\text{air}}. \quad (2.1)$$

In this equation $C_1$ and $C_2$ are the partial capacitance of the CPW with only the lower and the upper dielectric layers, respectively. Further $C_{\text{air}}$ is the partial capacitance of the CPW in the absence of all the dielectric layers.
FIGURE 2.1 Schematic of a CPW with top and bottom metal cover: (a) Sandwiched between two dielectric substrates; (b) on a double-layer dielectric substrate.
FIGURE 2.2 Configuration for partial capacitances for a CPW sandwiched between two dielectric substrates: (a) $C_1$; (b) $C_2$; (c) $C_{air}$.
Calculation of $C_1$  The capacitance $C_1$ of the lower partial dielectric region is given by [3]

$$C_1 = 2\varepsilon_0(\varepsilon_r - 1) \frac{K(k_1)}{K(k_1')}, \quad (2.2)$$

where the modulus of the complete elliptic integrals $K(k_1)$ and $K(k_1')$ are [3]

$$k_1 = \frac{\sinh(\pi S/4h_1)}{\sinh\{[\pi(S + 2W)]/4h_1]\}, \quad (2.3)$$

$$k_1' = \sqrt{1 - k_1^2}. \quad (2.4)$$

Calculation of $C_2$  The capacitance $C_2$ of the upper partial dielectric region is given by [3]

$$C_2 = 2\varepsilon_0(\varepsilon_r - 1) \frac{K(k_2)}{K(k_2')}, \quad (2.5)$$

where

$$k_2 = \frac{\sinh(\pi S/4h_2)}{\sinh\{[\pi(S + 2W)]/4h_2]\}, \quad (2.6)$$

$$k_2' = \sqrt{1 - k_2^2}. \quad (2.7)$$

Calculation of $C_{\text{air}}$  The capacitance $C_{\text{air}}$ is given by [3]

$$C_{\text{air}} = 2\varepsilon_0 \frac{K(k_3)}{K(k_3')} + 2\varepsilon_0 \frac{K(k_4)}{K(k_4')}, \quad (2.8)$$

where

$$k_3 = \frac{\tanh(\pi S/4h_3)}{\tanh\{[\pi(S + 2W)]/4h_3]\}, \quad (2.9)$$

$$k_4 = \frac{\tanh(\pi S/4h_4)}{\tanh\{[\pi(S + 2W)]/4h_4]\}, \quad (2.10)$$

$$k_3' = \sqrt{1 - k_3^2}, \quad (2.11)$$

$$k_4' = \sqrt{1 - k_4^2}. \quad (2.12)$$

Calculation of Effective Dielectric Constant ($\varepsilon_{\text{eff}}$), Phase Velocity ($v_{\text{ph}}$), and Characteristic Impedance ($Z_0$)  Substituting Eqs. (2.2), (2.5), and (2.8) into
Eq. (2.1) gives

\[
C_{\text{CPW}} = 2\varepsilon_0(\varepsilon_{r1} - 1) \frac{K(k_1)}{K(k_1')} + 2\varepsilon_0(\varepsilon_{r2} - 1) \frac{K(k_2)}{K(k_2')} + 2\varepsilon_0 \left[ \frac{k(k_3)}{K(k_3')} + \frac{K(k_4)}{K(k_4')} \right] \\
= 2\varepsilon_0 \left[ \frac{K(k_3)}{K(k_3')} + \frac{K(k_4)}{K(k_4')} \right] \left\{ 1 + (\varepsilon_{r1} - 1) \left[ \frac{k(k_3)}{K(k_3')} + \frac{K(k_4)}{K(k_4')} \right]^{-1} + (\varepsilon_{r2} - 1) \left[ \frac{k(k_3)}{K(k_3')} + \frac{K(k_4)}{K(k_4')} \right]^{-1} \right\}.
\]

(2.13)

Under quasi-static approximation \( \varepsilon_{\text{eff}} \) is defined as [3]

\[
\varepsilon_{\text{eff}} = \frac{C_{\text{CPW}}}{C_{\text{air}}},
\]

(2.14)

Substituting Eqs. (2.8) and (2.13) into (2.14) gives

\[
\varepsilon_{\text{eff}} = 1 + q_1(\varepsilon_{r1} - 1) + q_2(\varepsilon_{r2} - 1)
\]

(2.15)

where the terms \( q_1 \) and \( q_2 \) are called the partial filling factors, and they are equal to

\[
q_1 = \frac{K(k_1)}{K(k_1')} \left[ \frac{k(k_3)}{K(k_3')} + \frac{K(k_4)}{K(k_4')} \right]^{-1},
\]

(2.16)

\[
q_2 = \frac{K(k_2)}{K(k_2')} \left[ \frac{k(k_3)}{K(k_3')} + \frac{K(k_4)}{K(k_4')} \right]^{-1}.
\]

(2.17)

Further \( v_{\text{ph}} \) and \( Z_0 \) are defined as [3]

\[
v_{\text{ph}} = \frac{c}{\sqrt{\varepsilon_{\text{eff}}}},
\]

(2.18)

\[
Z_0 = \frac{1}{C_{\text{CPW}}v_{\text{ph}}}
\]

(2.19)

where \( c \) is the velocity of light in free space. Equations (2.8), (2.14), (2.18), and (2.19) give

\[
Z_0 = \frac{1}{cC_{\text{air}}\sqrt{\varepsilon_{\text{eff}}}},
\]

(2.20a)

\[
= \frac{60\pi}{\sqrt{\varepsilon_{\text{eff}}}} \left[ \frac{k(k_3)}{K(k_3')} + \frac{K(k_4)}{K(k_4')} \right]^{-1}.
\]

(2.20b)
For the CPW on a double-layer dielectric substrate shown in Figure 2.1(b), the partial capacitances are determined from the structures illustrated in Figure 2.3(a) to (c). Since these structures resemble those in the previous example, Eqs. (2.2), (2.3), (2.8), to (2.10) are still valid. However, the only change is in the equation for the partial capacitance \( C_2 \), which is as follows [3]:

\[
C_2 = 2\varepsilon_0(\varepsilon_{r2} - \varepsilon_{r1}) \frac{K(k_2)}{K(k'_2)}. \quad (2.21)
\]

Equation (2.6) for the modulus of the elliptical integral is still valid. In a manner similar to the previous case by combining the above equations an expression for \( \varepsilon_{\text{eff}} \) is obtained which is as follows [3]:

\[
\varepsilon_{\text{eff}} = 1 + q_1(\varepsilon_{r1} - 1) + q_2(\varepsilon_{r2} - \varepsilon_{r1}). \quad (2.22)
\]

Equations (2.16) and (2.17) for the partial filling factors \( q_1 \) and \( q_2 \) are valid in this case also. Lastly Eq. (2.20) holds good for the characteristic impedance. In the sections that follow several limiting cases will be discussed and expressions for \( \varepsilon_{\text{eff}} \) and \( Z_0 \) presented.

### 2.2.2 Conventional Coplanar Waveguide on an Infinitely Thick Dielectric Substrate

This structure is schematically illustrated in Figure 2.4. In order for the equations derived earlier to be applicable, we have to set \( h_1 = \infty \), \( \varepsilon_{r2} = 1 \) and \( h_3 = h_4 = \infty \). When \( h_1 = \infty \), Eqs. (2.3) and (2.4) reduce to

\[
k_1 = k_0 = \frac{S}{S + 2W}, \quad (2.23)
\]

\[
k'_1 = k'_0. \quad (2.24)
\]

Hence Eq. (2.2) for \( C_1 \) becomes

\[
C_1 = 2\varepsilon_0(\varepsilon_{r1} - 1) \frac{K(k_0)}{K(k'_0)}. \quad (2.25)
\]

When \( \varepsilon_{r2} \) is set equal to 1 in Eq. (2.5), \( C_2 \) becomes zero, that is,

\[
C_2 = 0. \quad (2.26)
\]

Lastly, when \( h_3 = h_4 = \infty \), Eqs. (2.9) and (2.10) become

\[
k_3 = k_4 = k_0 = \frac{S}{S + 2W}. \quad (2.27)
\]
FIGURE 2.3 Configuration for partial capacitances for a CPW on a double layer dielectric substrate: (a) $C_1$, (b) $C_2$, (c) $C_{air}$.
and hence Eq. (2.8) for $C_{\text{air}}$ simplifies to

$$C_{\text{air}} = 4\varepsilon_0 \frac{K(k_0)}{K(k_0')}.$$  \hfill (2.28)

Substituting Eqs. (2.25), (2.26), and (2.28) into Eq. (2.1) gives

$$C_{\text{CPW}} = 2\varepsilon_0(\varepsilon_{r1} + 1) \frac{K(k_0)}{K(k_0')}.$$  \hfill (2.29)

Substituting Eqs. (2.28) and (2.29) into (2.14) gives

$$\varepsilon_{\text{eff}} = \frac{1 + \varepsilon_{r1}}{2}.$$  \hfill (2.30)

Substituting Eq. (2.30) into (2.18) gives

$$v_{\text{ph}} = \frac{c}{\sqrt{(1 + \varepsilon_{r1})/2}},$$  \hfill (2.31)

and Eqs. (2.19), (2.29), and (2.31) gives

$$Z_0 = \frac{30\pi}{\sqrt{(\varepsilon_{r1} + 1)/2}} \frac{K(k_0')}{K(k_0')}.$$  \hfill (2.32)

The expression for $\varepsilon_{\text{eff}}$ and $Z_0$ are identical to those given by Wen [1].
2.2.3 Conventional Coplanar Waveguide on a Dielectric Substrate of Finite Thickness

Consider the structure schematically illustrated in Figure 2.5. In this case $\varepsilon_{r2} = 1$ and $h_3 = h_4 = \infty$. Hence Eq. (2.2) gives

$$\begin{align*}
C_1 &= 2\varepsilon_0(\varepsilon_{r1} - 1) \frac{K(k_1)}{K(k'_1)},
\end{align*}$$

(2.33)

where $k_1$ and $k'_1$ are given by Eqs. (2.3) and (2.4), respectively. From Eqs. (2.5), when $\varepsilon_{r2} = 1$, we have

$$\begin{align*}
C_2 &= 0.
\end{align*}$$

(2.34)

From Eqs. (2.8) to (2.10), when $h_3 = h_4 = \infty$ we have

$$\begin{align*}
k_3 = k_4 &= k_0 = \frac{S}{S + 2W},
\end{align*}$$

(2.35)(a)

and

$$\begin{align*}
C_{\text{air}} &= 4\varepsilon_0 \frac{K(k_0)}{K(k'_0)}.
\end{align*}$$

(2.35)(b)

Substituting Eqs. (2.33) to (2.35) into Eq. (2.1) gives

$$\begin{align*}
C_{\text{CPW}} &= 2\varepsilon_0(\varepsilon_{r1} - 1) \frac{K(k_1)}{K(k'_1)} + 4\varepsilon_0 \frac{K(k_0)}{K(k'_0)}
\end{align*}$$

(2.36)
which yields from Eq. (2.14),

$$
\varepsilon_{\text{eff}} = \frac{C_{\text{CPW}}}{C_{\text{air}}} = 1 + \frac{(\varepsilon_{r1} - 1)}{2} \frac{K(k_1)}{K(k_0)} \frac{K(k'_0)}{K(k'_1)}.
$$

(2.37)

Lastly, from Eq. (2.20),

$$
Z_0 = \frac{1}{c C_{\text{air}} \sqrt{\varepsilon_{\text{eff}}}} = \frac{30\pi}{\sqrt{\varepsilon_{\text{eff}}}} \frac{K(k'_0)}{K(k_0)}
$$

(2.38)

The expression above of $\varepsilon_{\text{eff}}$ and $Z_0$ is identical to those given by [4], [5]. The computed $\varepsilon_{\text{eff}}$ and $Z_0$ are presented in Figures 2.6(a) and (b), respectively, for a CPW on an alumina substrate.

It is worth mentioning here that in a related study [6] it has been shown that when the substrate thickness is less than twice the slot width, the deviation from the results of infinite dielectric (Section 2.2.2) is about 10 to 15 percent. Hence the propagation characteristics of lines with high $Z_0$, and therefore large slot widths on thin substrates, should be determined using Eqs. (2.37) and (2.38).

In [7] the $Z_0$ computed using Eq. (2.38) and by the spectral domain method are compared. The spectral domain computations are carried out at 1 GHz to avoid the effects of frequency dispersions. Table 2.1 presents this comparison. The results demonstrate that the accuracy of the conformal mapping results is better than 1 percent for a wide range of physical dimensions and available dielectric materials.

Although the conformal mapping expressions are rigorously valid at zero frequency, they can be used for the design of GaAs MMICs at millimeter wave frequencies [7]. The upper frequency limit is determined by comparing the computed quasi-static $\varepsilon_{\text{eff}}$ and $Z_0$ with the spectral domain values and observing the frequency at which the two sets of results deviate more than a few percent. This comparison is presented later in Section 2.6.6.

### 2.2.4 Conventional Coplanar Waveguide on a Finite Thickness Dielectric Substrate and with a Top Metal Cover

An upper metal shielding is inevitably present in microwave monolithic integrated circuits (MMICs) and also in hybrid circuits when flip-chip active elements are inserted [8]. This structure is schematically illustrated in Figure 2.7. In this case, $\varepsilon_{r2} = 1$ and $h_3 = \infty$. Proceeding in a manner similar to the previous cases, $\varepsilon_{\text{eff}}$ and $Z_0$ are given by

$$
\varepsilon_{\text{eff}} = 1 + q_3 (\varepsilon_{r1} - 1),
$$

(2.39)
where

\[ q_3 = \frac{K(k_4)/K(k'_4)}{[K(k_0)/K(k'_0)] + [K(k_4)/K(k'_4)]}, \]  

(2.40)

where \( k_0, k_1, \) and \( k_4 \) are given by Eqs. (2.23), (2.3), and (2.10), respectively:

\[ Z_0 = \frac{60\pi}{\sqrt{\varepsilon_{\text{eff}}}} \cdot \frac{1}{[K(k_0)/K(k'_0)] + [K(k_4)/K(k'_4)]}. \]  

(2.41)

There equations are identical to those in [5].
TABLE 2.1  Comparison of \( Z_0(\Omega) \) of Conventional CPW with Spectral Domain Technique at 1 GHz, \( h_1 = 200 \mu m, t = 0 \)

<table>
<thead>
<tr>
<th>( a/b )</th>
<th>( b (\mu m) )</th>
<th>( \varepsilon_{r1} = 20 )</th>
<th>( \varepsilon_{r1} = 12.9 )</th>
<th>( \varepsilon_{r1} = 2.25 )</th>
<th>Spectral Domain</th>
</tr>
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<tr>
<td>50</td>
<td>54.49</td>
<td>67.95</td>
<td>140.75</td>
<td>55.76</td>
<td>68.28</td>
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<tr>
<td>170</td>
<td>57.52</td>
<td>70.29</td>
<td>142.86</td>
<td>57.52</td>
<td>70.27</td>
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<tr>
<td>0.2</td>
<td>230</td>
<td>59.00</td>
<td>72.13</td>
<td>144.83</td>
<td>59.02</td>
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<td>350</td>
<td>62.89</td>
<td>76.44</td>
<td>147.85</td>
<td>62.60</td>
</tr>
<tr>
<td>50</td>
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<td>51.47</td>
<td>106.57</td>
<td>42.22</td>
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</tr>
<tr>
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<td>53.60</td>
<td>108.47</td>
<td>43.86</td>
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</tr>
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<td>109.82</td>
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<td>26.80</td>
</tr>
<tr>
<td></td>
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<td>27.56</td>
<td>33.61</td>
<td>66.59</td>
<td>27.53</td>
</tr>
</tbody>
</table>

Source: From Reference [7], © 1992 IEEE.

FIGURE 2.7  Schematic of a CPW on a dielectric substrate of finite thickness and with a top metal cover.
2.2.5 Conventional Coplanar Waveguide Sandwiched between Two Dielectric Substrates

This structure is schematically illustrated in Figure 2.8. In this case $h_3 = h_4 = \infty$, hence Eqs. (2.9) and (2.10) simplify to

$$k_3 = k_4 = k_0 = \frac{S}{S + 2W},$$

(2.42)

and therefore

$$K(k_3) = K(k_4) = K(k_0).$$

Substituting for $K(k_3)$ and $K(k_4)$ into Eqs. (2.16) and (2.17) results in

$$q_1 = \frac{1}{2} \frac{k(k_1)}{K(k_1')} \frac{K(k_0')}{K(k_0)},$$

(2.43)

$$q_2 = \frac{1}{2} \frac{K(k_2)}{K(k_2')} \frac{K(k_0')}{K(k_0)}.$$  

(2.44)

The $C_{\text{air}}$ from Eq. (2.8) simplifies to

$$C_{\text{air}} = 4\varepsilon_0 \frac{K(k_0)}{K(k_0')}.$$  

(2.45)

Last, on substituting the expression above into Eqs. (2.15) and (2.20), we obtain

FIGURE 2.8  Schematic of a CPW sandwiched between two dielectric substrates.
2.2.6 Conventional Coplanar Waveguide on a Double-Layer Dielectric Substrate

There are three variants to this structure and the first variant is shown in Figure 2.9(a). This variant follows from Figure 2.1 by letting \( h_3 \) and \( h_4 \) equal to infinity. Under these boundary conditions, Eqs. (2.42) to (2.44) derived earlier are also valid here. An expression for \( \varepsilon_{\text{eff}} \) is obtained by substituting Eqs. (2.43) and (2.44) into Eq. (2.22), and this is as follows:

\[
\varepsilon_{\text{eff}} = 1 + \frac{(\varepsilon_{r1} - 1)}{2} \frac{K(k_1')}{K(k_0')} + \frac{(\varepsilon_{r2} - \varepsilon_{r1})}{2} \frac{K(k_2')}{K(k_0')}. \tag{2.48}
\]

This equation for \( \varepsilon_{\text{eff}} \) when substituted into Eq. (2.47) results in the \( Z_0 \) of the structure. In [9] both \( \varepsilon_{\text{eff}} \) and \( Z_0 \) are computed as a function of \( h_2 \) in the range of 5 to 50 \( \mu \text{m} \) for a CPW with \( S = 50 \mu \text{m}, W = 30 \mu \text{m}, \varepsilon_{r1} = 13, \varepsilon_{r2} = 4 \), and the thickness of the lower substrate, \( (h_1 - h_2) \) equal to 500 \( \mu \text{m} \). The computed results are shown to be in good agreement with those obtained using a full wave analysis.

The second variant is shown in Fig. 2.9(b). This structure has an infinitely thick lower dielectric substrate; that is, \( h_1 \) is equal to infinity. When \( h_1 = \infty \), the capacitance \( C_1 \) is given by Eq. (2.25). Equation (2.21) for the capacitance \( C_2 \) is also valid here. Further for \( h_3 \) and \( h_4 \) equal to infinity, the capacitance \( C_{\text{air}} \) is given by Eq. (2.28). Knowing \( C_1, C_2, \) and \( C_{\text{air}} \) allows one to derive an expression of \( \varepsilon_{\text{eff}} \) as follows:

\[
\varepsilon_{\text{eff}} = 1 + \frac{(\varepsilon_{r1} + 1)}{2} \frac{K(k_1')}{K(k_0')} + \frac{(\varepsilon_{r2} - \varepsilon_{r1})}{2} \frac{K(k_2')}{K(k_0')} \tag{2.49}
\]

The \( Z_0 \) from Eq. (2.20a) is

\[
Z_0 = \frac{30\pi}{\sqrt{\varepsilon_{\text{eff}}}} \frac{K(k_0')}{K(k_0)}. \tag{2.50}
\]

In [7] the \( Z_0 \) computed using Eq. (2.50) and by the spectral domain method are compared for a wide range of parameters. The spectral domain computations are carried out at 1 GHz to avoid the effect of frequency dispersion. Table 2.2 presents this comparison. The comparison shows that the accuracy of the conformal mapping results in better than 1 percent for wide range of physical dimensions and available dielectric materials.
FIGURE 2.9 Variants of a CPW on a double-layer dielectric substrate: (a) Open CPW on finite thickness substrates; (b) open CPW on infinitely thick support substrate: (c) covered CPW on infinitely thick support substrate.
CONVENTIONAL COPLANAR WAVEGUIDE ON A MULTILAYER DIELECTRIC SUBSTRATE

<table>
<thead>
<tr>
<th>W (μm)</th>
<th>S (μm)</th>
<th>Conformal Mapping</th>
<th>Spectral Domain</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>( \varepsilon_{r2} = 20 )</td>
<td>( \varepsilon_{r2} = 12.9 )</td>
</tr>
<tr>
<td></td>
<td></td>
<td>( \varepsilon_{r1} = 10 )</td>
<td>( \varepsilon_{r1} = 3.78 )</td>
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<td>800</td>
<td>34.42</td>
<td>44.60</td>
</tr>
</tbody>
</table>

Source: From Reference [7], © 1992 IEEE.

To demonstrate that the quasi-static TEM mode has very small dispersion, the \( \varepsilon_{\text{eff}} \) and \( Z_0 \) are computed using the spectral domain technique [10] and presented in Table 2.3 [7]. Table 2.3 shows that in the case of a CPW with slot width and strip width of 200 and 120 μm, respectively, on a 200 μm thick GaAs substrate (\( \varepsilon_r = 12.9 \)) backed by a thick quartz substrate (\( \varepsilon_r = 3.78 \)), the deviation in \( \varepsilon_{\text{eff}} \) and \( Z_0 \) at 45 GHz from its value at 1 GHz is as small as 2.08 and 2.19 percent, respectively. This frequency limit extends to 65 GHz with deviation in \( \varepsilon_{\text{eff}} \) and \( Z_0 \) of 2.23 and 0.29 percent, respectively, when the slot width is reduced from 200 to 20 μm.

To study the effect of the lower substrate on the CPW propagation characteristics, the \( Z_0 \) is computed as a function of the strip width. Figure 2.10 presents the computed characteristics [7]. In this figure the slot width is held constant, and the relative permittivity of the lower substrate is used as a parameter. It is observed that the \( Z_0 \) is less sensitive to changes in the permittivity of the supporting dielectric for relatively small values of the ratio.
TABLE 2.3 Dispersion in $Z_0$ and $\varepsilon_{\text{eff}}$ of CPW on a Double-Layer Dielectric Substrate Calculated Using Spectral Domain Technique for $\varepsilon_{\text{r1}} = 3.78$, $h_1 = \infty$, $\varepsilon_{\text{r2}} = 12.9$, $h_2 = 200\,\mu$m, $t = 0$

<table>
<thead>
<tr>
<th>$f$ (GHz)</th>
<th>$Z_0$ (\Omega)</th>
<th>$\Delta Z_0$ (percent)</th>
<th>$\varepsilon_{\text{eff}}$</th>
<th>$\Delta \varepsilon_{\text{eff}}$ (percent)</th>
<th>$Z_0$ (\Omega)</th>
<th>$\Delta Z_0$ (percent)</th>
<th>$\varepsilon_{\text{eff}}$</th>
<th>$\Delta \varepsilon_{\text{eff}}$ (percent)</th>
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<td>2.23</td>
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</table>

Source: From Reference [7], © 1992 IEEE.

FIGURE 2.10 Characteristic impedance as a function of the strip width with the slot width and the relative permittivity of the infinitely thick support substrate as parameters, $h_1 = \infty$, $\varepsilon_{\text{r2}} = 12.9$, $h_2 = 200\,\mu$m, $t = 0$. (From Reference [7], © IEEE 1992.)
$S/h_2$ and $W/h_2$. However, $Z_0$ is more sensitive for large values of $S/h_2$ and or $W/h_2$.

The third variant is shown in Fig. 2.9(c). In this case the structure has a top metal cover. The capacitances $C_1$ and $C_2$ are given by Eqs. (2.25) and (2.21), respectively. The capacitance $C_{\text{air}}$ is given by

$$C_{\text{air}} = 2\varepsilon_0 \left[ \frac{K(k_0)}{K(k'_0)} + \frac{K(k_4)}{K(k'_4)} \right].$$  \hspace{1cm} (2.51)

Knowing $C_1$, $C_2$, and $C_{\text{air}}$ an expression for $\varepsilon_{\text{eff}}$ is derived and is as follows:

$$\varepsilon_{\text{eff}} = 1 + q_1(\varepsilon_{r1} - 1) + q_2(\varepsilon_{r2} - \varepsilon_{r1}).$$  \hspace{1cm} (2.52)

The partial filling factors $q_1$ and $q_2$ are

$$q_1 = \frac{K(k_0)}{K(k'_0)} \left[ \frac{K(k_0)}{K(k'_0)} + \frac{K(k_4)}{K(k'_4)} \right]^{-1},$$  \hspace{1cm} (2.53)

$$q_2 = \frac{K(k_2)}{K(k'_2)} \left[ \frac{K(k_0)}{K(k'_0)} + \frac{K(k_4)}{K(k'_4)} \right]^{-1}.$$  \hspace{1cm} (2.54)

The $Z_0$ is

$$Z_0 = \frac{60\pi}{\sqrt{\varepsilon_{\text{eff}}}} \left[ \frac{K(k_0)}{K(k'_0)} + \frac{K(k_4)}{K(k'_4)} \right].$$  \hspace{1cm} (2.55)

The height of the shield above a certain height has negligible effect on the propagation characteristics and hence its presence can be ignored. This height is called the critical height $h_{4c}$. A reasonable theoretical definition for a theoretical critical shield height to ground plane separation $h_{4c}/b$ is the height $h_{4c}$ above which the absolute difference between the $Z_0$ of the CPW in Figs. 2.9(b) and (c) is less than 0.1 percent. Figure 2.11 shows the ratio $h_{4c}/b$ as a function of the strip width with the slot width as a parameter. As a concluding remark it is worth mentioning that in [11] the conformal mapping technique has been extended to a CPW on a three-layer dielectric substrate.

### 2.2.7 Experimental Validation

**Effective Dielectric Constant**  
Equation (2.37) for $\varepsilon_{\text{eff}}$ of a conventional CPW on a finite thickness substrate (Fig. 2.5) has been validated in [2] by comparing with the time domain reflectometer (TDR) measurements [12] made on CPW fabricated on 0.65 mm thick alumina substrate ($\varepsilon_r = 9.8$). This comparison made at 4 GHz shows that when $W/h_1$ is approximately 1.0 (thick substrate),
the error is on the order of 0.4 percent and that when \( W/h_1 \) is approximately 3.6 (thin substrate), the error is on the order of 4.5 percent [2].

**Characteristic Impedance** In order to validate Eq. (2.38), the computed \( Z_0 \) is compared in Figure 2.12 with the experimental values obtained from [13], [14] and [15]. The \( Z_0 \) is experimentally determined using a TDR [13], [15] or from scattering parameters (S-parameters) [14] measurements. It should be pointed out that Eq. (2.38) assumes that the ground planes extend to infinity and the conductor thickness is zero, but the CPW circuits in [13], [14] and [15] have finite size ground planes in the range of 0.05 in. to 0.138 in. and the conductor thickness is in the range of 1.8 to 15 \( \mu \)m. Further, as discussed earlier, the accuracy of the computed results depends on the ratios \( W/h_1 \) and \( S/(S + 2W) \). For a CPW on a thick substrate with narrow slots, \( W/h_1 \) is less than or equal to 0.5 and \( S/(S + 2W) \) is greater or equal to 0.5. The difference between the measured and the computed \( Z_0 \) is small and is less than or equal to 3.3 percent. For a CPW on a thick substrate with fairly wide slots, \( W/h_1 \) is less than or equal to 0.5 and \( S/(S + 2W) \) is in the range of 0.4 to 0.5. The difference in \( Z_0 \) increases to about 5.8 percent. Last, for a CPW on a thin substrate with very wide slots, \( W/h_1 \) is in the range of 0.5 to 2.0 and \( S/(S + 2W) \) is less than or equal to 0.4; the difference in \( Z_0 \) ranges from a few percent to as much as 11 percent.
FIGURE 2.12  Computed and measured $Z_0$ of CPW as a function of $S/(S + 2W)$: (a) $\varepsilon_r = 9.2$, $h_1 = 0.05$ in., $S = 0.05$ in.; (b) $\varepsilon_r = 9.7$, $h_1 = 0.64$ mm, $S + 2W = 1.0$ mm; (c) $\varepsilon_r = 9.6$, $h_1 = 0.025$ in., $S = 0.02$ in.
2.3 QUASITIC TEM ITERATIVE TECHNIQUES TO DETERMINE $\varepsilon_{eff}$ AND $Z_0$

Section 2.2 discussed the application of conformal mapping method to CPW and its variants. The conformal mapping method resulted in closed form equations to calculate $\varepsilon_{eff}$ and $Z_0$. The purpose of this section is to acquaint the reader with other quasi-static TEM methods, such as the relaxation method [16] and the hybrid method [17]. These methods are iterative in nature and hence is different from the conformal mapping method. They can also take into consideration nonuniform geometry and or irregular boundaries.

2.3.1 Relaxation Method

In this method the two-dimensional Laplace equation is solved along the cross section of the CPW to obtain $\varepsilon_{eff}$ and $Z_0$. This is done by expanding the Laplace equation to form a simultaneous difference equation. In the numerical model the CPW is assumed to be housed inside a metal enclosure that is held at zero potential. Further the CPW conductor thickness, which is much smaller than the substrate thickness, is assumed to be zero. The numerical model is validated by comparing the computed $Z_0$ with the experimentally measured values. The experimental CPW lines are fabricated on a dielectric substrate of relative permittivity 9.4 and thickness 0.61 mm. A TDR is used to measure the
The maximum difference between the measured and modeled $Z_0$ values is 3 percent [16].

### 2.3.2 Hybrid Method

The hybrid method combines the Galerkin finite-element method and the conformal-mapping technique. In this method, first, Wen’s [1] mapping function is adopted, which transforms the original infinite domain into a finite image domain. This mapping also overcomes the field singularity difficulty around the strip edges. The problem is then solved in this image domain by the Galerkin finite-element method.

The computed $\varepsilon_{\text{eff}}$ for conventional CPW agrees well with the conformal mapping results only for large $a/b$ ratios [17]. The computed $Z_0$ is almost the same as that provided by the conformal mapping method [17]. An interesting feature of this method is that it can provide the magnitude of the field components in the cross-section of the structure.

### 2.4 FREQUENCY-DEPENDENT TECHNIQUES FOR DISPERSION AND CHARACTERISTIC IMPEDANCE

#### 2.4.1 Spectral Domain Method

In this section the spectral domain analysis [18, 19] is presented initially for a single slot line and later extended to the case of a coupled slot line. The schematic of a single slot line on a dielectric substrate is shown in Figure 2.13(a). This structure has three regions that are defined as follows:

- Region 1 for $h_1 < y$
- Region 2 for $0 \leq y \leq h_1$
- Region 3 for $y < 0$

The structure supports a hybrid mode which can be considered as a superposition of TE and TM modes.

In a planar waveguide, the fields associated with the TM and TE modes may be derived from the scalar electric potential function $\phi(x, y)$ and from the scalar magnetic potential function $\psi(x, y)$ respectively. These functions are related to the electric vector potential function $\overline{\phi}(x, y)$ and to the magnetic vector potential function $\overline{\psi}(x, y)$ as follows:

\[
\overline{\phi}(x, y) = \phi(x, y)e^{i\gamma z} \hat{k}, \quad (2.56a)
\]
\[
\overline{\psi}(x, y) = \psi(x, y)e^{i\gamma z} \hat{k}, \quad (2.56b)
\]

where $\hat{k}$ denotes the unit vector in the $z$-direction and $\gamma$ is the propagation
constant along the longitudinal $z$-direction. In the loss less case $\gamma$ is equal to

$$\gamma = j\beta.$$  

(2.56c)

The scalar potential functions are solutions to the scalar Helmholtz equations in the three spatial regions and are as follows:

$$[\nabla^2_{xy} + (\omega^2 \mu_i \varepsilon_i + \gamma^2)]\phi_i(x, y) = 0,$$

(2.57a)

$$[\nabla^2_{xy} + (\omega^2 \mu_i \varepsilon_i + \gamma^2)]\psi_i(x, y) = 0,$$

(2.57b)

where $\nabla^2_{xy}$ denotes the two-dimensional Laplacian operator in the transverse $x$- and $y$-directions, $\omega$ is the angular frequency, $\varepsilon_i$ and $\mu_i$ are the permittivity and
permeability of the three spatial regions, respectively, and $i = 1, 2, 3$ defines the three spatial regions. Further let

$$\omega^2 \mu_i \varepsilon_i + \gamma^2 = k_i^2 - \beta^2 = k_i^2, \quad i = 1, 2, 3.$$  \hspace{1cm} (2.57c)

Using Maxwell’s equations, it is possible to show that in a source-free medium, the fields associated with the TM mode can be derived from an electric vector potential function $\vec{\phi}(x, y)$ as follows:

$$\begin{align*}
\vec{E} &= \nabla \times \vec{\phi}(x, y) \\
\vec{H} &= j\omega \varepsilon \nabla \times \vec{\phi}(x, y)
\end{align*}$$ \hspace{1cm} (2.58a)

On substituting Eq. (2.56a), we have

$$\begin{align*}
\vec{E}_{ii} &= \gamma \nabla \phi_i(x, y) \exp(\gamma z) \\
\vec{H}_{ii} &= -j\omega \varepsilon \vec{k} \times \nabla \phi_i(x, y) \exp(\gamma z) \\
E_{zi} &= k_i^2 \phi_i(x, y) \exp(\gamma z)
\end{align*}$$ \hspace{1cm} (2.58b)

where

$$\nabla_i = \frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j}$$ \hspace{1cm} (2.58c)

and $\hat{i}$ and $\hat{j}$ are unit vectors in the $x$- and $y$-directions.

Similarly the fields associated with the TE modes can be derived from a magnetic vector potential function $\vec{\psi}(x, y)$ as follows:

$$\begin{align*}
\vec{E} &= -j\omega \mu \nabla \times \vec{\psi}(x, y) \\
\vec{H} &= \nabla \times \nabla \times \vec{\psi}(x, y)
\end{align*}$$ \hspace{1cm} (2.59a)

On substitution of Eq. (2.56b), we have

$$\begin{align*}
\vec{E}_{ii} &= j\omega \mu k \times \nabla \phi_i(x, y) \exp(\gamma z) \\
\vec{H}_{ii} &= \gamma \nabla \phi_i(x, y) \exp(\gamma z) \\
H_{zi} &= k_i^2 \phi_i(x, y) \exp(\gamma z)
\end{align*}$$ \hspace{1cm} (2.59b)

Thus from Eqs. (2.58b) and (2.59b), we obtain

$$\begin{align*}
E_{xi} &= \left( \gamma \frac{\partial \phi_i(x, y)}{\partial x} - j\omega \mu_i \frac{\partial \psi_i(x, y)}{\partial y} \right) \exp(\gamma z), \hspace{1cm} (2.60a) \\
E_{yi} &= \left( \gamma \frac{\partial \phi_i(x, y)}{\partial y} + j\omega \mu_i \frac{\partial \psi_i(x, y)}{\partial x} \right) \exp(\gamma z). \hspace{1cm} (2.60b)
\end{align*}$$
\[ H_{xi} = \left( \gamma \frac{\partial \psi_i(x, y)}{\partial x} + j \omega \varepsilon_i \frac{\partial \phi_i(x, y)}{\partial y} \right) \exp(\gamma z), \]  
\[ H_{yi} = \left( \gamma \frac{\partial \psi_i(x, y)}{\partial y} - j \omega \varepsilon_i \frac{\partial \phi_i(x, y)}{\partial x} \right) \exp(\gamma z), \]

where \( i = 1, 2, 3 \) defines the three regions.

Equations (2.57a) and (2.57b) are second-order partial differential equations. A simple way to solve these equations is to transform them by an integral transform into an ordinary differential equations and then solve them analytically. The appropriate boundary conditions for Eqs. (2.57a) and (2.57b) are, first, \( \phi_i(x, y) \) as well as \( \psi_i(x, y) \) approach zero as \( x \) and or \( y \) approach \( \pm \infty \). Second, the time average power flow is finite; that is, \( \int_{-\infty}^{\infty} |\phi_i(x, y)|^2 \, dx \) or \( \int_{-\infty}^{\infty} |\psi_i(x, y)|^2 \, dx \) is bounded. Hence \( \phi_i(x, y) \) and \( \psi_i(x, y) \) are continuous, absolutely integrable, and square integrable. These are also the necessary conditions for a Fourier transform to exist. Therefore the scalar potential functions can be transformed into the Fourier domain by a Fourier transformation defined as

\[ \mathcal{F}\{\phi(x, y)\} = \tilde{\phi}(x, y) = \int_{-\infty}^{\infty} \phi(x, y) e^{j\omega x} \, dx \]  

where the transform is expressed by a tilde above the symbol. Applying the Fourier transformation above to Eqs. (2.57a) and (2.57b) and making use of the identities

\[ \mathcal{F}\left( \frac{\partial \phi_i(x, y)}{\partial x} \right) = -j \omega \tilde{\phi}_i(x, y) \]  

and

\[ \mathcal{F}\left( \frac{\partial^2 \phi_i(x, y)}{\partial x^2} \right) = -\omega^2 \tilde{\phi}_i(x, y), \]  

the following ordinary differential equations are obtained

\[ \frac{d^2}{dy^2} \tilde{\phi}_i(x, y) = \gamma_i^2 \tilde{\phi}_i(x, y), \]  

\[ \frac{d^2}{dy^2} \tilde{\psi}_i(x, y) = \gamma_i^2 \tilde{\psi}_i(x, y), \]

where

\[ \gamma_i^2 = \omega^2 - \gamma^2 - \omega^2 \mu_i \varepsilon_i = \omega^2 + \beta^2 - k_i^2. \]
The solutions to Eqs. (2.64) and (2.65) are given by [19]

\[
\begin{align*}
\tilde{\phi}_1(x, y) &= A^e(x)\exp[-\gamma_1(y - h_1)], \quad & (2.67a) \\
\tilde{\phi}_2(x, y) &= B^e(x)\sinh \gamma_2 y + C^e(x)\cosh \gamma_2 y, \quad & (2.67b) \\
\tilde{\phi}_3(x, y) &= D^e(x)\exp(\gamma_3 y), \quad & (2.67c)
\end{align*}
\]

and

\[
\begin{align*}
\tilde{\psi}_1(x, y) &= A^h(x)\exp[-\gamma_1(y - h_1)], \quad & (2.68a) \\
\tilde{\psi}_2(x, y) &= B^h(x)\sinh \gamma_2 y + C^h(x)\cosh \gamma_2 y, \quad & (2.68b) \\
\tilde{\psi}_3(x, y) &= D^h(x)\exp(\gamma_3 y), \quad & (2.68c)
\end{align*}
\]

For the slot line under consideration \( k_1 = k_3 = k_0 \) and \( k_0 < \beta < k_2 \). Hence, for small values of the transform variable \( x \), that is, \( |x| < \sqrt{k_2^2 - \beta^2} \), \( \gamma_2 \) can be less than zero. In that case the hyperbolic functions in Eqs. (2.67) and (2.68) are replaced by trigonometric functions. The eight unknown coefficients \( A^e(x) \) to \( D^h(x) \) are related to the horizontal electric- and magnetic-field components at the interfaces \( y = 0 \) and \( y = D \) by the continuity conditions, to the surface current density on the metal and the electric field in the slot at \( y = h_1 \). Mathematically this is represented as follows [19]:

At \( y = 0 \),

\[
\begin{align*}
E_{z2}(x, 0, z) &= E_{z3}(x, 0, z), \quad & (2.69a) \\
E_{x2}(x, 0, z) &= E_{x3}(x, 0, z), \quad & (2.69b) \\
H_{z2}(x, 0, z) &= H_{z3}(x, 0, z), \quad & (2.69c) \\
H_{x2}(x, 0, z) &= H_{x3}(x, 0, z). \quad & (2.69d)
\end{align*}
\]

At \( y = h_1 \),

\[
\begin{align*}
E_{z1}(x, h_1, z) &= E_{z2}(x, h_1, z), \quad & (2.70a) \\
E_{x1}(x, h_1, z) &= E_{x2}(x, h_1, z), \quad & (2.70b) \\
E_{z1}(x, h_1, z) &= \begin{cases} E_z(x)e^{i\gamma z}, & |x| < W/2 \\ 0, & \text{elsewhere} \end{cases}, \quad & (2.70c) \\
E_{x1}(x, h_1, z) &= \begin{cases} E_x(x)e^{i\gamma z}, & |x| < W/2 \\ 0, & \text{elsewhere} \end{cases}, \quad & (2.70d) \\
H_{z1}(x, h_1, z) - H_{z2}(x, h_1, z) &= \begin{cases} j_x(x)e^{i\gamma z}, & |x| > W/2 \\ 0, & \text{elsewhere} \end{cases}. \quad & (2.70e)
\end{align*}
\]
Green's function components. By inverting the matrix, a second set of coupled equations [19] are obtained in the space of complex functions of the real variable (x).

Where \( E_x(x) \) and \( E_z(x) \) are the unknown electric fields across the slot at \( y = h_1 \) and \( j_x(x) \) and \( j_z(x) \) are the unknown current density functions on the conductors at \( y = h_1 \).

If we denote the Fourier transform of the x- and z-directional electric field and current density components by [19]

\[
\begin{align*}
\tilde{E}_x(z) &= \mathcal{F}\{E_x(x)\}, \\
\tilde{E}_z(z) &= \mathcal{F}\{E_z(x)\}, \\
\tilde{j}_x(z) &= \mathcal{F}\{j_x(x)\}, \\
\tilde{j}_z(z) &= \mathcal{F}\{j_z(x)\}.
\end{align*}
\]

We obtain a set of coupled equations as derived in Appendix 2A. The set is expressed as [19]

\[
\begin{bmatrix}
M_1(x, \beta) & M_2(x, \beta) \\
M_3(x, \beta) & M_4(x, \beta)
\end{bmatrix}
\begin{bmatrix}
\tilde{j}_x(z) \\
\tilde{j}_z(z)
\end{bmatrix}
= \begin{bmatrix}
\tilde{E}_x(z) \\
\tilde{E}_z(z)
\end{bmatrix},
\]

(2.72)

where the elements of the M-matrix are the Fourier transforms of dyadic Green's function components. By inverting the M-matrix, a new matrix \( N \) and a second set of coupled equations [19] are obtained

\[
\begin{bmatrix}
N_1(x, \beta) & N_2(x, \beta) \\
N_3(x, \beta) & N_4(x, \beta)
\end{bmatrix}
\begin{bmatrix}
\tilde{E}_x(z) \\
\tilde{E}_z(z)
\end{bmatrix}
= \begin{bmatrix}
\tilde{j}_x(z) \\
\tilde{j}_z(z)
\end{bmatrix}.
\]

(2.73)

The coupled Eqs. (2.73) are further simplified if an inner product is defined on the space of complex functions of the real variable \( z \) over the domain \( -\infty < z < +\infty \) as

\[
\langle f(z), g(z) \rangle = \int_{-\infty}^{+\infty} f(z)g^*(z)dz,
\]

(2.74)

where the asterisk above the symbol denotes complex conjugate. Taking the inner product with the Fourier transform of the electric-field components yields

\[
\begin{align*}
\langle N_1(x, \beta)\tilde{E}_x(z), \tilde{E}_x(z) \rangle + \langle N_2(x, \beta)\tilde{E}_z(z), \tilde{E}_x(z) \rangle &= \langle \tilde{j}_x(z), \tilde{E}_x(z) \rangle, \\
\langle N_3(x, \beta)\tilde{E}_x(z), \tilde{E}_z(z) \rangle + \langle N_4(x, \beta)\tilde{E}_z(z), \tilde{E}_z(z) \rangle &= \langle \tilde{j}_z(z), \tilde{E}_z(z) \rangle,
\end{align*}
\]

(2.75)

Furthermore, by the assumption that the directional electric field over the domain \( x = 0 \) is zero outside the slot region, we have

\[
\langle N_1(x, \beta)\tilde{E}_x(z), \tilde{E}_x(z) \rangle + \langle N_2(x, \beta)\tilde{E}_z(z), \tilde{E}_x(z) \rangle = \langle \tilde{j}_x(z), \tilde{E}_x(z) \rangle,
\]

(2.76a)

and

\[
\langle N_3(x, \beta)\tilde{E}_x(z), \tilde{E}_z(z) \rangle + \langle N_4(x, \beta)\tilde{E}_z(z), \tilde{E}_z(z) \rangle = \langle \tilde{j}_z(z), \tilde{E}_z(z) \rangle,
\]

(2.76b)
The right-hand sides of Eq. (2.75) are zero as is evident from Parseval's theorem. For example,

\[
\langle \tilde{J}_x(x), \tilde{E}_x(x) \rangle = \int_{-\infty}^{+\infty} \tilde{J}_x(x)\tilde{E}_x(x)dx = 2\pi \int_{-\infty}^{+\infty} j_x(x)E_x(x)dx = 0
\]

because \(j_x(x) = 0\) for \(|x| < W/2\) and \(E_x(x) = 0\) for \(|x| > W/2\) from the boundary conditions (2.70). Hence the integrand \(j_x(x) E_x(x) = 0\) for any value of \(x\). Up to this point, the formulation of the problem is exact, since no approximations have been made.

The next step is to solve Eqs. (2.75a) and (2.75b) simultaneously by means of Galerkin’s method. This is accomplished by first expanding \(E_x(x)\) and \(E_z(x)\) in a set of complete basis functions as follows [19]:

\[
E_x(x) = \sum_{n=1}^{\infty} a_n e_{x_n}(x), \quad (2.76a)
\]

\[
E_z(x) = \sum_{n=1}^{\infty} b_n e_{z_n}(x). \quad (2.76b)
\]

If we restrict the analysis to a one-term approximation, \(\tilde{E}_x(x) \approx \mathcal{F}\{e_x(x)\}\) and \(\tilde{E}_z(x) \approx \mathcal{F}\{e_z(x)\}\). Then Eq. (2.75) becomes

\[
a \int_{-\infty}^{+\infty} N_1(x, \beta)|\tilde{E}_x(x)|^2dx + b \int_{-\infty}^{+\infty} N_2(x, \beta)\tilde{E}_x(x)(\tilde{E}_z(x))^* dx = 0,
\]

\[
a \int_{-\infty}^{+\infty} N_3(x, \beta)\tilde{E}_x(x)(\tilde{E}_z(x))^* dx + b \int_{-\infty}^{+\infty} N_4(x, \beta)|\tilde{E}_z(x)|^2dx = 0. \quad (2.77)
\]

The dispersion characteristics of the slot line is determined by varying \(\beta\) such that the determinant of the coefficient matrix of (2.77) is zero for a given set of physical parameters at a desired frequency of operation.

A choice of the basis function which approximates the field closely is [19]

\[
e_x(x) = \begin{cases} 
1, & |x| \leq W/2 \\
0, & \text{elsewhere}
\end{cases} \quad (2.78)
\]

\[
e_z(x) = \begin{cases} 
x\sqrt{(W/2)^2 - x^2}, & |x| \leq W/2 \\
0, & \text{elsewhere}
\end{cases}
\]
The Fourier transform of Eqs. (2.78) is

\[ \tilde{E}_x(x) = \pi B_0 \left( \frac{xW}{2} \right) \]
\[ \tilde{E}_z(x) = j \frac{\sqrt{2}}{4} \pi \frac{W}{x} B_2 \left( \frac{xW}{2} \right) \]  

(2.79)

where \( B_0 \) and \( B_2 \) are the Bessel functions of the first kind of order zero and two, respectively.

**Characteristic Impedance** The characteristic impedance \( Z_0 \) for a slot line is defined as [19]

\[ Z_0 = \frac{V_0^2}{2P_{avg}} \]

(2.80)

where \( V_0 \) is the slot voltage and \( P_{avg} \) is the time average power flow. To reduce the algebraic complexity, the \( z \)-directed electric field component given in Eq. (2.78) is neglected. This is referred to as the first-order approximation. The slot voltage \( V_0 \) is expressed as

\[ V_0 = \int_{-W/2}^{+W/2} E_x(x)dx. \]

(2.81)

By performing an analytical integration for \( E_x \) given by Eq. (2.78), \( V_0 \) is equal to \( \pi \). \( P_{avg} \) is defined as [19]

\[ P_{avg} = \frac{1}{2} \text{Re} \left\{ \int_S \left[ \int_{-\infty}^{\infty} \tilde{E}_y \times (\tilde{H}_t)^* \cdot \hat{a}_z dxdy \right] \right\}. \]

(2.82)

The subscript \( t \) indicates transverse field components and \( S \) is the cross-sectional area. Assuming that a wave propagating in the \(-z\)-direction, the equation above reduces to

\[ P_{avg} = \frac{1}{2} \text{Re} \left\{ \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} (E_y H_x^* - E_x H_y^*) dxdy \right\}. \]

(2.83)

For a wave propagating in the \(-z\)-direction, the \( z \) dependence is of the form \( e^{j\gamma z} \), where \( \gamma = j\beta \) for a loss less case. The \( E_x, E_y, H_x, \) and \( H_y \) components can be expressed in terms of the scalar potential functions given in Eqs. (2.60a) to (2.60d):
\[ E_x H_x^* = \beta^2 \frac{\partial \phi_1(x, y)}{\partial y} \frac{\partial \psi_1(x, y)}{\partial x} + \omega \epsilon \beta \left( \frac{\partial \phi_1(x, y)}{\partial y} \right)^2 \]
\[ + \omega \mu \beta \left( \frac{\partial \psi_1(x, y)}{\partial y} \right)^2 + \omega^2 \mu \epsilon \frac{\partial \phi_1(x, y)}{\partial y} \frac{\partial \psi_1(x, y)}{\partial z}, \quad (2.84) \]
\[ E_y H_y^* = \beta^2 \frac{\partial \phi_1(x, y)}{\partial x} \frac{\partial \psi_1(x, y)}{\partial y} - \omega \epsilon \beta \left( \frac{\partial \phi_1(x, y)}{\partial x} \right)^2 \]
\[ - \omega \mu \beta \left( \frac{\partial \psi_1(x, y)}{\partial x} \right)^2 + \omega^2 \mu \epsilon \frac{\partial \phi_1(x, y)}{\partial x} \frac{\partial \psi_1(x, y)}{\partial y}, \quad (2.85) \]

Equation (2.82) with the substitution above takes on the following form:

\[
P_{\text{avg}} = \frac{1}{2} \text{Re} \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} \left\{ \omega \mu \beta \left[ \left( \frac{\partial \psi_1(x, y)}{\partial x} \right)^2 + \left( \frac{\partial \psi_1(x, y)}{\partial y} \right)^2 \right] \right. \]
\[ + \omega \epsilon \beta \left( \frac{\partial \phi_1(x, y)}{\partial x} \right)^2 + \left( \frac{\partial \phi_1(x, y)}{\partial y} \right)^2 \]
\[ + \left( \beta^2 + k_f^2 \right) \left( \frac{\partial \phi_1(x, y)}{\partial y} \frac{\partial \psi_1(x, y)}{\partial x} - \frac{\partial \phi_1(x, y)}{\partial x} \frac{\partial \psi_1(x, y)}{\partial y} \right) \} \, dx \, dy, \quad (2.86) \]

where \( k_f^2 = \omega^2 \mu \epsilon \). The limits of integration are infinite since the slot line is an open structure.

The next step is to transform Eq. (2.85) into the spectral domain. Since the limits of integration extends to infinity, the transformation is made possible through the use of Parseval's relation, which is given as

\[
\int_{-\infty}^{+\infty} f^*(x) g(x) \, dx = \int_{-\infty}^{+\infty} \mathcal{F}[f] \mathcal{F}[g] \, dt, \quad (2.87) \]

To facilitate the use of Parseval's relation, the first term in Eq. (2.86) is expressed as the product of two complex quantities as follows:

\[
\left( \frac{\partial \psi_1(x, y)}{\partial x} \right)^2 + \left( \frac{\partial \psi_1(x, y)}{\partial y} \right)^2
\]
\[ = \left( \frac{\partial \psi_1(x, y)}{\partial x} + j \frac{\partial \psi_1(x, y)}{\partial y} \right) \times \left( \frac{\partial \psi_1(x, y)}{\partial x} - j \frac{\partial \psi_1(x, y)}{\partial y} \right). \quad (2.88) \]

A similar relation holds good for the second term in Eq. (2.86) and making use of the identity

\[
\mathcal{F}[f'(x)] = -j \omega \mathcal{F}[f], \quad (2.89) \]
the time average power flow is

\[ P_{\text{avg}} = \frac{1}{4\pi} \Re \left[ \int_{-\infty}^{+\infty} \int_{-\infty}^{+\infty} \left( -x^2 \beta \omega \epsilon_0 \left| \tilde{\phi}_i(x, y) \right|^2 - \beta \omega \mu_0 \left| \frac{\partial \tilde{\psi}_i(x, y)}{\partial y} \right|^2 ight) \, dx \, dy \right] \]

\[ -\beta \omega \epsilon_0 \left| \frac{\partial \tilde{\phi}_i(x, y)}{\partial y} \right|^2 - \beta \omega \mu_0 |\tilde{\psi}_i(x, y)|^2 \]

\[ -jx\beta^2 \left( \tilde{\phi}_i(x, y)^* \frac{\partial \tilde{\psi}_i(x, y)}{\partial y} + \frac{\partial \tilde{\phi}_i(x, y)}{\partial y} \tilde{\psi}_i(x, y)^* \right) \]

\[ +jxk_1^2 \left( \tilde{\phi}_i(x, y)^* \frac{\partial \tilde{\psi}_i(x, y)}{\partial y} + \frac{\partial \tilde{\phi}_i(x, y)}{\partial y} \tilde{\psi}_i(x, y)^* \right) \, dx \, dy. \quad (2.90) \]

Since \( \tilde{\phi}_i(x, y) \) and \( \tilde{\psi}_i(x, y) \) take different forms in the three spatial regions, as in Eqs. (2.67) and (2.68), the equation above has to be evaluated for each region separately. In addition the double integral reduces to a single integral by performing the integration with respect to \( y \) analytically. In Appendix 2B the integrands for the three regions are separately derived.

**Coupled Slot Lines** The structure shown in Figure 2.13(b) is considered as coupled slot lines. The two natural modes supported by this structure are the even and odd modes. These modes are defined as

\[ E_x(x) = E_x(-x) \quad \text{for the even mode}, \]

\[ E_x(x) = -E_x(-x) \quad \text{for the odd mode}. \quad (2.91) \]

The dyadic Green’s function given in Eq. (2.73) is a function of \( x, \beta, \epsilon_r, h_1 \), and the operating frequency, but it is independent of the slot configuration. The dimensions of the slot enter into the computations only through the basis function. Thus it is only necessary to modify Eq. (2.78) to suit the coupled slot line geometry and field distribution.

A choice of the basis function that approximates the fields of the coupled slot line closely is

\[ e_x(x) = \begin{cases} 
1 \\
\frac{1}{\sqrt{(W/2)^2 - \{x - [(S + W)/2]\}^2}}, & S/2 < x < S/2 + W \\
\pm 1 \\
\sqrt{(W/2)^2 - \{x + [(S + W)/2]\}^2}, & -S/2 - W < x < -S/2 \\
0, & \text{elsewhere.} \end{cases} \quad (2.92) \]

The + sign for the even mode and – sign for the odd mode. Figure 2.14 shows graphically the assumed field distribution for coupled slot lines. In comparing
Eq. (2.92) with Eq. (2.78), we notice that the former is a shifted version of the latter. Hence, to obtain the Fourier transform of Eq. (2.92), the shifting property of the Fourier transform is used. That is, if

\[
\mathcal{F}\{\phi(x)\} = \tilde{\phi}(x) = \int_{-\infty}^{+\infty} \phi(x)e^{j\omega x} dx, \quad \text{then} \quad \mathcal{F}\{\phi(x-x_0)\} = e^{j\omega x_0}\tilde{\phi}(x).
\] (2.93)

Hence the Fourier transform of the electric field in Eq. (2.92) for the even mode is

\[
\tilde{E}_{xe}(x) = (e^{j\omega(S+Wx)/2} + e^{-j\omega(S+Wx)/2})\tilde{E}_x(x) = 2\cos\left(\frac{x(S+W)}{2}\right)\tilde{E}_x(x)
\] (2.94)

and for the odd mode is

\[
\tilde{E}_{xo}(x) = (e^{j\omega(S+Wx)/2} - e^{-j\omega(S+Wx)/2})\tilde{E}_x(x) = +2j\sin\left(\frac{x(S+W)}{2}\right)\tilde{E}_x(x)
\] (2.95)

where \(\tilde{E}_x(x)\) is given by Eq. (2.78). A similar transformation holds good for the \(z\)-directed electric field \(e_z(x)\). The expression for the characteristic impedance is changed to [19]

\[
Z_{0,0,e} = \frac{V_0^2}{P_{\text{avg},0,e}},
\] (2.96)

since the total time average power surrounding the transmission lines is now due to two lines.
**Computed Characteristics for Coupled Slot Lines**  The computed even-mode and odd-mode wavelength ratio \((\lambda_g/\lambda)\), where \(\lambda_g\) and \(\lambda\) are the guide wavelength and free space wavelength, respectively, is shown in Figure 2.15(a) [19]. The corresponding characteristic impedance is shown in Figure 2.15(b) [19].

The validity of the foregoing results is checked in the limit where the separation \(S\) between the slots tends to be very small. In this limit the even-mode characteristic impedance \(Z_{0,e}\) approaches one-half of \(Z_0\), where \(Z_0\) is the characteristic impedance of a single slot line with twice the width of the slot in the coupled structure. The dispersion characteristics for both the structures, however, is the same.

From the above characteristics some interesting observations can be made. First, the characteristic impedance of the CPW is one-half of the odd-mode characteristic impedance \(Z_{0,o}\) for equal slot width. Second, for large \(S/h_1\) as frequency increases, \(Z_{0,e}\) and \(Z_{0,o}\) converge to \(Z_0\). Where \(Z_0\) is the characteristic impedance of a single slot with no coupling. Third, for a fixed \(h_1/\lambda\), the ratio \(\lambda_g/\lambda\) for the even-mode first increases and then decreases as \(S/h_1\) increases from a small to a large value. This is because for small separation, the metal strip between the slots has negligible effect on the wave, and therefore the wave propagates as if it were on a slot of width \(2(W/h_1) + S/h_1\). As the separation increases the slot width effectively increases and hence \(\lambda_g/\lambda\) increases. As \(S/h_1\) continues to increases, the waves on the two slot lines start to decouple and eventually propagate as if on two independent slot lines of width \(W/h_1\). The ratio \(\lambda_g/\lambda\) therefore decreases.

As a concluding remark, it may be useful to indicate other techniques that have been used to analyze CPW structures. In [20] and [21] the CPW was analyzed by modeling the structure as a capacitive iris in a rectangular waveguide. In [22] the conformal mapping technique and the variational reaction theory were combined and solved using the finite element method (FEM). Finally, in [23] the CPW was analyzed using the finite difference time domain technique (FDTD).

### 2.4.2 Experimental Validation

The computed \(\varepsilon_{eff}\) using the spectral-domain technique for CPW on alumina and GaAs substrates are compared with the measured values over the frequency range of 1 to 25 GHz [24]. The experimental values for \(\varepsilon_{eff}\) are determined using an automatic network analyzer with time-domain option. Figure 2.16 presents the above comparison.

The computed \(\varepsilon_{eff}\) values for CPW on Duroid and Cuflon substrates based on the technique described in [20] are compared with the experimentally measured values over the frequency range of 2 to 18 GHz [25]. The experimental values are determined from the measured resonance frequencies and the physical length of a pair of series-gap coupled straight resonators fabricated on these substrates. Figure 2.17(a) and (b) presents this comparison.

The computed \(Z_0\) using the spectral-domain technique for CPW on GaAs substrate is compared with the experimentally measured values [26]. The CPW
FIGURE 2.15 Computed even-mode and odd-mode characteristics as a function of frequency with the separation as a parameter, $W/h_1 = 0.25, \varepsilon_i = 11$: (a) Wavelength ratio; (b) characteristic impedance. (From Reference [19], © IEEE 1975.)
FIGURE 2.16  Measured and computed effective dielectric constant as a function of the frequency: GaAs: $\varepsilon_r = 12.9$, $S = 0.075$ mm, $W = 0.05$ mm, $h_1 = 0.4$ mm, $t = 0.002$ mm; Ceramic: $\varepsilon_r = 9.8$, $S = 0.2$ mm, $W = 0.01$ mm, $h_1 = 0.635$ mm, $t = 0.003$ mm. (From Reference [24], with permission from Microwave Exhibitions and Publishers.)

FIGURE 2.17  Measured and computed effective dielectric constant as a function of the frequency: (a) $\varepsilon_r = 2.2$, $h_1 = 0.125$ in., $W = 0.01$ in., $S/(S + 2W) = 0.9$; (b) $\varepsilon_r = 2.1$, $h_1 = 0.062$ in., $W = 0.01$ in. $S/(S + 2W) = 0.86$. 
impedance is determined from the measured two-port S-parameters of through lines. The S-parameters are obtained using on-wafer RF probes and a calibrated automatic network analyzer. Figure 2.18 presents this comparison.

2.5 EMPIRICAL FORMULA TO DETERMINE DISPERSION BASED ON SPECTRAL DOMAIN RESULTS

An empirical formula to compute $\varepsilon_{\text{eff}}$ of CPW shown in Figure 2.5 has been obtained. This is done by curve fitting the dispersion data obtained using the spectral domain method. The expression is valid into the terahertz regime and given below [27], [28]:

$$\sqrt{\varepsilon_{\text{eff}}(f)} = \sqrt{\varepsilon_q} + \frac{(\sqrt{\varepsilon_{r1}} - \sqrt{\varepsilon_q})}{(1 + a F^{-b})},$$

(2.97)

where

- $f = \text{frequency}$
- $F = f/f_{\text{TE}}, \text{the normalized frequency}$
- $f_{\text{TE}} = c/(4h_1\sqrt{\varepsilon_{r1}} - 1), \text{the cutoff frequency for the lowest-order TE mode}$
- $\varepsilon_q = \text{effective permittivity at the quasi-static limit}$
- $b \approx 1.8, \text{is a constant independent of the dimensions}$
The factor $a$ is computed from the expression [28]

$$\log(a) \approx u \log\left(\frac{S}{W}\right) + v$$  \hspace{1cm} (2.98)

where $u$ and $v$ depend on the substrate thickness $h_1$ as follows [28]:

$$u \approx 0.54 - 0.64q + 0.015q^2$$
$$v \approx 0.43 - 0.86q + 0.540q^2$$  \hspace{1cm} (2.99)

and $q = \log(S/h_1)$.

The preceding formula for $\varepsilon_{\text{eff}}$ is accurate to within 5 percent for the following range of parameters [28]:

$$0.1 < \frac{S}{W} < 5$$
$$0.1 < \frac{S}{h_1} < 5$$
$$1.5 < \varepsilon_{\tau_1} < 50$$
$$0 < \frac{f}{f_{TE}} < 10$$  \hspace{1cm} (2.100)

A similar set of equations was presented in [29].

### 2.5.1 Comparison of Coplanar Waveguide Dispersion with Microstrip

Equation (2.97) is used to compare the dispersion characteristics of a 50$\Omega$ CPW ($S = 85\ \mu$m, $W = 50\ \mu$m) with a 50$\Omega$ microstrip ($W = 73\ \mu$m) on an identical GaAs substrate ($\varepsilon_{\tau_1} = 13$, $h_1 = 100\ \mu$m). The cutoff frequency $f_{TE}$ for this substrate is about 216.5 GHz. Figure 2.19 presents the $\sqrt{\varepsilon_{\text{eff}}}$ for the two transmission lines as a function of the normalized frequency [28]. The figure shows that the quasi-static value of the effective permittivity $\varepsilon_{q}$ is lower for the CPW compared to the microstrip. This is expected because the CPW has greater fringe fields. At infinite frequencies the effective permittivity, $\varepsilon_{\text{eff}}$ approaches $\varepsilon_{\tau_1}$ in both cases. This implies that ultrashort pulses having bandwidths greater than 700 GHz ($\log(f/f_{TE}) \geq 0.5$) will suffer greater dispersion in the CPW. On the other hand, since the $\varepsilon_{\text{eff}}$ increases with frequency more gradually for CPW, longer pulses with narrow bandwidth will suffer lower dispersion.

In general, the dispersion for both CPW and microstrip can be reduced by reducing the substrate thickness. For CPW, dispersion can be slightly reduced by decreasing the strip and slot dimensions, but the $\varepsilon_{\text{eff}}$ at low frequencies remains lower than the corresponding microstrip and thus it is intrinsically more dispersive for short pulses.
2.6 SYNTHESIS FORMULAS TO DETERMINE $\varepsilon_{\text{eff}}$ AND $Z_0$ BASED ON QUASI-STATIC EQUATIONS

Closed form formulas to computer $\varepsilon_{\text{eff}}$ and $Z_0$ of CPW shown in Figure 2.5 are available [30] to [32]. These formulas are obtained by function approximation and by curve-fitting the quasi-static equations. The synthesis formulas are valid over a very wide range of relative substrate permittivity ($1.5 \leq \varepsilon_{r1} \leq 120$). Consequently these formulas are broad enough for most CPW circuit design, which includes printed antennas on low-permittivity substrates as well as monolithic microwave integrated circuits on high-permittivity semiconductor substrates.

The synthesis formulas for the strip width $S$ or the slot width $W$ are expressed in terms of $\varepsilon_{r1}$, $h_1$, $Z_0$ and either the slot width $W$ or the strip width $S$, respectively. The CPW is schematically illustrated in Figure 2.5. The expression for the strip width will be first presented.

When

$$\frac{W}{h_1} \leq \frac{10}{[3(1 + \ln \varepsilon_{r1})]} \quad \text{and} \quad \frac{S}{h_1} \leq \frac{80}{[3(1 + \ln \varepsilon_{r1})]},$$

the strip width is given by

$$S = W \times G(\varepsilon_{r1}, h_1, Z_0, W), \quad (2.101)$$

with

$$G = 0.25 \exp\left(\frac{30\pi^2}{Z_0^{0.5}}\right) + \exp\left(-\frac{30\pi^2}{Z_0^{0.5}}\right) - 1 \quad \text{for} \quad Z_0 < \frac{60\sqrt{2\pi}}{(\varepsilon_{r1} + 1)^{0.5}}, \quad (2.102)$$
In these expressions, \( e_{\text{eff}} \) is given by

\[
\begin{align*}
\varepsilon_{\text{eff}}(\varepsilon_r, h_1, Z_0, W) &= T_1[1 + (\varepsilon_r - 1)1.5Z_0T_2] \quad \text{for } \varepsilon_r < 6.0, \quad (2.104) \\
\varepsilon_{\text{eff}}(\varepsilon_r, h_1, Z_0, W) &= (\varepsilon_r + 1)T_3T_4 \quad \text{for } \varepsilon_r \geq 6.0, \quad (2.105)
\end{align*}
\]

with

\[
T_1 = \text{sech} \left[ \frac{\varepsilon_r}{\varepsilon_r + 1} \left[ \frac{47.56}{Z_0} \right]^2 \times \exp \left[ \left( 1 + 0.0064Z_0 \frac{W}{h_1} \right) \times \ln \left( 0.6 + \frac{W}{h_1} \right) \right] \right],
\]

(2.106)

\[
T_2 = \left( \frac{1}{837.5} \right) \ln \left[ 2 \times \frac{(1 + g)}{(1 - g)} \right] \quad \text{for } 0.841 \leq g < 1,
\]

(2.107)

\[
T_2 = \left( \frac{84.85}{\ln \left[ \frac{2 \times [1 + (1 - g^4)^{0.25}]}{[1 - (1 - g^4)^{0.25}]} \right] \right)^{-1} \quad \text{for } 0 < g \leq 0.841,
\]

(2.108)

\[
g = \left( \frac{\exp[\pi(1 + p)W/2h_1] - \exp[\pi W/2h_1]}{\exp[\pi(2 + p)W/2h_1] - 1} \right)^{0.5},
\]

(2.109)

\[
p = 0.25 \exp \left[ \frac{30 \sqrt{2\pi^2}}{Z_0(\varepsilon_r + 1)^{0.5}} \right] + \exp \left[ - \frac{30 \sqrt{2\pi^2}}{Z_0(\varepsilon_r + 1)^{0.5}} \right] - 1
\]

(2.110)

\[
p = \left\{ 0.125 \exp \left[ \frac{Z_0(\varepsilon_r + 1)^{0.5} - 0.5}{60 \sqrt{2}} \right] \right\}^{-1} \quad \text{for } Z_0 \geq \frac{60 \sqrt{2\pi}}{(\varepsilon_r + 1)^{0.5}},
\]

(2.111)

\[
T_3 = \text{sech} \left[ \frac{\varepsilon_r^6}{(\varepsilon_r + 1)^7} \left[ \frac{150.4}{Z_0} \right]^2 \times \exp \left[ \left( 1 + 0.0008\varepsilon_r Z_0 \frac{W}{h_1} \right) \right. \right.
\]

\[
\left. \times \ln \left( 0.3 + \frac{W}{h_1} \right) \right]\right], \quad (2.112)
\]

\[
T_4 = 0.5 + [0.02125 - 0.345Q - 0.0005(0.25 + Q)\varepsilon_r] \frac{QW}{h_1}
\]

\[- \left\{ 1 + \exp \left[ 3.5 - 1.55 \ln \left( \frac{W}{h_1} \right) \right] \right\}^{-1}, \quad (2.113)
\]
\[ Q = \left\{ 1 - 0.5 + 0.25 \times \exp \left[ \frac{30\sqrt{2\pi^2}}{Z_0(\varepsilon_{r1} + 1)^{0.5}} \right] \right\}^2 \quad \text{for } Z_0 < \frac{60\sqrt{2\pi}}{(\varepsilon_{r1} + 1)^{0.5}}, \]

\[ Q = 4 \exp \left\{ - \left( \frac{Z_0}{120} \right) \times \left[ 2(\varepsilon_{r1} + 1)^{0.5} \right] \right\} \quad \text{for } Z_0 \geq \frac{60\sqrt{2\pi}}{(\varepsilon_{r1} + 1)^{0.5}}. \]

(2.114)

(2.115)

In an analogous manner the slot width can be expressed. When

\[ \frac{S}{h_1} \leq \frac{80}{3(1 + \ln \varepsilon_{r1})} \quad \text{and} \quad \frac{W}{h_1} \leq \frac{10}{3(1 + \ln \varepsilon_{r1})} \]

the slot width \( W \) is given by

\[ W = \frac{S}{G(\varepsilon_{r1}, h_1, Z_0, S)}, \]

(2.116)

with

\[ G = 0.25 \exp \left[ \frac{30\pi^2 Z_0^{0.5}}{Z_0^{\varepsilon_{\text{eff}}}} \right] + \exp \left[ - \frac{30\pi^2 Z_0^{0.5}}{Z_0^{\varepsilon_{\text{eff}}}} \right] - 1 \quad \text{for } Z_0 < \frac{60\sqrt{2\pi}}{(\varepsilon_{r1} + 1)^{0.5}}, \]

\[ G = \left[ 0.125 \exp \left( \frac{Z_0^{\varepsilon_{\text{eff}}}}{60} - 0.5 \right) \right]^{-1} \quad \text{for } Z_0 \geq \frac{60\sqrt{2\pi}}{(\varepsilon_{r1} + 1)^{0.5}}, \]

(2.117)

(2.118)

where \( \varepsilon_{\text{eff}} \) is equal to

\[ \varepsilon_{\text{eff}}(\varepsilon_{r1}, h_1, Z_0, S) = (1 + T_A) \times \left[ 1 + (\varepsilon_{r1} - 1)^{1.5} Z_0 T_B \right], \]

with

\[ T_A = \tanh \left\{ \frac{\varepsilon_{r1}^{7}}{(\varepsilon_{r1} + 1)^{8}} \left[ \frac{60}{Z_0} \right]^2 \times \exp \left( \frac{1 + 0.002 Z_0 S}{Qh_1} \right) \times \ln \left( \frac{S}{Qh_1} \right) \right\} \]

for \( \varepsilon_{r1} < 6, \)

(2.119)

\[ T_A = \tanh \left\{ \frac{\varepsilon_{r1}^{5}}{(\varepsilon_{r1} + 1)^{6}} \left[ \frac{60}{Z_0} \right]^2 \times \exp \left( \frac{1 + 0.002 Z_0 S}{Qh_1} \right) \times \ln \left( \frac{S}{Qh_1} \right) \right\} \]

for \( \varepsilon_{r1} \geq 6, \)

(2.120)

\[ T_B = \left( \frac{1}{837.5} \right) \times \ln \left[ \frac{2(1 + g)}{1 - g} \right] \quad \text{for } 0.841 \leq g < 1, \]

(2.121)
\[
T_B = \left( 84.85 \ln \left\{ 2 \times \left[ \frac{1 + (1 - g^2)^{0.25}}{1 - (1 - g^2)^{0.25}} \right] \right\} \right)^{-1} \quad \text{for } 0 < g \leq 0.841,
\]

\[
g = \left\{ \frac{\sinh(\pi S/4h_1)}{\sinh\left[ \left( \pi (1 + 2/Q)S \right)/4h_1 \right]} \right\}^{0.5},
\]

\[
Q = 0.25 \exp \left\{ \frac{30 \sqrt{2\pi}}{Z_0(\varepsilon_r + 1)^{0.5}} \right\} + \exp \left\{ -\frac{30 \sqrt{2\pi}}{Z_0(\varepsilon_r + 1)^{0.5}} \right\} - 1
\]

\[
\text{for } Z_0 < \frac{60\sqrt{2\pi}}{(\varepsilon_r + 1)^{0.5}},
\]

\[
Q = \left\{ 0.125 \times \exp \left[ \frac{Z_0(\varepsilon_r + 1)^{0.5}}{60\sqrt{2}} \right] - 0.5 \right\}^{-1} \quad \text{for } Z_0 \geq \frac{60\sqrt{2\pi}}{(\varepsilon_r + 1)^{0.5}}.
\]

The accuracy of Eq. (2.101) is 1 percent for \( \varepsilon_r > 6.0 \) and better than 3 percent for the entire \( \varepsilon_r \) range, while the accuracy of Eq. (2.116) is 1 percent for \( \varepsilon_r > 6.0 \) and better than 2 percent for the entire \( \varepsilon_r \) range.

### 2.7 COPLANAR WAVEGUIDE WITH ELEVATED OR BURIED CENTER STRIP CONDUCTOR

The conventional CPW on a GaAs substrate has a \( Z_0 \) approximately in the range of 30 to 80 \( \Omega \). In applications, such as, reduced-size hybrid couplers, broadband bias network, subpicosecond sampling circuits, etc., there is a need for CPW with \( Z_0 \) greater than 80 \( \Omega \). A straightforward approach to achieve high \( Z_0 \) for a given ground-to-ground separation \( (S + 2W) \) is by reducing the center strip conductor width \( S \). The disadvantage of this approach is the steep increase in attenuation due to ohmic losses. In addition the \( Z_0 \) becomes very sensitive to the strip width-to-slot width ratio and any small deviation causes significant change in \( Z_0 \). A solution to this problem is to either elevate or bury the center strip conductor as shown in Figure 2.20 [33] to [38]. In Figure 2.20(a) and (b) the center strip conductor is either elevated and supported by or buried beneath several dielectric layers respectively. In Figure 2.20(c), the center strip conductor is fabricated as a sequence of air-bridges and hence is supported by posts at regular intervals. In this case, for the purpose of numerical simulation, the center strip conductor is considered to be elevated and supported by an air dielectric. The propagation characteristics of the lines above will be discussed next. The technique employed to compute the \( Z_0 \) of CPW with elevated center strip conductor on dielectric layers has not been revealed in the original reference. The characteristics for CPW with elevated center strip conductor on air dielectric were obtained using the Sonnet Software.
FIGURE 2.20 Coplanar Waveguide with (a) elevated center strip conductor on dielectric layers, (b) buried center strip conductor, and (c) elevated center strip conductor on air dielectric.
2.7.1 CPW with Elevated Center Strip Conductor Supported on Dielectric Layers

This structure is shown in Fig. 20(a). The substrate is GaAs ($\varepsilon_r = 12.9$), and the dielectric layers are polyimide ($\varepsilon_r = 3.3$). In a practical structure each polyimide layer is 2.5 $\mu$m thick and is formed using a spin-coating method to ensure uniform thickness [34], [35]. For this structure the computed $Z_0$ as a function of the ground-to-ground separation with the thickness $h$ of the polyimide layer as a parameter is shown in Figure 2.21. The strip width $S$ is held fixed at 9 $\mu$m. The $Z_0$ for a conventional CPW with $h$ equal to zero is also shown on the same figure for comparison. As an example, for an elevated CPW with $Z_0$ equal to 100 $\Omega$, the ground-to-ground separation in 40 $\mu$m for $h$ equals 10 $\mu$m, while a conventional CPW requires a ground-to-ground separation in excess of 120 $\mu$m [35]. Thus in MMICs, for a desired ground-to-ground separation, high $Z_0$ can be achieved by using an elevated CPW that does not require the center strip width to be excessively narrow.

2.7.2 CPW with Elevated Center Strip Conductor Supported on Posts

This structure is shown in Figure 2.20(c). Normal air-bridge fabrication process is used to elevate the center strip conductor to a height of 2 to 3 $\mu$m above the GaAs substrate. Table 2.4 compares the computed $\varepsilon_{\text{eff}}$, $Z_0$ and attenuation of conventional CPW with the elevated CPW for identical strip and slot widths.

![Figure 2.21](image-url)  
**FIGURE 2.21** Computed characteristic impedance as a function of the ground-to-ground separation for elevated CPW with weight of the dielectric layer as a parameter: $\varepsilon_{r1} = 12.9$, $\varepsilon_{r2} = 3.3$, $S = 9$ $\mu$m. (From Reference [35], © IEEE 1992.)
TABLE 2.4 Comparison of Computed $\varepsilon_{\text{eff}}$, $Z_0$ and Attenuation of Conventional CPW with the Elevated CPW for Identical $S$ and $W$

<table>
<thead>
<tr>
<th></th>
<th>Conventional CPW (Computed)</th>
<th>Elevated CPW</th>
<th>Measured</th>
</tr>
</thead>
<tbody>
<tr>
<td>$\varepsilon_{\text{eff}}$</td>
<td>6.4</td>
<td>2.62</td>
<td>2.62</td>
</tr>
<tr>
<td>$Z_0$ ($\Omega$)</td>
<td>60</td>
<td>101</td>
<td>97</td>
</tr>
<tr>
<td>$\alpha$ (dB/mm)</td>
<td>0.25</td>
<td>0.13</td>
<td>0.1</td>
</tr>
</tbody>
</table>

Note: $S=12\,\mu$m, $W=18\,\mu$m, $h=2.6\,\mu$m, $t=2.9\,\mu$m, $h_1=500\,\mu$m, $\varepsilon_r=12.9$, $\sigma_{\text{gold}}=30\,S/\mu$m, $\tan\delta_e=3\times10^{-4}$, $F=20\,\text{GHz}$.

[38]. The results show that by elevating the center strip the $Z_0$ increases from 60 to 100 $\Omega$, which is about 66 percent, while the attenuation decreases from 0.25 to 0.13 dB/mm, which is about 50 percent. The table also shows that the computed and measured propagation parameters of the elevated CPW are in good agreement. Table 2.5 compares the strip width and attenuation of conventional CPW with elevated CPW for identical $Z_0$ and ground-to-ground separation. Clearly, the strip width of the conventional CPW is significantly smaller than that of the elevated CPW. A narrower strip width is consequently responsible for the higher attenuation. Figure 2.22 shows the computed $\varepsilon_{\text{eff}}$, $Z_0$ and attenuation as a function of the ground-to-ground separation for elevated CPW with air dielectric. The strip width and the height $h$ are held fixed at 10 and 2.5 $\mu$m, respectively. The range of $Z_0$ that can be realized is from about 100 to 150 $\Omega$.

As a concluding remark it is interesting to note that the capacitance per unit length and the inductance per unit of the elevated CPW with air dielectric is nearly four times smaller and nearly equal to that of conventional CPW respectively [36]. Hence this structure is well suited for picosecond sampling circuits [37].

TABLE 2.5 Comparison of Strip Width and Attenuation of Conventional CPW with Elevated CPW for Identical $Z_0$ and $S+2W$

<table>
<thead>
<tr>
<th></th>
<th>Conventional CPW</th>
<th>Elevated CPW</th>
</tr>
</thead>
<tbody>
<tr>
<td>$S$ ($\mu$m)</td>
<td>1.5</td>
<td>12</td>
</tr>
<tr>
<td>$\alpha$ (dB/mm)</td>
<td>0.5</td>
<td>0.1</td>
</tr>
</tbody>
</table>

Note: $Z_0=97\,\Omega$, $S+2W=48\,\mu$m, $h=2.6\,\mu$m, $t=2.9\,\mu$m, $h_1=500\,\mu$m, $\varepsilon_r=12.9$, $\sigma_{\text{gold}}=30\,S/\mu$m, $\tan\delta_e=3\times10^{-4}$, $F=20\,\text{GHz}$. 
FIGURE 2.22 Computed effective dielectric constant, characteristic impedance, and attenuation as a function of ground-to-ground separation for elevated CPW with air dielectric: $h_1 = \infty$, $\varepsilon_{r1} = 12.9$, $h = 2.5 \mu m$, $t = 2.5 \mu m$, $S = 10 \mu m$, $F = 20$ GHz, $\varepsilon_{r2} = 1.0$. (From Reference [38], © IEEE 1996.)

2.8 COPLANAR WAVEGUIDE WITH GROUND PLANE OR CENTER STRIP CONDUCTOR UNDERPASSES

In a conventional CPW low $Z_0$ is achieved by fabricating a very narrow slot width and a very wide center strip conductor. The disadvantages of this approach are, first, that the current density at the slot edges is high, which increases conductor losses; second, the wide strip conductor has potential to couple power from the dominant CPW mode to spurious unwanted propagation modes. Therefore conventional CPW is not recommended for lines with $Z_0$ less than about 30 $\Omega$.

Using multilayer CPW technology, those problems can be addressed. In the new geometry either the ground planes can be extended underneath the center strip conductor, as shown in Figure 2.23(a), or the center strip conductor can be extended under the ground planes, as shown in Figure 2.23(b) [39, 40]. Because the conductors in the new configurations are overlapping, an almost arbitrarily low $Z_0$ can be realized without significantly increasing conductor losses. Table 2.6 summarizes the characteristics of the two types of CPW.

2.9 COPLANAR WAVEGUIDE FIELD COMPONENTS

In the design of coplanar waveguide circuits and devices, such as ferrite isolators and circulators, electro-optic modulators, and traveling wave antennas, knowledge of the field components is essential. In this section, the field
FIGURE 2.23  Low impedance coplanar waveguide: (a) With ground plane underpasses; (b) with center strip conductor underpasses.

<table>
<thead>
<tr>
<th>TABLE 2.6 Coplanar Waveguide with Underpass Conductors</th>
</tr>
</thead>
<tbody>
<tr>
<td>Ground Plane Underpasses</td>
</tr>
<tr>
<td>--------------------------</td>
</tr>
<tr>
<td>Center strip conductor, ( \mu m )</td>
</tr>
<tr>
<td>Slot width, ( \mu m )</td>
</tr>
<tr>
<td>Overlap, ( \mu m )</td>
</tr>
<tr>
<td>( Z_0, \Omega )</td>
</tr>
<tr>
<td>Loss (dB/mm) at 10 GHz</td>
</tr>
</tbody>
</table>

Note: Substrate is semi-insulating GaAs of thickness 200 \( \mu m \) and \( \varepsilon_r = 12.85 \).
FIGURE 2.24 (a) Schematic of the coplanar waveguide; (b) Development of waveguide model for coplanar waveguide: magnetic walls at $y = 0$ and $y = b$ and electric walls at $x = 0$ and $x = a$.

components in the air region above the slots, in the substrate and in the air region below the substrate for a CPW are presented [41].

In order to simplify the notation, the coordinate system shown for the CPW in Figure 2.13(b) is modified as in Figure 2.24(a). For the case of odd excitation, a magnetic wall is placed at the $y = 0$ plane; it then suffices to restrict the analysis to the right half of the structure. The coplanar waveguide problem is reduced to a rectangular waveguide problem by inserting electric wall in the planes perpendicular to the slot at $x = 0$ and $x = a = \lambda_g/2$ ($\lambda_g$ is the slot mode wavelength) and magnetic wall at $y = b$; this is illustrated in Figure 2.24(b) [20].

On the air side of the slot ($z \leq 0$), the $E_x$ and $E_z$ components of the electric field and $H_x$, $H_y$, and $H_z$ components of the magnetic field exist. From Maxwell’s equations it follows that the $E_x$ component of the electric field on the air side of the slot is zero. On the substrate side of the slot $E_x$, $E_y$, and $E_z$
component of the electric field and \( H_x, H_y \) and \( H_z \) component of the magnetic field exist. The \( E_y \) component of the electric field and the \( H_x \) component of the magnetic field are determined as explained in [20], while the rest of the electric field and the magnetic field components are determined by the application of Maxwell's equations.

The rectangular coordinates \( x, y, z \), the slot width \( W \), substrate thickness \( h \), the center strip conductor width \( S \), and relative permittivity of the substrate material \( \varepsilon_{\text{r,1}} \) are indicated in Figure 24(a). A factor \( \exp[j(\omega t - 2\pi x/\lambda_g)] \) is assumed for each field component, implying wave propagation in the \(+x\)-direction only; \( V_0 \) is the voltage directly across the slot.

\[
V_0 = \int_{-s/2}^{s/2} E_x \, dy. \tag{2.126}
\]

**Air Side of the Slot** \( z \leq 0 \)

\[
E_y = \frac{2V_0}{b} \sum_{n>0} \sin \frac{n\pi y}{b} \sin \frac{n\pi \delta}{2} e^{-\gamma \sqrt{|z|}}, \tag{2.127}
\]

\[
E_z = -\frac{2V_0}{b} \sum_{n>0} 1_{F_n} \sin \frac{n\pi \delta}{2} \cos \frac{n\pi y}{b} e^{-\gamma \sqrt{|z|}}, \tag{2.128}
\]

\[
H_x = -j \frac{2V_0}{\eta b} \left( \frac{\lambda}{\lambda_g} \right)^2 \frac{2b}{\lambda} \sum_{n>0} 1_{F_n} \cos \frac{n\pi y}{b} e^{-\gamma \sqrt{|z|}}, \tag{2.129}
\]

\[
H_y = \frac{2V_0}{\eta b} \frac{\lambda}{\lambda_g} \sum_{n>0} \frac{1}{F_n} \sin \frac{n\pi \delta}{2} \frac{n\pi \delta}{2} \cos \frac{n\pi y}{b} e^{-\gamma \sqrt{|z|}}, \tag{2.130}
\]

\[
H_z = \frac{2V_0}{\eta b} \frac{\lambda}{\lambda_g} \sum_{n>0} \sin \frac{n\pi \delta}{2} \frac{n\pi \delta}{2} \cos \frac{n\pi y}{b} e^{-\gamma \sqrt{|z|}}. \tag{2.131}
\]

**Substrate Side of the Slot** \( 0 \leq z \leq h \)

\[
E_x = j \frac{2V_0}{\lambda_g} \sum_{n>0} \frac{2}{n[1 + (2b/n\lambda_g)^2]} \sin \frac{n\pi \delta}{2} \frac{n\pi \delta}{2} \cdot \left\{ \cos \frac{n\pi y}{b} \frac{\coth q_n - \tanh r_n \sinh \gamma_{n1} z}{\tanh r_n + (2b/n\lambda_g)^2 \coth q_n} \right\}, \tag{2.132}
\]

\[
E_y = \frac{2V_0}{b} \sum_{n>0} \sin \frac{n\pi \delta}{2} \frac{n\pi \delta}{2} \sin \frac{n\pi y}{b} \cdot \left\{ \cosh \gamma_{n1} z \frac{\tanh r_n + (2b/n\lambda_g)^2 \coth q_n}{1 + (2b/n\lambda_g)^2} \sinh \gamma_{n1} z \right\}, \tag{2.133}
\]
\[
E_z = -\frac{2V_0}{b} \sum_{n>0}^\infty F_{n1} \left[ \sin \frac{n\pi \delta / 2}{n\pi \delta / 2} \sin \frac{n\pi \delta}{2} \right] \cos \frac{n\pi y}{b} \left\{ \sin \gamma_{n1} z - \tanh r_n \cosh \gamma_{n1} z \right\},
\]

(2.134)

\[
H_x = j \frac{2V_0}{b\eta} \left( \frac{\lambda}{\lambda_g} \right)^2 \frac{2b}{\lambda} \sum_{n>0}^\infty \frac{1}{nF_{n1}} \left[ \sin \frac{n\pi \delta / 2}{n\pi \delta / 2} \sin \frac{n\pi \delta}{2} \right] \sin \frac{n\pi y}{b} \nonumber
\]

\[
\cdot \left\{ \left[ \frac{F_{n1} \coth q_n - \varepsilon_r (\lambda_g / \lambda)^2 \tanh r_n}{1 + (2b/n\lambda_g)^2} \right] \cosh \gamma_{n1} z - \left[ 1 - \varepsilon_r (\lambda_g / \lambda)^2 \right] \sinh \gamma_{n1} z \right\},
\]

(2.135)

\[
H_y = -\frac{2V_0}{\eta b} \frac{\lambda}{\lambda_g} \sum_{n>0}^\infty \frac{1}{F_{n1}} \left[ \sin \frac{n\pi \delta / 2}{n\pi \delta / 2} \sin \frac{n\pi \delta}{2} \right] \cos \frac{n\pi y}{b} \nonumber
\]

\[
\cdot \left\{ \left[ \frac{F_{n1} \coth q_n + \varepsilon_r (2b/n\lambda)^2 \tanh r_n}{1 + (2b/n\lambda_g)^2} \right] \cosh \gamma_{n1} z - \sinh \gamma_{n1} z \right\},
\]

(2.136)

\[
H_z = \frac{2V_0}{\eta b} \frac{\lambda}{\lambda_g} \sum_{n>0}^\infty \left[ \sin \frac{n\pi \delta / 2}{n\pi \delta / 2} \sin \frac{n\pi \delta}{2} \right] \sin \frac{n\pi y}{b} \left[ \cosh \gamma_{n1} z - \coth q_n \sinh \gamma_{n1} z \right].
\]

(2.137)

**Substrate Side of the Slot** \( z \gg h_i \)

The expressions for the field components on the substrate side of the slot \( z \gg h_1 \) are derived from Eqs. (2.132) to (2.137) by replacing \( \gamma_{n1} z \) by \( \gamma_{n1} h_1 \). Further the equations are multiplied by the factor \( \exp[-\gamma_n (z - h_1)] \), indicating that the fields decay exponentially. Symbols not defined above are \( \eta = 376.7 \Omega \), \( \delta = W/b \), \( \bar{\delta} = (S + W)/b \), and

\[
F_n = \frac{b_{\gamma_n}}{n\pi} = \sqrt{1 + \left( \frac{2bv}{n\lambda} \right)^2},
\]

(2.138)

\[
F_{n1} = \frac{b_{\gamma_{n1}}}{n\pi} = \sqrt{1 - \left( \frac{2bv}{n\lambda} \right)^2},
\]

(2.139)

\[
v = \sqrt{\left( \frac{\lambda}{\lambda_g} \right)^2 - 1}, \quad u = \sqrt{\varepsilon_r - \left( \frac{\lambda}{\lambda_g} \right)^2},
\]

(2.140)

\[
r_n = \gamma_{n1} h_1 + \tanh^{-1} \left( \frac{F_{n1}}{\varepsilon_r F_n} \right),
\]

(2.141)

\[
q_n = \gamma_{n1} h_1 + \coth^{-1} \left( \frac{F_n}{F_{n1}} \right).
\]

(2.142)

\( \lambda \) and \( \lambda_g \) are the free space wavelength and guide wavelength, respectively.
FIGURE 2.25 Computed electric-field distribution in the cross section (x = 0 plane).

Figures 2.25 and 2.26 illustrate the computed electric field and magnetic field, respectively, in the cross section of the coplanar waveguide. The $\varepsilon_r = 16$, $h_1/\lambda = 0.07$, $S/h_1 = 1$, $W/h_1 = 0.4$, the frequency is equal to 3 GHz, and $b \rightarrow \infty$. Since the expressions involve summing an infinite series, the following criterion for terminating the series at $n_f$ is adopted: $n_f = n_0/(1 + z/z_1)$, where $n_0$ and $z_1$ are constants. In the above case $n_0 = 1000$ and $z_1 = 0.005$ in. are found suitable.

It is observed that the electric-field lines extend across the slot while the magnetic-field lines are perpendicular to the air-dielectric interface in the slot. The electric and magnetic field in the right half of the structure are in a direction opposite to the electric and magnetic field in the left half of the structure. Furthermore part of the magnetic-field lines encircle the center conducting strip separating the two slots. Hence it should be possible to realize CPW circulators whose function is dominated by the transverse magnetic field component. The longitudinal view in Figure 2.27 shows that in the air regions the magnetic-field lines curve and return to the slot at half-wavelength intervals. Consequently a wave propagating along the structure has an elliptically polarized magnetic field. Hence it should be possible to successfully exploit the elliptically polarized magnetic field in the design of CPW resonance isolators and differential phase shifters.
FIGURE 2.26  Computed magnetic-field distribution in the cross section ($x = 0$ plane).

FIGURE 2.27  Computed magnetic field in the longitudinal section ($y = (S + W)/2$ plane) through the slot.
2.10 COPLANAR WAVEGUIDE ON A CYLINDRICAL SURFACE

2.10.1 Analytical Expressions Based on Quasi-static Conformal Mapping Technique

A CPW on the outside and the inside surfaces of a cylindrical dielectric tube is shown in Figures 2.28(a) and (b). In the figure the CPW center strip conductor width and the slot width are designated as $S$ and $W$, respectively. The inner and outer radius and the relative permittivity of the dielectric tube are designated as $a$, $b$, and $\varepsilon_r$, respectively. The CPW ground-to-ground separation is designated as $d$. The thickness $t_m$ of the metallizations is assumed to be negligible. The dielectric material that constitutes the tube is assumed to be loss less, and the conductivity of the metal coating is assumed to be perfect.

The analysis of the CPW on the outside surface [42] is first presented. The sequence of conformal mapping to transform the structure of Figure 2.28(a) into a parallel plate capacitor is shown in Figure 2.29. The first step is to transform the CPW on the outside surface of a cylinder into a planar CPW with finite ground planes as shown in Figure 2.29(a) through the mapping [42]

$$z = -j\ln\left(\frac{b}{r}\right) + \phi. \quad (2.143)$$

The second step is to calculate the capacitance of the structure with the dielectric replaced by free space. To facilitate this, the first quadrant of Figure 2.29(a) is transformed into the upper half of the $t$-plane as shown in Figure 2.29(b) through the mapping [42]

$$t = z^2 \quad (2.144)$$

and then into a parallel plate region as shown in Figure 2.29(c) through the mapping [42]

$$w = \int_{t_0}^{t} \frac{dt}{\sqrt{t(t-t_1)(t-t_2)(t-t_3)}}. \quad (2.145)$$

The capacitance of the structure considering all four quadrants is given by [42]

$$C_a = 4\varepsilon_0 \frac{K(k_1)}{K(\sqrt{1-k_1^2})}, \quad (2.146)$$

where

$$k_1 = \frac{S}{S+2W} \sqrt{\frac{1-(S+2W)^2/4b^2\pi^2}{1-S^2/4b^2\pi^2}} \quad (2.147)$$
FIGURE 2.28 The geometry of a cylindrical coplanar waveguide: (a) On the outside surface, (b) on the inside surface.
FIGURE 2.29 Conformal mapping steps for a CPW on the outside surface of a cylinder: (a) Intermediate transformation into a planar structure; (b) intermediate transformation for the air region; (c) mapping into a parallel plate capacitor for the air region, Re(z) > 0; (d) intermediate transformation for the dielectric region, Re(z) > 0; (e) mapping into parallel plate capacitor for the dielectric region, Re(z) > 0.
and $K$ is the complete elliptic integral of the first kind. The third step is to calculate the capacitance of the structure with the dielectric substrate replaced by a substrate of relative permittivity $\varepsilon_r - 1$. To facilitate this computation, the dielectric-air interfaces are replaced by magnetic walls. Then, through the mapping [42]

$$x = \cosh^2 \left[ \frac{\pi z}{2 \ln(b/a)} \right] \quad (2.148)$$

and

$$w = \int_{x_0}^{x} \frac{dx}{\sqrt{(x - 1)(x - x_1)(x - x_2)(x - x_3)}} \quad (2.149)$$

the right half of dielectric region in Figure 2.29(a) is first transformed into the upper half of the x-plane and then transformed into a parallel plate region as shown in Figure 2.29(d) and (e). The capacitance of the structure considering both the left and the right half is [42]

$$C_d = 2\varepsilon_0(\varepsilon - 1) \frac{K(k_2)}{K(\sqrt{1 - k_2^2})} \quad (2.150)$$

where

$$k_2 = \frac{\sinh(AS)}{\sinh(A(S + 2W))} \sqrt{\frac{1 - \sinh^2(A(S + 2W))/\sinh^2(2Ab\pi)}{1 - \sinh^2(AS)/\sinh^2(2Ab\pi)}} \quad (2.151)$$

$$A = \frac{\pi}{4b \ln(b/a)} \quad (2.152)$$

The total capacitance $C$ per unit length of the original structure is the sum of the capacitances $C_a$ and $C_d$. That is,

$$C = C_a + C_d \quad (2.153)$$

The effective dielectric constant is given by [42]

$$\varepsilon_{\text{eff}} = \frac{C}{C_a} = 1 + \frac{C_d}{C_a} = 1 + \frac{\varepsilon - 1}{2} \cdot \frac{K(\sqrt{1 - k_1^2})}{K(k_1)} \cdot \frac{K(k_2)}{K(\sqrt{1 - k_2^2})} \quad (2.154)$$
The characteristic impedance is given by [42]

\[ Z_0 = \frac{\sqrt{\varepsilon_{\text{eff}}}}{Cc} \]

\[ = \frac{120\pi\varepsilon_0}{C_a\sqrt{\varepsilon_{\text{eff}}}} \]

\[ = \frac{30\pi}{\sqrt{\varepsilon_{\text{eff}}}} \frac{K(\sqrt{1 - k_1^2})}{K(k_1)} , \]

where \( c \) is the velocity of light in free space. The effective dielectric constant and characteristic impedance for a CPW on the inside surface of a cylindrical dielectric tube has the same form as Eqs. (2.154) and (2.155), except that \( a \) and \( b \) are interchanged [42]. Finally, it may be mentioned that the foregoing structures have been analyzed using full-wave techniques and the results can be found in [43] and [44].

### 2.10.2 Computed Effective Dielectric Constant and Characteristic Impedance

The quasi-static \( \varepsilon_{\text{eff}} \) and \( Z_0 \) are computed via Eqs. (2.154) and (2.155), respectively. The computed \( \varepsilon_{\text{eff}} \) and \( Z_0 \) as a function of \( S/d \) for a CPW on the outside surface of a cylinder are presented in Figure 2.30(a) and (b) [42]. The characteristics are illustrated for two different ground plane separations, namely \( d = h \) and \( d = 4h \). In Figure 2.30(a) and (b) the computed \( \varepsilon_{\text{eff}} \) and \( Z_0 \) for a planar CPW [5] are included for comparison. The curvature effect is significant for large CPW, that is, when \( d = 4h \). It is also observed that in decreasing the curvature, that is, increasing the ratio \( a/b \), the \( \varepsilon_{\text{eff}} \) decreases. In the limit where the curvature becomes very small, that is, where the ratio \( a/b \) approaches unity, the \( \varepsilon_{\text{eff}} \) approaches that of the planar structure. The \( Z_0 \), however, is much less sensitive to the curvature, specially for small CPW, that is, when \( d = h \). These results contrast with the case of a CPW on the inside surface for which the \( \varepsilon_{\text{eff}} \) increases as the curvature decreases.

### 2.11 Effect of Metallization Thickness on Coplanar Waveguide Characteristics

A conventional coplanar waveguide is shown in Figure 2.5. For this structure the analysis presented in earlier sections ignored the thickness of the metal conductors. However, in the analysis presented in [45], [46] and [47] conductor thickness is taken into account. In these references the analysis is carried out using quasi-static method, frequency dependent network analytical method
FIGURE 2.30 Computed characteristics for a coplanar waveguide on the outside surface of a dielectric tube, \( \varepsilon_r = 3.0, \ h = 1.524 \text{ mm} \): (a) Effective dielectric constant; (b) characteristic impedance. (From Reference [42], © IEEE 1997.)
of electromagnetic fields, and spectral domain method, respectively. The computed $Z_0$ using the spectral domain method [26] with metal thickness $t$ and separation between ground planes $S + 2W$ as parameters is presented in Figure 2.31(a) and (b). Figure 2.31(a) shows that for fixed $S + 2W$ and aspect ratio $S/(S + 2W)$, the $Z_0$ decreases as $t$ increases. Figure 2.31(b) shows that for fixed $t$ and $S/(S + 2W)$, the $Z_0$ increases as $S + 2W$ increases. In [45] it has been shown that the effect of $t$ on $Z_0$ is smaller for substrates of higher dielectric constant.

The computed $\varepsilon_{\text{eff}}$ is shown in Figure 2.31(c) for fixed $S + 2W = 25 \mu\text{m}$. The $\varepsilon_{\text{eff}}$ deviates appreciably as $t$ increases. Notice that increasing $S + 2W$ from $25 \mu\text{m}$ to $100 \mu\text{m}$ has a small effect on $\varepsilon_{\text{eff}}$. In [45] it has been shown that the effect of $t$ on $\varepsilon_{\text{eff}}$ is larger for substrates of higher dielectric constant.

APPENDIX 2A: SPECTRAL DOMAIN DYADIC GREEN’S FUNCTION COMPONENTS

Equations for the tangential field components $E_zi$, $H_zi$, $E_xi$, and $H_xi$ from Eqs. (2.58b), (2.59b), (2.60a), and (2.60c) are substituted into the set of continuity Eqs. (2.69a) to (2.69d) at the interface $y = 0$. The resulting equations are transformed into the Fourier domain by taking the transform with respect to $x$. This process yields the following equations at the interface $y = 0$:

\[
k_{c2}^2\tilde{\phi}_2(x, 0) = k_{co}^2\tilde{\phi}_3(x, 0), \quad (2A.1a)
\]

\[
-jx\gamma\tilde{\phi}_2(x, 0) - j\omega\mu_0 \frac{\partial}{\partial y}\tilde{\psi}_2(x, 0) = -jx\gamma\tilde{\phi}_3(x, 0) - j\omega\mu_0 \frac{\partial}{\partial y}\tilde{\psi}_3(x, 0), \quad (2A.1b)
\]

\[
k_{c2}^2\tilde{\psi}_2(x, 0) = k_{co}^2\tilde{\psi}_3(x, 0), \quad (2A.1c)
\]

\[
-jx\gamma\tilde{\psi}_2(x, 0) + j\omega\epsilon_2 \frac{\partial}{\partial y}\tilde{\phi}_2(x, 0) = -jx\gamma\tilde{\psi}_3(x, 0) + j\omega\epsilon_0 \frac{\partial}{\partial y}\tilde{\phi}_3(x, 0), \quad (2A.1d)
\]

where the transform is expressed by a tilde above the symbol.

Next the equations for the tangential fields are substituted into the set of continuity Eqs. (2.70a) to (2.70f) at the interface $y = h_1$. Once again, upon taking the Fourier transform, the following equations are obtained:

\[
k_{co}^2\tilde{\phi}_1(x, h_1) = k_{c2}^2\tilde{\phi}_2(x, h_1), \quad (2A.2a)
\]

\[
-jx\gamma\tilde{\phi}_1(x, h_1) - j\omega\mu_0 \frac{\partial}{\partial y}\tilde{\psi}_1(x, h_1) = -jx\gamma\tilde{\phi}_2(x, h_1) - j\omega\mu_0 \frac{\partial}{\partial y}\tilde{\psi}_2(x, h_1), \quad (2A.2b)
\]
FIGURE 2.31 Computed characteristics of conventional coplanar waveguide, $\varepsilon_{r1} = 12.9$, $h_1 = 500 \mu m$: (a) The aspect ratio as a function of $Z_0$ with metallization thickness as parameter, $S + 2W = 25 \mu m$; (b) the aspect ratio as a function of $Z_0$ with $S + 2W$ as parameter, $t = 4 \mu m$; (c) the aspect ratio as a function normalized metallization thickness with $\varepsilon_{eff}$ as parameter, $S + 2W = 25 \mu m$. (From Reference [26]. © IEEE 1991.)
where

\[ \mu_1 = \mu_2 = \mu_3 = \mu_0, \]

\[ \varepsilon_1 = \varepsilon_3 = \varepsilon_0, \]

and

\[ \varepsilon_2 = \varepsilon_{r1} \text{ so that} \]

\[ k_{c1} = k_{c3} = k_{c0}. \]

The two Helmholtz Eqs. (2.57a) and (2.57b) whose solutions are Eqs. (2.67) and (2.68) are now substituted into Eqs. (2A.1) and (2A.2). The coefficients \( A^e \) through \( D^h \) are functions of \( x \) as indicated within parenthesis. However, to keep
the notations simple, within the parentheses $x$ with the coefficients is omitted in the mathematical steps that follow:

\[
k_{c2}^2 C^e = k_{c0}^2 D^e, \tag{2A.3a}
\]

\[-jx_1 C^e - j\omega \mu_0 \gamma^2_2 B^h = -jx_1 D^e - j\omega_0 \gamma^2_2 D^h, \tag{2A.3b}
\]

\[k_{c2}^2 C^h = k_{c0}^2 D^h, \tag{2A.3c}
\]

\[-jx_1 C^h + j\omega \epsilon_0 \gamma^2_2 B^e = -jx_1 D^h + j\omega_0 D^e, \tag{2A.3d}
\]

\[k_{c0}^2 A^e = k_{c2}^2 \left[ B^e \sinh \gamma^2 h_1 + C^e \cosh \gamma^2 h_1 \right], \tag{2A.3a}
\]

\[-jx_1 A^e + j\omega \mu_0 \gamma^2_1 A^h = -jx_1 \left[ B^e \sinh \gamma^2 h_1 + C^e \cosh \gamma^2 h_1 \right]
\]

\[-j\omega_0 \gamma^2_1 \left[ B^h \cosh \gamma^2 h_1 + C^h \sinh \gamma^2 h_1 \right], \tag{2A.3b}
\]

\[k_{c0}^2 A^h = \tilde{E}_x(z), \tag{2A.3c}
\]

\[-jx_1 A^h + j\omega \mu_0 \gamma^2_1 A^e = \tilde{E}_x(z), \tag{2A.3d}
\]

\[k_{c0}^2 A^h - k_{c2}^2 \left[ B^h \sinh \gamma^2 h_1 + C^h \cosh \gamma^2 h_1 \right] = \tilde{D}_x(z), \tag{2A.3e}
\]

\[-jx_1 A^h - j\omega_0 \gamma^2_1 A^e + jx_1 \left[ B^h \sinh \gamma^2 h_1 + C^h \cosh \gamma^2 h_1 \right] - j\omega_0 \gamma^2_1 \times \left[ B^e \cosh \gamma^2 h_1 + C^e \sinh \gamma^2 h_1 \right] = \tilde{D}_x(z). \tag{2A.3f}
\]

In the mathematical steps that follow, the unknown coefficients $A^e$ through $A^h$ are replaced to obtain a direct relation between the current density and the electric field components.

From Eqs. (2A.3a) and (2A.3c),

\[D^e = \left( \frac{k_{c2}}{k_{c0}} \right)^2 C^e, \tag{2A.5}
\]

\[D^h = \left( \frac{k_{c2}}{k_{c0}} \right)^2 C^h. \tag{2A.6}
\]

Substituting $D^e$ and $D^h$ into Eqs. (2A.3b) and (2A.3d), $B^h$ and $B^e$ are expressed as

\[B^h = \frac{x_1}{\omega \mu_0 \gamma^2_2} \left[ \left( \frac{k_{c2}}{k_{c0}} \right)^2 - 1 \right] C^e + \frac{\gamma^2_3}{\gamma^2_2} \left( \frac{k_{c2}}{k_{c0}} \right)^2 C^h, \tag{2A.7}
\]

\[B^e = -\frac{x_1}{\omega \mu_0 \gamma^2_2} \left[ \left( \frac{k_{c2}}{k_{c0}} \right)^2 - 1 \right] \mu_0 \epsilon_2 C^h + \frac{\gamma^2_3}{\gamma^2_2} \left( \frac{k_{c2}}{k_{c0}} \right)^2 \frac{\epsilon_0}{\epsilon_2} C^e. \tag{2A.8}
\]

Let us define two new variables $F_1$ and $F_2$ such that

\[F_1 = \frac{x_1}{\omega \mu_0 \gamma^2_2} \left[ \left( \frac{k_{c2}}{k_{c0}} \right)^2 - 1 \right], \tag{2A.9}
\]
With these substitutions the equations for $B^h$ and $B^e$ simplify to

$$B^h = F_1 C^e + F_2 C^h,$$  \hspace{1cm} (2A.11)

$$B^e = \frac{\varepsilon_0}{\varepsilon_2} F_2 C^e - \frac{\mu_0}{\varepsilon_2} F_1 C^h.$$  \hspace{1cm} (2A.12)

Substitute Eq. (2A.12) into Eq. (2A.4a) to obtain

$$A^e = \left(\frac{k_{e2}}{k_{c0}}\right)^2 \left(\frac{\varepsilon_0}{\varepsilon_2} F_2 \sinh \gamma_2 h_1 + \cosh \gamma_2 h_1\right) C^e - \left\{\left(\frac{k_{e2}}{k_{c0}}\right)^2 \frac{\mu_0}{\varepsilon_2} F_1 \sinh \gamma_2 h_1\right\} C^h.$$  \hspace{1cm} (2A.13)

Define two new variables $G_1$ and $G_2$ as follows:

$$G_1 = \left(\frac{k_{e2}}{k_{c0}}\right)^2 \left(\frac{\varepsilon_0}{\varepsilon_2} F_2 \sinh \gamma_2 h_1 + \cosh \gamma_2 h_1\right),$$  \hspace{1cm} (2A.14)

$$G_2 = -\left(\frac{k_{e2}}{k_{c0}}\right)^2 \frac{\mu_0}{\varepsilon_2} F_1 \sinh \gamma_2 h_1.$$  \hspace{1cm} (2A.15)

With these substitutions

$$A^e = G_1 C^e + G_2 C^h.$$  \hspace{1cm} (2A.16)

Substitute Eqs. (2A.11), (2A.12), and (2A.16) into Eq. (2A.4b) to obtain

$$A^h = \left[\frac{\gamma^2}{\omega \mu_0 \gamma_1} \left( G_1 - \frac{\varepsilon_0}{\varepsilon_2} F_2 \sinh \gamma_2 h_1 - \cosh \gamma_2 h_1\right) - \frac{\gamma_2}{\gamma_1} F_1 \cosh \gamma_2 h_1\right] C^e$$

$$+ \left[\frac{\gamma^2}{\omega \mu_0 \gamma_1} \left( G_2 + \frac{\mu_0}{\varepsilon_2} F_1 \sinh \gamma_2 h_1\right) - \frac{\gamma_2}{\gamma_1} (F_2 \cosh \gamma_2 h_1 + \sinh \gamma_2 h_1)\right] C^h.$$  \hspace{1cm} (2A.17)

Define two new variables $G_3$ and $G_4$ as follows:

$$G_3 = \frac{\gamma^2}{\omega \mu_0 \gamma_1} \left( G_1 - \frac{\varepsilon_0}{\varepsilon_2} F_2 \sinh \gamma_2 h_1 - \cosh \gamma_2 h_1\right) - \frac{\gamma_2}{\gamma_1} F_1 \cosh \gamma_2 h_1,$$  \hspace{1cm} (2A.18)

$$G_4 = \frac{\gamma^2}{\omega \mu_0 \gamma_1} \left( G_2 + \frac{\mu_0}{\varepsilon_2} F_1 \sinh \gamma_2 h_1\right) - \frac{\gamma_2}{\gamma_1} (F_2 \cosh \gamma_2 h_1 + \sinh \gamma_2 h_1).$$  \hspace{1cm} (2A.19)
Then
\[ A^h = G_3 C^e + G_4 C^h. \] (2A.20)

Equations (2A.16) and (2A.20) are rewritten in matrix form as
\[
\begin{bmatrix}
G_1 & G_2 \\
G_3 & G_4
\end{bmatrix}
\begin{bmatrix}
C^e \\
C^h
\end{bmatrix}
= 
\begin{bmatrix}
A^e \\
A^h
\end{bmatrix},
\] (2A.21a)

that is,
\[ [G][C] = [A]. \] (2A.21b)

Inverting the \([G]\) and solving for \([C]\) yields
\[ [C] = [G]^{-1}[A]. \] (2A.22a)

That is,
\[
C^e = J_1 A^e + J_2 A^h, \] (2A.22b)
\[
C^h = J_3 A^e + J_4 A^h, \] (2A.22c)

where
\[
\begin{align*}
J_1 &= G_4/\det G \\
J_2 &= -G_2/\det G \\
J_3 &= -G_3/\det G \\
J_4 &= G_1/\det G
\end{align*}
\]

with \(\det G = G_1 G_4 - G_2 G_3\).

Substituting Eqs. (2A.22b) and (2A.22c) into Eqs. (2A.11) and (2A.12), we have
\[
B^e = \left( \frac{\varepsilon_0}{\varepsilon_2} F_2 J_1 - \frac{\mu_0}{\varepsilon_2} F_1 J_3 \right) A^e + \left( \frac{\varepsilon_0}{\varepsilon_2} F_2 J_2 - \frac{\mu_0}{\varepsilon_2} F_1 J_4 \right) A^h, \] (2A.23)
\[
B^h = (F_1 J_1 + F_2 J_3) A^e + (F_1 J_2 + F_2 J_4) A^h. \] (2A.24)

Define the four new variables \(K_1, K_2, K_3, \) and \(K_4\) as follows:
\[
K_1 = \frac{\varepsilon_0}{\varepsilon_2} F_2 J_1 - \frac{\mu_0}{\varepsilon_2} F_1 J_3, \] (2A.25a)
\[ K_2 = \frac{\varepsilon_0}{\varepsilon_2} F_2 j_2 - \frac{\mu_0}{\varepsilon_2} F_1 j_4, \quad (2A.25b) \]
\[ K_3 = F_1 j_1 + F_2 j_3, \quad (2A.25c) \]
\[ K_4 = F_1 j_2 + F_2 j_4. \quad (2A.25d) \]

Then

\[ B^e = K_1 A^e + K_2 A^h, \quad (2A.26a) \]
\[ B^h = K_3 A^e + K_4 A^h. \quad (2A.26b) \]

Substitute Eqs. (2A.22b), (2A.22c), (2A.26a), and (2A.26b) into Eqs. (2A.4e) and (2A.4f) to obtain

\[-k_{e2}^2 (K_3 \sinh \gamma_2 h_1 + J_3 \cosh \gamma_2 h_1) A^e + k_{e0}^2 \left[ 1 - \frac{k_{e2}^2}{k_{e0}^2} (K_4 \sinh \gamma_2 h_1 + J_4 \cosh \gamma_2 h_1) \right] A^h = \tilde{f}_s(x), \quad (2A.27a)\]

\[ j\omega_{e0} \gamma_1 \left\{ \frac{\gamma_1}{\omega_{e0} \gamma_1} - (K_3 \sinh \gamma_2 h_1 + J_3 \cosh \gamma_2 h_1) \right. \]
\[ - \frac{\varepsilon_2}{\varepsilon_0} \gamma_2 (K_1 \cosh \gamma_2 h_1 + J_1 \sinh \gamma_2 h_1) - 1 \left\} A^e \]
\[ + j\omega_{e2} \gamma_2 \right\{ \frac{\gamma_2}{\omega_{e2} \gamma_2} - (K_4 \sinh \gamma_2 h_1 + J_4 \cosh \gamma_2 h_1 - 1) \right. \]
\[ - (K_2 \cosh \gamma_2 h_1 + J_2 \sinh \gamma_2 h_1) \left\} A^h = \tilde{f}_s(x) \quad (2A.27b) \]

Define four new variables \( L_1, L_2, L_3, \) and \( L_4 \) as follows:

\[ L_1 = -(K_3 \sinh \gamma_2 h_1 + J_3 \cosh \gamma_2 h_1), \quad (2A.28a) \]
\[ L_2 = 1 - \left( \frac{k_{e2}}{k_{e0}} \right)^2 (K_4 \sinh \gamma_2 h_1 + J_4 \cosh \gamma_2 h_1), \quad (2A.28b) \]
\[ L_3 = \frac{\gamma_1}{\omega_{e0} \gamma_1} (K_3 \sinh \gamma_2 h_1 + J_3 \cosh \gamma_2 h_1) \]
\[ - \frac{\varepsilon_2}{\varepsilon_0} \gamma_2 (K_1 \cosh \gamma_2 h_1 + J_1 \sinh \gamma_2 h_1) - 1, \quad (2A.28c) \]
\[ L_4 = \frac{\gamma_2}{\omega_{e2} \gamma_2} (K_4 \sinh \gamma_2 h_1 + J_4 \cosh \gamma_2 h_1 - 1) \]
\[ - (K_2 \cosh \gamma_2 h_1 + J_2 \sinh \gamma_2 h_1). \quad (2A.28d) \]
Then
\[ k_{c_2}^2 L_1 A^e + k_{c_0}^2 L_2 A^h = \tilde{J}_x(x), \]  
(2A.29a)
\[ j \omega \varepsilon_0 \gamma_1 L_3 A^e + j \omega \varepsilon_2 \gamma_2 L_4 A^h = \tilde{J}_z(x). \]  
(2A.29b)

Equations (2A.29a) and (2A.29b) are rewritten in matrix form as
\[
\begin{bmatrix}
  k_{c_2}^2 & k_{c_0}^2 L_2 \\
  j \omega \varepsilon_0 \gamma_1 L_3 & j \omega \varepsilon_2 \gamma_2 L_4
\end{bmatrix}
\begin{bmatrix}
  A^e \\
  A^h
\end{bmatrix}
= \begin{bmatrix}
  \tilde{J}_x(x) \\
  \tilde{J}_z(x)
\end{bmatrix}
\]  
(2A.29c)

that is,
\[ [L][A] = [J]. \]  
(2A.29d)

Inverting the [L] and solving for [A] yields \( A^e \) and \( A^h \) in terms of the current density components
\[ [A] = [L]^{-1}[J]. \]  
(2A.30a)

That is,
\[ A^e = \frac{j \omega \varepsilon_2 \gamma_2 L_4}{\det L} \tilde{J}_x(x) - \frac{k_{c_0}^2 L_2}{\det L} \tilde{J}_z(x), \]  
(2A.30b)
\[ A^h = -\frac{j \omega \varepsilon_0 \gamma_1 L_3}{\det L} \tilde{J}_x(x) + \frac{k_{c_2}^2 L_1}{\det L} \tilde{J}_z(x), \]  
(2A.30c)

where
\[ \det L = j \omega \varepsilon_2 \gamma_2 k_{c_0}^2 \left[ \left( \frac{k_{c_2}}{k_{c_0}} \right)^2 L_1 L_4 - \frac{\varepsilon_0}{\varepsilon_2} \gamma_1 L_2 L_3 \right]. \]  
(2A.30d)

When \( A^e \) and \( A^h \) are substituted in Eqs. (2A.4c) and (2A.4d), all the unknown coefficients are eliminated, and the electric-field components are expressed in terms of the current density components:
\[ \left( \frac{x \gamma_1 \omega \varepsilon_2 \gamma_2 L_4}{\det L} + \frac{\omega^2 \mu_0 \varepsilon_0 \gamma_1^2 L_3}{\det L} \right) \tilde{J}_x(x) + \left( \frac{j \omega \gamma_1 k_{c_0}^2 L_2}{\det L} + \frac{j \omega \mu_0 \gamma_1 k_{c_1}^2 L_1}{\det L} \right) \tilde{J}_z(x) = \tilde{E}_x(x), \]  
(2A.31)
\[ \left( \frac{k_{c_0}^2 \omega \varepsilon_2 \gamma_2 L_4}{\det L} \right) \tilde{J}_x(x) - \left( \frac{k_{c_0}^4 L_2}{\det L} \right) \tilde{J}_z(x) = \tilde{E}_z(x). \]  
(2A.32)
Define five new variables $M_1$, $M_2$, $M_3$, $M_4$, and $M_5$ as follows:

\[
M_1 = \left( -\frac{j\gamma y}{k_{c0}} L_4 - \frac{j\omega \mu_0 e_0 \gamma_1}{k_{c0}^2 e_3} L_3 \right) \frac{1}{M_5}, \tag{2A.33}
\]

\[
M_2 = \left( \frac{\gamma y}{\omega e_2 \gamma_2} L_2 + \frac{\mu_0 \gamma_1}{e_2 \gamma_2} \left( \frac{k_{c1}}{k_{c0}} \right)^2 L_1 \right) \frac{1}{M_5}, \tag{2A.34}
\]

\[
M_3 = \frac{L_4}{M_5}, \tag{2A.35}
\]

\[
M_4 = \frac{j k_{c0}^2}{\omega e_2 \gamma_2} \frac{L_2}{M_5}, \tag{2A.36}
\]

\[
M_5 = \left( \frac{k_{c2}}{k_{c0}} \right)^2 L_1 L_4 - \frac{\varepsilon_0 \gamma_1}{e_2 \gamma_2} L_2 L_3. \tag{2A.37}
\]

Then

\[
\begin{bmatrix}
M_1 & M_2 \\
M_3 & M_4
\end{bmatrix}
\begin{bmatrix}
J_x \\
J_z
\end{bmatrix} =
\begin{bmatrix}
E_x \\
E_z
\end{bmatrix}. \tag{2A.38}
\]

**APPENDIX 2B: TIME AVERAGE POWER FLOW IN THE THREE SPATIAL REGIONS**

The expressions for the time average power flow in the three spatial regions indicated in Figure 2.13(a) are derived from Eq. (2.90). The first step is to substitute the solutions to the Helmholtz’s equations, namely, Eqs. (2.67) and (2.68) into Eq. (2.90). There are eight terms under the double integral sign. The double integral is reduced to a single integral by performing the integration with respect to $y$ analytically. Analogous to Appendix 2A, within parentheses $\pi$ associated with the coefficients $A^n$ through $D^h$ is omitted. Further $\mu_1 = \mu_2 = \mu_3 = \mu_0$, $\varepsilon_1 = \varepsilon_3 = \varepsilon_0$, and $\varepsilon_2 = \varepsilon_{r1}$. Hence from Eqs. (2.57c) and (2.66), $\omega^2 \mu_i \varepsilon_i = k_i^2$ ($i = 1, 2, 3$), $k_1 = k_3 = k_0$, and $\gamma_1 = \gamma_3$. The tilde and the asterisk denote transform and complex conjugate, respectively.

**Region 1, $h_1 \leq y \leq \infty$** The integration with respect to $y$ is shown below for each of the eight terms of Eq. (2.90):

\[
\frac{1}{4\pi} \Re \int_{-\infty}^{+\infty} \int_{h_1}^{+\infty} -\alpha^2 \beta \omega e_1 |\tilde{\phi}_1|^2 dy dz = \frac{1}{4\pi} \Re \int_{-\infty}^{+\infty} \int_{h_1}^{+\infty} \alpha^2 \beta \omega e_0 |A^n \exp[ -\gamma_1 (y - h_1)]|^2 dy dz,
\]
\[ I_{11} = -\frac{1}{4\pi} \text{Re} \int_{-\infty}^{+\infty} \frac{x^2}{2\gamma_1} \beta \omega \mu_0 |A|^2 \, dx; \quad (2B.1) \]

\[ \frac{1}{4\pi} \text{Re} \int_{-\infty}^{+\infty} \int_{h_1}^{+\infty} -\beta \omega \mu_1 \frac{\partial \psi_1}{\partial y}^2 \, dy \, dx \]

\[ = -\frac{1}{4\pi} \text{Re} \int_{-\infty}^{+\infty} \int_{h_1}^{+\infty} \beta \omega \mu_0 |A^h| \{ \exp - \gamma_1(y - h_1) \} |(-\gamma_1)|^2 \, dy \, dx, \]

\[ I_{12} = -\frac{1}{4\pi} \text{Re} \int_{-\infty}^{+\infty} \frac{\beta \omega \mu_0 \gamma_1^2}{2\gamma_1} |A^h|^2 \, dx; \quad (2B.2) \]

\[ \frac{1}{4\pi} \text{Re} \int_{-\infty}^{+\infty} \int_{h_1}^{+\infty} -\beta \omega \mu_1 \frac{\partial \phi_1}{\partial y}^2 \, dy \, dx \]

\[ = -\frac{1}{4\pi} \text{Re} \int_{-\infty}^{+\infty} \int_{h_1}^{+\infty} \beta \omega \mu_0 |A^e| \{ \exp - \gamma_1(y - h_1) \} |(-\gamma_1)|^2 \, dy \, dx, \]

\[ I_{13} = -\frac{1}{4\pi} \text{Re} \int_{-\infty}^{+\infty} \frac{\beta \omega \mu_0 \gamma_1^2}{2\gamma_1} |A^e|^2 \, dx; \quad (2B.3) \]

\[ \frac{1}{4\pi} \text{Re} \int_{-\infty}^{+\infty} \int_{h_1}^{+\infty} -x^2 \beta \omega \mu_1 |\tilde{\psi}_1|^2 \, dy \, dx \]

\[ = -\frac{1}{4\pi} \text{Re} \int_{-\infty}^{+\infty} \int_{h_1}^{+\infty} x^2 \beta \omega \mu_0 |A^e| \exp[-\gamma_1(y - h_1)]^2 \, dy \, dx, \]

\[ I_{14} = -\frac{1}{4\pi} \text{Re} \int_{-\infty}^{+\infty} \frac{x^2 \beta \omega \mu_0}{2\gamma_1} |A^e|^2 \, dx; \quad (2B.4) \]

\[ \frac{1}{4\pi} \text{Re} \int_{-\infty}^{+\infty} \int_{h_1}^{+\infty} -jx \beta^2 \frac{\partial \tilde{\psi}_1}{\partial y} \, dy \, dx \]

\[ = -\frac{1}{4\pi} \text{Re} \int_{-\infty}^{+\infty} \int_{h_1}^{+\infty} jx \beta^2 A^e \exp[-\gamma_1(y - h_1)] \]

\[ \times [A^h\{ \exp - \gamma_1(y - h_1) \}(-\gamma_1)]^* \, dy \, dx, \]

\[ I_{15} = \frac{1}{4\pi} \text{Re} \int_{-\infty}^{+\infty} \frac{jx \beta^2}{2} A^e[A^h]^* \, dx; \quad (2B.5) \]

\[ \frac{1}{4\pi} \text{Re} \int_{-\infty}^{+\infty} \int_{h_1}^{+\infty} -jx \beta^2 \frac{\partial \tilde{\phi}_1}{\partial y} \, dy \, dx \]

\[ = -\frac{1}{4\pi} \text{Re} \int_{-\infty}^{+\infty} \int_{h_1}^{+\infty} jx \beta^2 A^e \{ \exp - \gamma_1(y - h_1) \}(-\gamma_1) \]

\[ \times [A^h\{ \exp[-\gamma_1(y - h_1)] \}]^* \, dy \, dx, \]

\[ I_{16} = \frac{1}{4\pi} \text{Re} \int_{-\infty}^{+\infty} \frac{jx \beta^2}{2} A^e[A^h]^* \, dx; \quad (2B.6) \]


\[
\frac{1}{4\pi} \text{Re} \int_{-\infty}^{+\infty} \int_{h_1}^{+\infty} jxk_1^2 \bar{\phi}_1^* \frac{\partial \bar{\psi}_1}{\partial y} \, dy \, dx = \frac{1}{4\pi} \text{Re} \int_{-\infty}^{+\infty} \int_{h_1}^{+\infty} jxk_0^2 [A^e \exp(-\gamma_1(y - h_1))]^* \\
\times [A^b \{\exp - \gamma_1(y - h_1)(-\gamma_1)\}] \, dy \, dx,
\]

\[
I_{17} = -\frac{1}{4\pi} \text{Re} \int_{-\infty}^{+\infty} \frac{jxk_0^2}{2} [A^e]^*A^b \, dx; \quad (2B.7)
\]

\[
\frac{1}{4\pi} \text{Re} \int_{-\infty}^{+\infty} \int_{h_1}^{+\infty} jxk_1^2 \frac{\partial \bar{\phi}_1^*}{\partial y} \bar{\psi}_1 \, dy \, dx = \frac{1}{4\pi} \int_{-\infty}^{+\infty} \int_{h_1}^{+\infty} jxk_0^2 [A^e \{\exp - \gamma_1(y - h_1)\}(-\gamma_1)]^* \\
\times [A^b \exp(-\gamma_1(y - h_1))] \, dy \, dx,
\]

\[
I_{18} = -\frac{1}{4\pi} \text{Re} \int_{-\infty}^{+\infty} \frac{jxk_0^2}{2} [A^e]^*A^b \, dx. \quad (2B.8)
\]

Substituting Eqs. (2B.1) to (2B.8) into Eq. (2.90), the following expression for \( P_{\text{avg}} \) in region 1 is obtained:

\[
P_{\text{avg}} = -\frac{1}{8\pi} \text{Re} \int_{-\infty}^{+\infty} \left[ \frac{x^2 + \gamma_1^2}{2\gamma_1} (\varepsilon_0|A^e|^2 + \mu_0|A^h|^2) \right. \\
\left. + j2\lambda(k_0^2|A^e|^*A^h - \beta^2 A^e[A^h]^*) \right] \, dx. \quad (2B.9)
\]

A negative sign in front of the integral sign is because a wave propagating in the \(-z\)-direction is assumed.

**Region 2, \( 0 \leq y \leq h_1 \)** We first consider the case where \( \gamma_2^2 > 0 \) and \( \gamma_2 \) is real. The integration with respect to \( y \) is shown below for each of the eight terms of Eq. (2.90):

\[
\frac{1}{4\pi} \text{Re} \int_{-\infty}^{+\infty} \int_{0}^{h_1} -x^2 \beta \varepsilon_2 \bar{\phi}_2^2 \, dy \, dx = \frac{1}{4\pi} \text{Re} \int_{-\infty}^{+\infty} \int_{0}^{h_1} -x^2 \beta \varepsilon_2 (B^e \sinh \gamma_2 y + C^e \cosh \gamma_2 y) \\
\times (B^e* \sinh \gamma_2 y + C^e* \cosh \gamma_2 y) \, dy \, dx,
\]
\[
I_{21} = \frac{1}{4\pi} \Re \int_{-\infty}^{+\infty} \int_{0}^{h_1} -\alpha^2 \beta \omega \mu_2 |\vec{\psi}_2|^2 \left\{ (|B^e|^2 + |C^e|^2) \frac{\sinh 2\gamma_2 h_1}{4\gamma_2} + \left( \frac{B^e C^{e*} + C^e B^{e*}}{2} \right) \frac{(\cosh 2\gamma_2 h_1 - 1)}{2\gamma_2} + (|C^e|^2 - |B^e|^2) \frac{h_1}{2} \right\} dx;
\]

(2B.10)

\[
\frac{1}{4\pi} \Re \int_{-\infty}^{+\infty} \int_{0}^{h_1} -\alpha^2 \beta \omega \mu_2 |\vec{\psi}_2|^2 \frac{dy}{dx}
\]

\[
= \frac{1}{4\pi} \Re \int_{-\infty}^{+\infty} \int_{0}^{h_1} -\alpha^2 \beta \omega \mu_0 \left( |B^h|^2 \sinh \gamma_2 y + C^h \cosh \gamma_2 y \right) \times (B^h* \sinh \gamma_2 y + C^h* \cosh \gamma_2 y) dy dx;
\]

\[
I_{22} = \frac{1}{4\pi} \Re \int_{-\infty}^{+\infty} \int_{0}^{h_1} -\alpha^2 \beta \omega \mu_0 \left\{ (|B^h|^2 + |C^h|^2) \frac{\sinh 2\gamma_2 h_1}{4\gamma_2} + \left( \frac{B^h C^{h*} + C^h B^{h*}}{2} \right) \frac{(\cosh 2\gamma_2 h_1 - 1)}{2\gamma_2} + (|C^h|^2 - |B^h|^2) \frac{h_1}{2} \right\} dx;
\]

(2B.11)

\[
\frac{1}{4\pi} \Re \int_{-\infty}^{+\infty} \int_{0}^{h_1} -\beta \omega \mu_2 |\frac{\partial \vec{\psi}_2}{\partial y}|^2 \frac{dy}{dx}
\]

\[
= \frac{1}{4\pi} \Re \int_{-\infty}^{+\infty} \int_{0}^{h_1} -\beta \omega \mu_0 \gamma_2^2 (B^h \cosh \gamma_2 y + C^h \sinh \gamma_2 y) \times (B^h* \cosh \gamma_2 y + C^h* \sinh \gamma_2 y) dy dx;
\]

\[
I_{23} = \frac{1}{4\pi} \Re \int_{-\infty}^{+\infty} \int_{0}^{h_1} -\beta \omega \mu_0 \gamma_2^2 \left\{ (|B^h|^2 + |C^h|^2) \frac{\sinh 2\gamma_2 h_1}{4\gamma_2} + \left( \frac{B^h C^{h*} + C^h B^{h*}}{2} \right) \frac{(\cosh 2\gamma_2 h_1 - 1)}{2\gamma_2} + (|B^h|^2 - |C^h|^2) \frac{h_1}{2} \right\} dx;
\]

(2B.12)

\[
\frac{1}{4\pi} \Re \int_{-\infty}^{+\infty} \int_{0}^{h_1} -\beta \omega \mu_2 |\frac{\partial \vec{\phi}_2}{\partial y}|^2 \frac{dy}{dx}
\]

\[
= \frac{1}{4\pi} \Re \int_{-\infty}^{+\infty} \int_{0}^{h_1} -\beta \omega \mu_2 \gamma_2^2 (B^e \cosh \gamma_2 y + C^e \sinh \gamma_2 y) \times (B^{e*} \cosh \gamma_2 y + C^{e*} \sinh \gamma_2 y) dy dx,
\]
Equations (2B.10) through (2B.13) which correspond to the first four terms of Eq. (2.90), when combined together, result in the following equation:

\[
I_{21} + I_{22} + I_{23} + I_{24} = \frac{1}{4\pi} \Re \left[ \int_{-\infty}^{+\infty} -\beta \omega \gamma_2^2 \left( \left( |B|^2 + |C|^2 \right) \frac{\sinh 2\gamma_2 h_1}{\gamma_2} \right. \right. \\
+ \left. \left. \left( \frac{B^* C^* + C^* B^*}{2} \right) \left( \cosh 2\gamma_2 h_1 - 1 \right) + \left( |B|^2 - |C|^2 \right) \frac{h_1}{2} \right) \right] dx.
\] (2B.13)

Continuing the integration process, the fifth through eighth terms of Eq. (2.90) are as follows:

\[
I_{25} = \frac{1}{4\pi} \Re \left[ \int_{-\infty}^{+\infty} \int_{0}^{h_1} -j\alpha \beta^2 \phi \frac{\partial \tilde{\psi}^*}{\partial y} dy dx \right.
\]
\[
= \frac{1}{4\pi} \Re \left[ \int_{-\infty}^{+\infty} \int_{0}^{h_1} -j\alpha \beta^2 \gamma_2 (B^* \sinh \gamma_2 y + C^* \cosh \gamma_2 y) \right.
\]
\[
	imes (B^{h*} \cosh \gamma_2 y + C^{h*} \sinh \gamma_2 y) dy dx,
\]
\[
I_{25} = -\frac{1}{4\pi} \Re \left[ \int_{-\infty}^{+\infty} \int_{0}^{h_1} j\alpha \beta^2 \left( \sinh 2\gamma_2 h_1 \right) \left( \frac{B^* C^{h*} + C^* B^{h*}}{4} \right) \right.
\]
\[
+ \left. \left( \cosh 2\gamma_2 h_1 - 1 \right) \frac{B^* B^{h*} + C^* C^{h*}}{2} + \left( C^* B^{h*} - B^* C^{h*} \right) \frac{\gamma_2 h_1}{2} \right] dx.
\] (2B.15)
\[ I_{26} = -\frac{1}{4\pi} \text{Re} \int_{-\infty}^{+\infty} jx \beta^2 \left\{ \frac{\sinh 2\gamma_2 h_1}{4} \left( B^e C^{h*} + C^e B^{h*} \right) \\
+ \left( \frac{\cosh 2\gamma_2 h_1}{2} \right) \left( \frac{B^e B^{h*} + C^e C^{h*}}{2} \right) \right\} dx; \]

\[ \frac{1}{4\pi} \text{Re} \int_{-\infty}^{+\infty} \int_{0}^{h_1} jx k^2 \left( \phi^* \frac{\partial \tilde{\psi}}{\partial y} + \frac{\partial \tilde{\phi}^*}{\partial y} \tilde{\psi} \right) dy dx \]

\[ = \frac{1}{4\pi} \text{Re} \int_{-\infty}^{+\infty} \int_{0}^{h_1} jx k^2 \gamma_2 \times [(B^e \sinh \gamma_2 y + C^{h*} \cosh \gamma_2 y) \\
x (B^h \cosh \gamma_2 y + C^h \sinh \gamma_2 y) + (B^{h*} \cosh \gamma_2 y + C^e \sinh \gamma_2 y) \\
x (B^h \sinh \gamma_2 y + C^h \cosh \gamma_2 y)] dxdy, \]

\[ I_{27} + I_{28} = \frac{1}{4\pi} \text{Re} \int_{-\infty}^{+\infty} jx k^2 \left\{ (B^e B^h + C^e C^h) \left( \frac{\cosh 2\gamma_2 h_1}{2} - 1 \right) \\
+ (B^e C^h + C^e B^h) \frac{\sinh 2\gamma_2 h_1}{2} \right\} dx. \] (2B.17)

Combining Eqs. (2B.15) through (2B.17) results in the following:

\[ I_{25} + I_{26} + I_{27} + I_{28} \]

\[ = -\frac{1}{4\pi} \text{Re} \int_{-\infty}^{+\infty} jx \left\{ \frac{\sinh 2\gamma_2 h_1}{2} \left[ \beta^2 (B^e C^{h*} + C^e B^{h*}) - k^2 (B^e B^h + C^e C^h) \right] \right\} dx; \]

\[ \times \left( \frac{\cosh 2\gamma_2 h_1}{2} - 1 \right) \left[ \beta^2 (B^e B^{h*} + C^e C^{h*}) - k^2 (B^e B^h + C^e C^h) \right] \right\} dx. \] (2B.18)

Last, combining Eqs. (2B.14) and (2B.18), the expression for \( P_{\text{avg}} \) in region 2 is obtained:

\[ P_{\text{avg}} = -\frac{1}{4\pi} \text{Re} \int_{-\infty}^{+\infty} \left\{ \frac{\omega \beta}{2} \left\{ \sinh 2\gamma_2 h_1 \left[ \frac{\alpha^2 + \gamma_2^2}{\gamma_2^2} (\varepsilon_2 (|B^e|^2 + |C^e|^2) \\
+ \mu_0 (|B^h|^2 + |C^h|^2)) \right] \right\} \right\} \]

\[ + h_1 (\alpha^2 - \gamma_2^2)[\varepsilon_2 (|C^e|^2 - |B^e|^2) + \mu_0 (|C^h|^2 - |B^h|^2)] \]

\[ + (\cosh 2\gamma_2 h_1 - 1) \left[ \frac{\alpha^2 + \gamma_2^2}{2\gamma_2^2} (\varepsilon_2 (B^e C^e + C^e B^{h*}) + \mu_0 (B^h C^{h*} + C^h B^{h*})) \right] \]}
\[ + \frac{j\gamma}{2} \left\{ \sinh 2\gamma h_1 \left[ \beta^2 (B^* C^{h*} + C^e B^{h*}) - k^2 (B^{e*} C^h + C^{e*} B^h) \right] \\
+ (\cosh 2\gamma h_1 - 1) \left[ \beta^2 (B^* B^{h*} + C^e C^{h*}) - k^2 (B^{e*} C^h + C^{e*} B^h) \right] \right\} \, dx \]

(2B.19)

A negative sign in front of the integral sign is because a wave propagating in the \(-z\)-direction is assumed.

**Region 3, \(-\infty \leq y \leq 0\)** Proceeding in a manner analogous to region 1, the \(P_{\text{avg}}\) is given by

\[
P_{\text{avg}} = -\frac{1}{8\pi} \Re \int_{-\infty}^{+\infty} \left[ \frac{\omega\beta}{\gamma_1} \left( \varepsilon_0 |D^e(z)|^2 + \mu_0 |D^h(z)|^2 \right) \\
+ j2x(\beta^2 D^e(z)[D^{h*}(z)]^* - k_0^2 [D^e(z)]^* D^h(z)) \right] \, dx. \quad (2B.20)
\]

**REFERENCES**


CHAPTER 3

Conductor-Backed Coplanar Waveguide

3.1 INTRODUCTION

This chapter presents the characteristics of a coplanar waveguide with a lower ground plane. The lower ground plane provides mechanical strength for a thin and fragile wafer, such as GaAs, and acts as a heat sink for circuits with active devices. This configuration of the CPW is known as the conductor-backed coplanar waveguide (CBCPW). There are several other variants of this basic structure, and these are presented in [1].

The chapter commences with expressions based on quasi-static analysis for the effective dielectric constant ($\varepsilon_{\text{eff}}$) and characteristic impedance ($Z_0$) of CBCPW with and without a top metal cover. The computed $\varepsilon_{\text{eff}}$ and $Z_0$ as a function of the center conductor strip width $S$ and slot width $W$ are presented. In addition the frequency dependant guide wavelength ratio $\lambda_g/\lambda_0$, where $\lambda_g$ and $\lambda_0$ are the guide wavelength and free space wavelength, respectively, and $Z_0$ is also presented for comparison. In Section 3.3, the effect of conducting lateral walls on the dominant mode of the CBCPW is discussed and the closed form equation to calculate the $Z_0$ is presented. The effect of lateral electric and magnetic walls on the higher order mode propagation constant is discussed in Section 3.4. Two cases are considered separately, first, perfect conductors and lossless dielectric, second, conductors with finite thickness, finite conductivity, and lossless or lossy dielectric.

In Section 3.5 a new variant of the CBCPW, namely the channelized coplanar waveguide (CCPW), is presented. In a CCPW, by judicious choice of the lateral wall separation, the dielectric filled rectangular waveguide mode is suppressed. Further, since the ground planes are electrically connected by the side walls to the conductor backing, the excitation of spurious parallel plate modes is eliminated.
In Section 3.6 realization of the lateral walls in a practical circuit by the use of metal-filled vias is explained. In the last section analytical closed form expressions describing the quasi-TEM field patterns in both the air and the dielectric regions of the CBCPW are presented. Experimental results to validate the theoretical results are presented in almost all of the sections.

The CBCPW in this chapter is assumed to be symmetric and fabricated on an isotropic homogeneous dielectric substrate of arbitrary thickness \( h \) and relative permittivity \( \varepsilon_r \). Further, if not specified, the substrate metallization and the metal cover are assumed to have perfect conductivity.

### 3.2 CONDUCTOR-BACKED COPLANAR WAVEGUIDE ON A DIELECTRIC SUBSTRATE OF FINITE THICKNESS

#### 3.2.1 Analytical Expressions Based on Quasi-static TEM Conformal Mapping Technique to Determine Effective Dielectric Constant and Characteristic Impedance

A CBCPW with ground planes infinite in the lateral direction is shown in Figure 3.1. A quasi-static TEM mode is assumed to propagate on this structure. Based on this approximation, Wen’s [2] analysis for conventional CPW is extended in [3] to [7] to the CBCPW. The analysis provides simple analytical expressions for \( \varepsilon_{\text{eff}} \) and \( Z_0 \) as a function of the geometry. These expressions are given below:

\[
\varepsilon_{\text{eff}} = \frac{1 + \varepsilon_r \frac{K(k')}{K(k)} \frac{K(k_3)}{K(k_3')}}{1 + \frac{K(k')}{K(k)} \frac{K(k_3)}{K(k_3')}},
\]

\( 3.1 \)

**FIGURE 3.1** Schematic of conductor backed coplanar waveguide (CBCPW).
\[ Z_0 = \frac{60\pi}{\sqrt{\varepsilon_{\text{eff}}} \frac{1}{K(k)} + \frac{K(k_3)}{K(k')}} \]  

where

\[ k = a/b \]
\[ k_3 = \frac{\tanh(\pi a/2h)/\tanh(\pi b/2h)}{\tanh(\pi a/2h)/\tanh(\pi b/2h)} \]
\[ k' = \sqrt{1.0 - k^2} \]
\[ k'_3 = \sqrt{1.0 - k^2_3} \]

and \( K(k) \) is the complete elliptic integral of the first kind. Figure 3.2(a) and (b) presents the computed \( \varepsilon_{\text{eff}} \) and \( Z_0 \), respectively, for the CBCPW.

### 3.2.2 Experimental Validation

The \( \varepsilon_{\text{eff}} \) and characteristic impedance are not directly measured, instead, they are calculated from the measured complex \( S \)-parameters of the through lines. This procedure is preferred because the \( S \)-parameters can be very accurately measured with the computer controlled network analyzer and a RF probe station. To obtain expressions that relate the \( \varepsilon_{\text{eff}} \) and characteristic impedance to the measured \( S \)-parameters [8], consider the uniform through line of length \( L \) shown in Figure 3.3(a). The complex propagation constant and characteristic impedance of the through line are \( \gamma \) and \( Z \), respectively. When signals of equal magnitude and phase are applied to the line at port 1 and port 2, the line is said to be excited in the even mode. For this excitation a magnetic wall (open circuit) is placed at the center, between port 1 and port 2, as shown in Figure 3.3(b). The total signal \( S_e \) leaving port 1 is therefore

\[ s_e = S_{11} + S_{12}. \]  

The signal \( S_e \) also can be viewed as the reflected signal by the magnetic wall and can be expressed as

\[ S_e = \frac{z \coth \gamma l - 1}{z \coth \gamma l + 1}, \]  

where \( \gamma = \alpha + j\beta \),

\[ l = \frac{L}{2}, \]
\[ z = \frac{Z}{Z_0}. \]
FIGURE 3.2 Computed characteristics of CBCPW as a function of the shape ratio $k = a/b$, with the normalized substrate thickness $h/b$ as a parameters, $\varepsilon_r = 10$: (a) Effective dielectric constant, $\varepsilon_{\text{eff}}$; (b) characteristic impedance, $Z_0$. (From Reference [4], copyright © IEE.)

In the equations above $\alpha$ and $\beta$ are the attenuation constant and the propagation constant of the through line, respectively, and $Z_0$ is the characteristic impedance of the input and output lines respectively. Equation (3.4) can be rewritten as

$$z \coth \gamma l = \frac{1 + S_s}{1 - S_e}. \quad (3.5)$$
FIGURE 3.3 Uniform transmission line: (a) Configuration; (b) even excitation; (c) odd excitation.

In a similar manner, assuming an odd-mode excitation, an electric wall (short circuit) is placed at the center as shown in Figure 3.3(c). The corresponding equations are

\[ S_0 = S_{11} - S_{12}. \]  \hspace{1cm} (3.6)

and

\[ z \tanh \gamma l = \frac{1 + S_0}{1 - S_0}. \]  \hspace{1cm} (3.7)
Equations (3.5) and (3.7), when taken together, yield the complex propagation constant and characteristic impedance of the line [8]:

$$\tanh^2 \gamma l = \frac{(1 + S_o)}{(1 - S_o)} \frac{(1 + S_e)}{(1 - S_e)} \quad (3.8)$$

and

$$z^2 = \frac{(1 + S_e)}{(1 - S_e)} \frac{(1 + S_o)}{(1 - S_o)} \quad (3.9)$$

To carry out the experiments, CBCPW through lines are fabricated on a 100 \(\mu\)m thick GaAs substrate \((\varepsilon_r = 12.9)\) [8]. To keep the attenuation due to conduction loss small, the metalization thickness is chosen to be greater than the skin depth. Hence the topside metal forming the center strip conductor and the coplanar ground planes are evaporated gold of 1.5 \(\mu\)m thickness. The bottom side metal is made thicker as in a practical circuit, where it serves as a good heat sink also. Thus the bottom side metal is gold plated to a thickness greater than 3 \(\mu\)m. Further, to ensure that the through lines supports only a quasi-static TEM mode, the topside coplanar ground planes are connected to the bottom ground plane by filled metal vias [8]. The metal vias short circuit the electric fields of the parasitic parallel-plate mode and thus suppress its propagation. Alternatively, the CPW through lines can be placed in a narrow metal channel, which serves the same purpose as the vias and is demonstrated in [9] and [10].

The dimensions of the through lines are summarized in Table 3.1. The theoretical \(\varepsilon_{\text{eff}}\) determined from Eq. (3.1) and \(\varepsilon_{\text{eff}}\) calculated from Eq. (3.8) using the measured S-parameters are found to be in good agreement up to about 20 GHz [8]. However, at very low frequencies, typically below 1 GHz, the experimental \(\varepsilon_{\text{eff}}\) is higher than the theoretical \(\varepsilon_{\text{eff}}\). Further this effect is more pronounced as the strip conductor width is reduced. This phenomenon
can be explained by the skin effect due to finite conductivity and finite thickness of the gold metal [8].

The theoretical characteristic impedance obtained from Eq. (3.2), which neglects the conductor thickness $t$, is observed to be higher than the characteristic impedance obtained from Eq. (3.9) using the measured S-parameters. In all practical circuits the conductor thickness is finite. Hence an effective center strip and slot widths are obtained by applying the following correction [8]:

$$\Delta = 1.25t \frac{1 + \ln(2h/t)}{\pi}. \quad (3.10)$$

The theoretical characteristics impedance after this correction is observed to be lower than the measured values. The correction factor over estimates the thickness effect. The theoretical characteristic impedance with and without the correction are also summarized in Table 3.1. In general, the metal thickness has more effect on the lines with narrower slot width.

### 3.2.3 Analytical Expressions for CBCPW $\varepsilon_{\text{eff}}$ and $Z_0$ in the Presence of a Top Metal Cover

A CBCPW with a top metal cover is shown in Figure 3.4. The $\varepsilon_{\text{eff}}$ and $Z_0$ for this structure are given by [5]

$$\varepsilon_{\text{eff}} = 1 + q_2(\varepsilon_r - 1), \quad (3.11)$$

where

$$q_2 = \left. \begin{array}{c} \frac{K(k_3)}{K(k_3')} \end{array} \right| \frac{K(k_3) + K(k_4)}{K(k_3')} \quad (3.12)$$

and

$$Z_0 = \frac{60\pi}{\sqrt{\varepsilon_{\text{eff}}} \frac{1}{K(k_3)} + \frac{K(k_4)}{K(k_3')}} \quad (3.13)$$
where $K(k)$ is the complete elliptical integral of the first kind. If the cover height $h_1$ tends to infinity, then $k_4$ tends to $a/b$, and the expressions above reduce to those in Section 3.2.1.

It is interesting to note that there are four limiting cases [6] for the CBCPW with a top metal cover. The first case as shown in Figure 3.5(a) is when the height of the cover $h_1$ is comparable to the substrate thickness $h$ and the slot width $W$ is less than the critical slot width $W_c$. The critical slot width is defined as a slot width $W_c$ beyond which the expressions for the microstrip line [11] and [12] can replace those of the CPW within a required accuracy [6]. This case is the normal CBCPW with a top metal cover.

The second case is when the height of the top metal cover $h_1$ is much greater than the substrate thickness $h$ but the slot width $W$ is still less than $W_c$. On this structure shown in Figure 3.5(b) propagation is similar to a CBCPW.

The third case is when the height of the cover $h_1$ is comparable to the substrate thickness $h$ but the slot width $W$ is much larger than $W_c$. Here propagation takes place as on a covered microstrip line [11] as shown in Figure 3.5(c).

The last case is when the height of the cover is much greater than the substrate thickness $h$ and the slot width $W$ is also much greater than $W_c$. On this structure propagation is as on a open microstrip line [12] as shown in Figure 3.5(d).
FIGURE 3.5 Limiting cases of CBCPW with top cover as the height of the cover and or the slot width varies: (a) Normal CBCPW with a top cover; (b) CBCPW; (c) microstrip line with top cover; (d) microstrip line.
3.2.4 Dispersion and Characteristic Impedance from Full-Wave Analysis

The CBCPW structure shown in Figure 3.1 without the top metal cover has also been analyzed assuming infinite lateral extent using spectral domain technique [13]. Figure 3.6(a) and (b) shows the computed guide wavelength...
CONDUCTOR-BACKED COPLANAR WAVEGUIDE

FIGURE 3.6 Computed normalized guide wavelength ratio $\lambda_g/\lambda_0$ as a function of the frequency: (a) Normalized slot width $W/2h$ as a parameter, $\varepsilon_r = 13$, $h = 150\mu\text{m}$, $S/2h = 1/3$; (b) normalized strip width $S/2h$ as a parameter, $\varepsilon_r = 13$, $S/2 = 100\mu\text{m}$, $W/S = 1/2$. (From Reference [13], copyright © IEE.)
ratio \( \frac{\lambda_g}{\lambda_0} \), where \( \lambda_g \) and \( \lambda_0 \) are the guide wavelength and free space wavelength, respectively, as a function of frequency with the slot width \( W \) and substrate thickness \( h \) as parameters. Since the CBCPW structure is a combination of both microstrip line and coplanar waveguide, the properties tend to approach that of a microstrip line or that of a coplanar waveguide depending on the dimensions. For example, for a fixed substrate thickness \( h \) as \( W \) increases, the ratio \( \frac{\lambda_g}{\lambda_0} \) approaches that of a microstrip line. On the other hand, for a fixed slot width \( W \) and as the substrate thickness \( h \) increases, the ratio \( \frac{\lambda_g}{\lambda_0} \) approaches that of a conventional coplanar waveguide (CPW). These properties are illustrated in Fig. 3.6(a) and (b).

The characteristic impedance is defined as [13]

\[
Z_0 = \frac{Z_{0\text{ (air)}}}{\left(\frac{\lambda_g}{\lambda_0}\right)}
\]

(3.14)

Where \( Z_{0\text{ (air)}} \) is the characteristic impedance when \( \varepsilon_r = 1 \). The computed \( Z_0 \) is shown in Figure 3.7.

### 3.3 EFFECT OF CONDUCTING LATERAL WALLS ON THE DOMINANT MODE PROPAGATION CHARACTERISTICS OF CBCPW AND CLOSED FORM EQUATIONS FOR \( Z_0 \)

The cross section of a CBCPW with conducting lateral walls is shown in Figure 3.8. Depending on the distance of separation, the walls interact with the fields guided by the CBCPW structure and modify its propagation characteristics. This structure has been analyzed using quasi-static TEM approximation [14], and the \( \varepsilon_{\text{eff}} \) and \( Z_0 \) are obtained by numerically solving Laplace’s equation.

In carrying out the computations the distance \( g \) of the side wall from the outer edge of the slot is set equal to \( S/2 + W \). With \( g \) equal to \( S/2 + W \) and the ratio \( S/(S + 2W) \leq 0.8 \), the computed \( Z_0 \) is within 1 percent of its value with \( g \) very large. This, ensures that the side walls have minimum effect on the propagation. The accuracy of this numerical method is determined by comparing the results in the microstrip limit, that is, when \( S/(S + 2W) \) approaches zero, and also in the coplanar limit, that is, when \( h/S \) approaches infinity with other results. For example, when \( \varepsilon_r = 9.9 \) and 12.9, the computed \( Z_0 \) in the microstrip limit agrees with [15] and [13] to within 1 and 7 percent, respectively. In the CPW limit as \( h/S \rightarrow \infty \), the results asymptotically approach [2].

Based on the solution above a closed form empirical expression is presented for \( Z_0 \) [14], [16] for the CPW geometry shown in Figure 3.8 as follows:

\[
Z_0 = \left[ \frac{5q}{1 + 5q} \cdot \frac{1}{Z_m} + \frac{1}{1 + q} \cdot \frac{1}{Z_c} \right]^{-1}
\]

(3.15)
FIGURE 3.7 Computed characteristic impedance $Z_0$ as a function of the normalized strip width $S/2h$ with the normalized slot width $W/2h$ as a parameter, $\varepsilon_r = 13$, $h = 150 \mu$m. (From Reference [13], copyright © IEE.)

FIGURE 3.8 Schematic of CBCPW with conducting lateral walls.
where

\[
q = \frac{S}{h} \left( \frac{S + 2W}{S} - 1 \right) \left\{ 3.6 - 2 \exp \left[ - \frac{(\varepsilon_r + 1)}{4} \right] \right\}. \tag{3.16}
\]

This function reproduces the microstrip impedance \(Z_m\) exactly as \(q\) goes to infinity, and similarly for the CPW impedance \(Z_c\) as \(q\) goes to zero.

Approximate expressions for \(Z_m\) and \(Z_c\) are given below [17].

For \(S/h \leq 1\)

\[
Z_m = \frac{\eta}{2\pi \sqrt{\varepsilon_{\text{eff}}}} \ln \left\{ \frac{8h}{S} + 0.25 \frac{S}{h} \right\}. \tag{3.17}
\]

For \(S/h \geq 1\),

\[
Z_m = \frac{\eta}{\sqrt{\varepsilon_{\text{eff}}}} \left\{ \frac{S}{h} + 1.393 + 0.667 \ln \left( \frac{S}{h} + 1.444 \right) \right\}^{-1}, \tag{3.18}
\]

where \(\eta = 120\pi \ \Omega\) and

\[
\varepsilon_{\text{eff}} = \frac{\varepsilon_r + 1}{2} + \frac{\varepsilon_r - 1}{2} \left( 1 + \frac{10h}{S} \right)^{-1/2}. \tag{3.19}
\]

The maximum error in \(Z_m\) and \(\varepsilon_{\text{eff}}\) relative to [15], [18] is less than 2 percent. The \(Z_c\) is given by [17], [19]

\[
Z_c = \frac{30\pi}{\sqrt{\varepsilon_{\text{eff}}}} \frac{K(k')}{K(k)}, \tag{3.20}
\]

where

\[
k = \frac{S}{S + 2W} \quad \text{and} \quad k' = \sqrt{1 - k^2},
\]

\[
\varepsilon_{\text{eff}} = \frac{\varepsilon_r + 1}{2} \left\{ \tan \left[ 0.775 \ln \left( \frac{h}{W} \right) + 1.75 \right] 
\]

\[
+ \left( \frac{kW}{h} \left[ 0.04 - 0.7k + 0.01(1 - 0.1\varepsilon_r)(0.25 + k) \right] \right) \right\}. \tag{3.21}
\]

The maximum error in \(\varepsilon_{\text{eff}}\) is 1.5 percent for \(\varepsilon_r \geq 9\), \(h/W \geq 1\), and \(0 \leq k \leq 0.7\) when compared to [20]. With the foregoing substitutions, the expression in Eq. (3.15) for \(Z_q\) is accurate to within 2.2 percent for \(0.25 \leq h/S \leq 3\), \(0.1 \leq S/(S + 2W) \leq 0.8\) and \(\varepsilon_r \leq 30\).
3.3.1 Experimental Validation

Experimental validation is carried out by measuring the time domain response (TDR) of a multisection CBCPW structure [14] shown in Figure 3.9(a). In this structure the aspect ratio of the CBCPW, namely $S/(S+2W)$, is made to vary from a low to a high value while the characteristic impedance $Z_0$ is held constant at 50 $\Omega$. Thus the structure consists of alternate low and high aspect ratio uniform CBCPW sections cascaded by tapered CBCPW section. The taper profile is normally chosen according to a graph of $(S+2W)/S$ as a function of $S/h$ for $Z_0$ equal to 50$\Omega$. The numerical analysis above is based on

![Figure 3.9](image_url)

FIGURE 3.9 Tapered CBCPW test structure on a dielectric substrate, $\varepsilon_r = 4.7$, $h = 0.125$ in.: (a) Schematic of the conductor pattern; (b) measured TDR response, horizontal scale, 200 ps. (From Reference [14]. © 1983 IEEE.)
a two-dimensional solution of Laplace’s equation, and therefore it does not
give the effect of the rate of tapering on $Z_0$. Hence in the structure above, a
simple linear taper with an angle of $20^\circ$ is chosen. The overall length of the
structure is about 5 in.

The reflection coefficient is measured by a TDR and the response is shown
in Figure 3.9(b). The pulse used in the measurement has a rise time of 25 ps.
The measured response shows 50$\Omega$ nature of the entire structure [14]. Points
A to C in Figure 3.9(b) refer to the locations on the structure. The worst-case
deviation from 50$\Omega$ occurs due to over etch where the line width is a minimum,
that is, point B. The response drops to zero beyond point C, since the structure
is terminated in a short circuit.

3.4 EFFECT OF LATERAL WALLS ON THE HIGHER-ORDER MODE
PROPAGATION ON CBCPW

3.4.1 Perfect Conductors and Lossless Dielectric

Figure 3.10 shows a CBCPW with either electric or magnetic lateral walls. This
structure is modeled as a thick capacitive iris in a parallel plate waveguide
backed by a dielectric substrate and short circuited at one end in [22]. The
thick iris is also considered as a parallel plate waveguide. This model is similar
to that initially proposed for a slot line in [23]. For the purpose of analysis,
the whole structure is divided into three regions, namely the air region, the iris
region, and the dielectric substrate region. In each region the electromagnetic
fields are expressed as a series expansion in terms of TE and TM modes (with

![FIGURE 3.10 Analytical model for CBCPW with electric or magnetic lateral walls.](image-url)
The higher-order modes in a CBCPW with lateral electric or conducting walls is first discussed. Figure 3.11(a) shows the computed normalized propagation constant $\beta_{g}/\beta_{0}$ for the dominant as well as the higher-order modes for the electric wall case. Where $\beta_{g}$ and $\beta_{0}$ are the propagation constant in the guide and free space, respectively. The figure also includes the quasi-TEM...
mode propagation constant for a conventional CPW as well as for an unbounded CBCPW. The computed results show that the dominant mode for the CBCPW with lateral electric walls is a quasi-TEM mode with zero cutoff frequency. The presence of this mode is also verified using spectral domain method independently in [24]. This mode has a propagation constant higher than that of the conventional CPW and the unbounded CBCPW. The cutoff frequency of the higher-order modes depends on the distance between the lateral electric walls. This fact is also verified independently in [24].

Figure 3.11(b) shows the computed propagation constant for the CBCPW with lateral magnetic walls. The computed results show that on this structure two quasi-TEM modes with zero cutoff frequency can propagate. These modes correspond to the two electrostatic fields that are obtained by putting at equal or different potentials the center strip conductor and the top ground planes. These two modes are designated as $M_1$ and $M_2$ in Figure 3.11(b). It could be easily visualized that mode $M_1$ with higher propagation constant and consequently higher $\varepsilon_{\text{eff}}$ has a field distribution the same as a parallel plate waveguide perturbed by two slots on the top wall. The $\varepsilon_{\text{eff}}$ is equal to $\varepsilon_r$ at all frequencies. The mode designated $M_2$ and the higher-order modes are almost identical to those in Figure 3.11(a). Finally, the computations show that if the substrate thickness is increased from 150 to 500 μm with all other parameters remaining constant, the quasi-TEM mode propagation constant of the conventional CPW and the unbounded CBCPW approach each other but the cutoff frequencies of the higher-order modes are unaffected.

### 3.4.2 Conductors with Finite Thickness, Finite Conductivity, and Lossless or Lossy Dielectric

A CBCPW with top strip conductor and top ground planes with finite thickness and finite conductivity is analyzed using two different methods in [25] to [27]. The two methods are the mode-matching method [25] and the method of lines [26], [27], respectively. In the mode-matching methods, in order to realistically model a practical structure, the lateral walls and the bottom ground plane are assumed to have finite conductivity and perfect conductivity, respectively. Further in [25] a metal cover with perfect conductivity is placed above the structure. Since the guided energy is confined to the slots, it is assumed that the top metal cover, which is at a sufficiently large distance, will not perturb significantly the guiding characteristics of the structure. In the method of lines, the lateral walls and the bottom ground plane are assumed to have perfect conductivity and finite conductivity, respectively. Figure 3.12(a) and (b) shows the cross-sectional geometry of the CBCPW considered in the analysis above.

Consider the CBCPW shown in Figure 3.12(a). The computed normalized guide wavelength ratio $\lambda_g/\lambda_0$ and normalized leakage constant $z/k_0$, where $k_0 = 2\pi/\lambda_0$, for the dominant and the first higher-order mode using the mode-matching method for two different lateral wall separation are shown in
FIGURE 3.12 Cross-sectional geometry of CBCPW considered in the (a) mode-matching method and (b) method of lines.
Figure 3.13. The two lateral wall separations correspond to $g = 0.5$ mm and $g = 1.0$ mm, respectively. In the region in which the higher-order mode propagates with $\lambda_0/\lambda_g$ and leaky constant $\alpha/k_0$ both less than unity, an appreciable leakage effect is observed. The leaky mode radiates power into space at an angle to the transmission line. The leaky higher-order mode is cutoff when its normalized leaky attenuation constant is greater than unity. Below the appreciable leakage region, discontinuities in a CBCPW circuit cannot convert the CPW mode to the leaky higher-order mode and thus no power leakage occurs. Above this region, the higher-order mode becomes bounded and mode conversion will take place. In Figure 3.13, the single-mode frequency range is 17 and 26 GHz for the two lateral wall separations, respectively. The corresponding appreciable leakage regions are 17 to 19 and 26 to 30.5 GHz, respectively. Likewise consider the CBCPW shown in Figure 3.12(b). The parameters for this structure are $\varepsilon_r = 9.6$, $h = 0.254$ mm, $W = 0.15$ mm, $S = 0.3$ mm, $g = 1.0$ mm, $t = 3 \mu$m, and $t_s$ is equal to one skin depth $\delta$. The method of lines [26] predicts the cutoff frequencies for the first two higher-order modes to lie
between 23 and 25 GHz. In the next section experimental validation is provided for the computed results.

3.4.3 Experimental Validation

To experimentally validate the numerical results of the mode matching method [25], a 50 Ohm CBCPW through line is characterized by measuring the scattering parameters. The through line geometry and parameters are presented in Figures 3.12(a) and 3.13, respectively. The lateral wall separation for the experiment is such that $g = 1.0$ mm. The transmission coefficient $S_{21}$ is measured over the frequency range of dc to 26.5 GHz. The measurement shows that the through line is resonance free up to 17 GHz [25]. This is in agreement with the numerical results discussed in the previous section. Beyond 17 up to 26.5 GHz, the measured $S_{21}$ indicate the presence of several resonances. The first two resonances occur at about 17.7 and 18.4 GHz [25]. These resonances occur in the frequency range pertaining to appreciable leakage in accordance with the analysis. Further, these resonances are attributed to the first higher-order mode.

To experimentally validate the numerical results of the method of lines [26], a CBCPW through line is characterized by measuring the reflection coefficient $S_{11}$ over the frequency range of dc to 40.0 GHz. The CBCPW geometry is presented in Figure 3.12(b), and the parameters are indicated in the previous section. The measured $S_{11}$ is below $-10.0$ dB up to about 24 GHz indicating good impedance match and single-mode propagation. The $S_{11}$ increases beyond this frequency, and has a peak at about 25 GHz. This is possible if the power normally carried by the fundamental mode is now converted into a higher-order mode, which causes a high reflection or return loss [26]. This observation is in agreement with the numerical result discussed in the previous section.

3.5 CHANNELIZED COPLANAR WAVEGUIDE

This section presents a new variant of the CBCPW. The new structure has low height side conducting walls, which together with the conductor backing constitute a metal channel and hence is appropriately termed as channelized coplanar waveguide (CCPW) [9], [10]. The structure is shown in Figure 3.14.

The channel width $2B$ is chosen such that the dielectric filled rectangular waveguide mode is cutoff. As a consequence the ground planes are of finite extent with width $g$ typically less than 1.5S. Further, since the ground planes are electrically connected by the side walls to the conductor backing, the excitation of spurious parallel plate modes are eliminated. Figure 3.15 shows the measured and computed $\varepsilon_{\text{eff}}$ for a CCPW. The computed $\varepsilon_{\text{eff}}$ is based on the model reported in [21]. The agreement between the measured and modeled $\varepsilon_{\text{eff}}$ for a CCPW on a Duroid substrate ($\varepsilon_{r} = 2.2$) is excellent.
In [30] the computed $\lambda_o/\lambda_0$ and $Z_0$ for two variants of the structure above, namely the suspended CPW and inverted CPW, respectively, are represented. In these structures a very small air gap is introduced between the substrate and the lower ground plane. In [31] the characteristics of a suspended CCPW is described.

### 3.6 REALIZATION OF LATERAL WALLS IN PRACTICAL CIRCUITS

The previous sections showed that if closely spaced conducting lateral walls are introduced, the cutoff frequency of the higher-order modes can be raised. Thereby increasing the useful bandwidth of the circuit. However, introducing
these walls is not a trivial task because of small feature size of the circuits. A practical solution to this problem is to tie the top ground plane to the bottom conductor by metal-filled via holes [8], [28], [29]. To demonstrate the efficacy of this solution, a CBCPW on a 0.01 in. thick alumina substrate (\(\varepsilon_r = 9.6\)), with \(S = 0.2\) mm and \(W = 0.15\) mm, is fabricated. The spacing between the via holes in this circuit is 0.7 mm and the via hole row is at a distance of 0.2 mm from the edge of the slot [28]. This configuration of the CBCPW is interpreted as a rectangular waveguide with side walls 0.9 mm apart, which allows a fundamental waveguide mode to start propagating at about 55 GHz. Broadband measurements made on this through line using a coaxial test fixture and a calibrated network analyzer shows that the scattering parameters (\(S_{11}, S_{21}\)) deteriorates at approximately this frequency [28].

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REFERENCES


CHAPTER 4

Coplanar Waveguide with Finite-Width Ground Planes

4.1 INTRODUCTION

In this chapter the characteristics of a conventional coplanar waveguide (CPW) and a conductor-backed coplanar waveguide (CBCPW) with finite-width top ground planes are presented. The reason for making the top ground planes of finite extent is because this more closely models a practical CPW circuit. In addition, by taking a substrate with conductor backing, a CPW circuit mounted either on a metal base as in a package or in a test fixture for performance characterization is accurately modeled.

Section 4.2 commences with analytical expressions to determine the effective dielectric constant \( \varepsilon_{\text{eff}} \) and characteristic impedance \( Z_0 \) of a CPW with finite-width ground planes (FW-CPW) supported on a multilayer dielectric substrate. There expressions are derived using quasi-static TEM conformal mapping techniques. It is also shown that these expressions simplify when only one or two dielectric substrates are present as in the case of a conventional CPW or a sandwiched CPW. Computed \( \varepsilon_{\text{eff}} \) and \( Z_0 \) for the simplified structure are presented. The section concludes with a quantitative discussion on the dispersion and \( Z_0 \) obtained using full-wave analysis.

Section 4.3 commences with a qualitative discussion on the modes that are supported by a conductor-backed CPW with top ground planes of finite width (FW-CBCPW). However, in this chapter the discussion is limited to the dominant CPW mode and the microstrip-like mode (MSL). In addition the lower ground plane is considered either to be finite or infinite in extent. The section concludes with a quantitative discussion on the dispersion characteristics of the above two modes obtained using full-wave analysis.

Section 4.4 presents three models to predict the resonance observed in the characteristics of FW-CBCPW 50\( \Omega \) through lines. The accuracy of the predicted values are demonstrated by comparing with experimentally measured values.
4.2 CONVENTIONAL COPLANAR WAVEGUIDE WITH FINITE-WIDTH GROUND PLANES ON A DIELECTRIC SUBSTRATE OF FINITE THICKNESS

4.2.1 Analytical Expressions Based on Quasi-static TEM Conformal Mapping Techniques to Determine Effective Dielectric Constant and Characteristic Impedance

Initial studies on coplanar waveguide (CPW) with finite-width ground planes were limited to dielectric substrates of infinite thickness [1]. In [1] simple expression to calculate the normalized phase velocity ratio \( \frac{v_{ph}}{c} \), where \( c \) is the velocity of light in free space, and characteristic impedance \( Z_0 \) are presented. However, in a practical circuit, the thickness of the substrate is always finite. Hence subsequent studies considered a coplanar waveguide with finite width ground planes on (a) a dielectric substrate of finite thickness [2] to [4], (b) sandwiched between two dielectric substrates [5] and (c) sandwiched between multiple dielectric substrates [6].

A FW-CPW sandwiched between multiple dielectric substrates is shown in Figure 4.1. On this structure a quasi-static TEM mode is assumed to propagate. Using this approximation, the \( \varepsilon_{eff} \), phase velocity \( v_{ph} \), and \( Z_0 \) are given by [3]

\[
\varepsilon_{eff} = \frac{C}{C_0}, \quad (4.1)
\]
\[
v_{ph} = \frac{c'}{\sqrt{\varepsilon_{eff}}}, \quad (4.2)
\]
\[
Z_0 = \frac{1}{Cv_{ph}}, \quad (4.3)
\]

where \( c' \) is the speed of light in free space, \( C \) is the capacitance per unit length of the line, and \( C_0 \) is the capacitance per unit length of the line in the absence of dielectric substrates. Thus, to determine \( \varepsilon_{eff} \) and \( Z_0 \), one needs only to find the capacitance \( C \) and \( C_0 \). To find these capacitances, we assume that the boundaries of the dielectric layers are along the electric-field lines. In which case magnetic walls can be placed along the dielectric boundaries without disturbing the fields and the capacitance of the line can be divided into partial capacitances [3] and [6]. By this assumption the capacitance of the line shown in Figure 4.1 can be written as the superposition of six partial capacitances as follows [6]:

\[
C = C_0 + C_1 + C_2 + C_3 + C_4 + C_5. \quad (4.4)
\]

The configurations of these capacitances are shown in Figure 4.2(a) to (f).
FIGURE 4.1 Schematic of a FW-CPW on a multilayer dielectric substrate.

**Calculation of \( C_0 \)** As seen from Figure 4.2(a), \( C_0 \) is the capacitance of the line in the absence of all dielectrics. This capacitance is given by [3]

\[
C_0 = 4\varepsilon_0 \frac{K(k')}{K(k)}, \tag{4.5}
\]

where \( K \) is the complete elliptical integral of the first kind. The arguments \( k \) and \( k' \) are dependent on the geometry of the line and are given by

\[
k = \frac{c}{b} \sqrt{\frac{b^2 - a^2}{c^2 - a^2}}, \tag{4.6}
\]

\[
k' = \sqrt{1 - k^2} = \frac{a}{b} \sqrt{\frac{c^2 - b^2}{c^2 - a^2}}. \tag{4.7}
\]
FIGURE 4.2 Configurations for finding the capacitances: (a) $C_5$; (b) $C_1$; (c) $C_2$; (d) $C_3$, (e) $C_4$; (f) $C_5$.

**Calculation of $C_1$** The configuration of $C_1$ is shown in Figure 4.2(b). The assumption here is that the electric field exists only in the dielectric layer of thickness $h_1$ and relative dielectric constant $\varepsilon_r - 1$. The capacitance $C_1$ is given by [3]

$$C_1 = 2\varepsilon_0(\varepsilon_r - 1) \frac{k(k'_1)}{K(k'_1)}, \quad (4.8)$$

where

$$k_1 = \frac{\sinh(\Pi c/2h_1)}{\sinh(\Pi b/2h_1)} \sqrt{\frac{\sinh^2(\Pi b/2h_1) - \sinh^2(\Pi a/2h_1)}{\sinh^2(\Pi c/2h_1) - \sinh^2(\Pi a/2h_1)}}, \quad (4.9)$$

$$k'_1 = \sqrt{1 - k_1^2} = \frac{\sinh(\Pi a/2h_1)}{\sinh(\Pi b/2h_1)} \sqrt{\frac{\sinh^2(\Pi c/2h_1) - \sinh^2(\Pi b/2h_1)}{\sinh^2(\Pi c/2h_1) - \sinh^2(\Pi a/2h_1)}}. \quad (4.10)$$
**Calculation of \( C_2, C_3, C_4, \) and \( C_5 \)** The configurations of \( C_2, C_3, C_4, \) and \( C_5 \) are shown in Figure 4.2(c) to (f). The assumption here is that the electric field exists only in the dielectric layers of thickness \( h_2, h_3, h_4, \) and \( h_5 \) with relative dielectric constants of \( \varepsilon_{r2} - \varepsilon_{r1}, \varepsilon_{r3} - 1, \varepsilon_{r4} - \varepsilon_{r3}, \) and \( \varepsilon_{r5} - \varepsilon_{r4}, \) respectively. The capacitances are given by [3]

\[
C_2 = 2\varepsilon_0(\varepsilon_{r2} - \varepsilon_{r1}) \frac{K(k'_2)}{K(k_2)},
\]

\[
C_3 = 2\varepsilon_0(\varepsilon_{r3} - 1) \frac{K(k'_3)}{K(k_3)},
\]

\[
C_4 = 2\varepsilon_0(\varepsilon_{r4} - \varepsilon_{r3}) \frac{K(k'_4)}{K(k_4)},
\]

\[
C_5 = 2\varepsilon_0(\varepsilon_{r5} - \varepsilon_{r4}) \frac{K(k'_5)}{K(k_5)},
\]

where

\[
k_i = \frac{\sinh(\pi c/2h_i)}{\sinh(\pi b/2h_i)} \sqrt{\frac{\sinh^2(\pi b/2h_i) - \sinh^2(\pi a/2h_i)}{\sinh^2(\pi c/2h_i) - \sinh^2(\pi a/2h_i)}},
\]

\[
k'_i = \sqrt{1 - k_i^2} = \frac{\sinh(\pi a/2h_i)}{\sinh(\pi b/2h_i)} \sqrt{\frac{\sinh^2(\pi a/2h_i) - \sinh^2(\pi b/2h_i)}{\sinh^2(\pi c/2h_i) - \sinh^2(\pi a/2h_i)}},
\]

\[
i = 2, 3, 4, \) and \( 5.
\]

Substituting Eqs. (4.4), (4.5), (4.8), and (4.11) to (4.14) into Eq. (4.1) results in

\[
\varepsilon_{\text{eff}}^{\text{CPW}} = \frac{C}{C_0}
\]

\[
= 1 + \frac{1}{2} (\varepsilon_{r1} - 1) \frac{K(k) \ K(k'_1)}{K(k') \ K(k_1)}
\]

\[
+ \frac{1}{2} (\varepsilon_{r2} - \varepsilon_{r1}) \frac{K(k) \ K(k'_2)}{K(k') \ K(k_2)}
\]

\[
+ \frac{1}{2} (\varepsilon_{r3} - 1) \frac{K(k) \ K(k'_3)}{K(k') \ K(k_3)}
\]

\[
+ \frac{1}{2} (\varepsilon_{r4} - \varepsilon_{r3}) \frac{K(k) \ K(k'_4)}{K(k') \ K(k_4)}
\]

\[
+ \frac{1}{2} (\varepsilon_{r5} - \varepsilon_{r4}) \frac{K(k) \ K(k'_5)}{K(k') \ K(k_5)}
\]
From Eqs. (4.2) and (4.3) we obtain

\[ \\epsilon_{\text{CPW}}^{\text{CPW}} = \frac{c'}{\sqrt{\epsilon_{\text{eff}}^{\text{CPW}}}}, \]  

(4.18)

\[ Z_0^{\text{CPW}} = \frac{30\pi}{\sqrt{\epsilon_{\text{eff}}^{\text{CPW}}}} \frac{K(k)}{K(k')}, \]  

(4.19)

where \( k \) and \( k' \) are given by Eqs. (4.6) and (4.7).

For a FW-CPW on a substrate with a single dielectric layer as shown in Figure 4.3(a), \( \epsilon_{r1} = \epsilon_{r2} = \epsilon_{r3} = \epsilon_{r4} = 1 \) and Eq. (4.17) reduces to

\[ \epsilon_{\text{eff}}^{\text{CPW}} = 1 + \frac{1}{2} (\epsilon_{r5} - 1) \frac{K(k)}{K(k')} \frac{K(k')}{K(k')}, \]  

(4.20)

which is identical to the equation given in [3] and [4]. Figure 4.4(a) and (b) presents the computed \( \epsilon_{\text{eff}} \) and \( Z_0 \), respectively.

For a FW-CPW sandwiched between two dielectric layers as shown in Figure 4.3(b), \( \epsilon_{r1} = \epsilon_{r3} = \epsilon_{r4} = 1 \), and Eq. (4.17) reduces to

\[ \epsilon_{\text{eff}}^{\text{CPW}} = 1 + \frac{1}{2} (\epsilon_{r2} - 1) \frac{K(k)}{K(k')} \frac{K(k')}{K(k')}, \]  

(4.21)

Further, if the two dielectric layers have identical relative permittivity and thickness, then \( \epsilon_{r2} = \epsilon_{r5} = \epsilon_r \) and \( h_2 = h_5 = h \). In that case Eq. (4.21) further simplifies to

\[ \epsilon_{\text{eff}}^{\text{CPW}} = 1 + (\epsilon_r - 1) \frac{K(k)}{K(k')} \frac{K(k')}{K(k')}, \]  

(4.22)

where \( k \) and \( k' \) are given by Eqs. (4.6) and (4.7), respectively. The arguments \( k_s \) and \( k'_s \) are given by Eqs. (4.9) and (4.10), respectively, with \( h_1 \) replaced by \( h \). Equation (4.22) is identical to that given in [5].

Finally, for a FW-CPW on an infinitely thick dielectric substrate, \( h_5 \to \infty \) and \( k_s = k \). The effective dielectric constant from Eq. (4.20) is given by

\[ \epsilon_{\text{eff}}^{\text{CPW}} = \frac{1}{2}(\epsilon_r + 1), \]

where \( \epsilon_r \) is the relative permittivity of the substrate.

### 4.2.2 Dispersion and Characteristic Impedance from Full-Wave Analysis

The FW-CPW shown in Figure 4.3(a) has been analyzed using the spectral domain technique in [7]. The computed guide wavelength ratio, \( \lambda_0/\lambda_g \), where
\( \lambda_g \) and \( \lambda_0 \) are the guide wavelength and free space wavelength, respectively, is shown in Figure 4.5(a). For small ground plane width, the energy is more closely bounded within the region of the substrate and consequently \( \lambda_0/\lambda_g \) is higher than the conventional CPW. As the ground plane width increases, the \( \lambda_0/\lambda_g \) converges to that of the conventional CPW. The characteristic impedance \( Z_0 \) defined as \( Z_0 = Z_{0\text{air}}/\sqrt{\varepsilon_{\text{eff}}}, \) where \( Z_{0\text{air}} \) is the characteristic impedance of the air filled structure, is shown in Figure 4.5(b). Since the FW-CPW has a higher \( \varepsilon_{\text{eff}} \), the \( Z_0 \) is lower than the conventional CPW. As the ground plane width increases, the \( Z_0 \) converges to that of the conventional CPW. The relative change in both \( \lambda_0/\lambda_g \) and \( Z_0 \) between extremes does not exceed a few percent.
FIGURE 4.4 Contour of constant propagation parameters for FW-CPW, $\varepsilon_r = 13$, $h/b = 1$: (a) Effective dielectric constant, $\varepsilon_{\text{eff}}$; (b) characteristic impedance, $Z_0$. (From Reference [4], © 1987 IEEE.)

4.3 CONDUCTOR-BACKED COPLANAR WAVEGUIDE WITH FINITE-WIDTH GROUND PLANES ON A DIELECTRIC SUBSTRATE OF FINITE THICKNESS AND FINITE WIDTH

A conductor-backed coplanar waveguide with finite-width ground planes on a dielectric substrate of finite thickness and finite width (FW-CBCPW) is shown in Figure 4.6 [8]. The dominant CPW mode has its electric field components on this structure as sketched in Figure 4.6(a). In addition this structure can support a microstrip-like (MSL) propagating mode. This mode resembles a
FIGURE 4.5 Computed characteristics of FWCPW with normalized ground plane width as parameter, $e_r = 9.6$, $h = 0.07$ cm, $S = 0.05$ cm, $W = 0.1$ cm: (a) Guide wavelength ratio, $\lambda_0/\lambda_s$; (b) characteristic impedance, $Z_0$. (From Reference [7], with permission from AEÜ.)
parallel-plate transmission line mode and is shown in Figure 4.6(b). If the top ground planes are wide, then the next higher-order microstrip-like mode may exist as shown in Figure 4.6(c). If the dielectric substrate is even wider then the structure can support an image-guide-like propagating mode. However, for the initial study the structural parameters and the material constants are so chosen that the structure supports only the CPW mode and the MSL mode below 26.5 GHz [8].

For the purpose of analysis, modeling and computer simulation an equivalent CPW structure shown in Figure 4.7 is considered. The two perfect electric conductors (PEC) are located sufficiently far away from the guiding structure so as not to perturb the field distributions. This model is capable of providing the dispersion characteristics for a coplanar waveguide having top and bottom ground planes of finite width. Furthermore in this model, by setting both $t_2$ and $h_2$ equal to zero, the dispersion characteristics can be obtained for a coplanar waveguide with finite-width top ground planes and an infinitely wide lower ground plane.
The structure in Figure 4.7 is analyzed using the full-wave mode-matching technique [8] and [9]. The computed normalized propagation constant $\beta_g/\beta_0$, where $\beta_g$ and $\beta_0$ are the propagation constant in the guide and free space, respectively, for the FW-CPW with finite and infinitely wide lower ground plane [9] is presented in Figure 4.8. In the same figure the computed dispersion characteristics for the microstrip-like mode for the two cases of finite and infinitely wide lower ground plane, respectively, are also presented. The two sets of characteristics are computed over a very wide frequency range extending from about 1 GHz up to about 26 GHz. It is observed that at low frequencies, typically below 10 GHz, the phase constant of the MSL mode on a line with finite lower ground plane is significantly higher than with infinite lower ground plane. A possible reason for this to happen is the slower phase velocity on a line with finite lower ground plane because of smaller amount of fringing fields. On the other hand, the CPW mode has most of the energy concentrated around the slot regions. Hence the phase constants with finite and with infinite lower ground plane, respectively, differ by a constant amount over the above frequency range.
FIGURE 4.8 Computed normalized propagation constant $\beta_g/\beta_0$ as a function of frequency for MSL and CPW modes on FW-CBCPW with finite and infinite lower ground planes: $S = W = 0.508 \text{ mm}, g = 1.0 \text{ mm}, W_d = 0.0 \text{ mm}, h = 0.2 h_1 = 0.635 \text{ mm}, t_1 = 20 \mu\text{m}, \sigma = 5.8 \times 10^7 \text{ S/m (copper)},$ and $\varepsilon_0 = 10.2$. For infinite lower ground plane $h_2 = 0, t_2 = 0$, and for finite lower ground $h_2 = h_1, t_2 = t_1$. (From Reference [9], © 1993 IEEE.)

4.4 SIMPLE MODELS TO ESTIMATE FINITE GROUND PLANE RESONANCE IN CONDUCTOR-BACKED COPLANAR WAVEGUIDE

Consider the FW-CBCPW shown in Figure 4.9 and for the moment ignore the two notches cut in the top ground planes. The top ground planes are then viewed as two-dimensional resonators [10] and modeled as follows: first, as a patch antenna, second as an overmoded microstrip-like (MSL) transmission line, and finally using three-dimensional full-wave space domain integral equation (SDIE) technique.

When considering the ground planes as patch antennas, the effect of fringing fields are neglected and the resonant frequencies are computed as explained in [11] and [12]. When considering the ground planes as overmoded MSL, the dominant as well as the first higher-order modes are taken into consideration. Resonance occurs when the following condition is satisfied:

$$\beta_{\text{MSL}} l = n\pi,$$  \hspace{1cm} (4.23)

where $\beta_{\text{MSL}}$ is the propagation constant of the dominant or higher-order MSL mode and $l$ is the length of the line. In the case of SDIE techniques, the two-dimensional current distributions on the center strip conductor as well as the side planes are obtained. Knowing the current distributions, the resonance frequencies are determined.
FIGURE 4.9  Schematic of the 50Ω FW-CBCPW through line with two notches cut in the top ground plane: $S = W = 0.508$ mm, $g = 6.0$ mm, $l = 18.0$ mm, $W_p = 1.0$ mm, $W_c = 1.016$ mm, $h = 0.635$ mm, $\varepsilon_r = 10.2$

4.4.1 Experimental Validation

To validate the computed resonant frequencies, the top ground planes of the 50Ω FW-CBCPW through line without notches are grounded by wrapping copper foils as shown in Figure 4.9. The FW-CBCPW is excited through a small opening between the foils by two Cascade MTF-26 coaxial test fixtures. The dimensions of the through line are presented in Figure 4.9. The reflection coefficient $S_{11}$ and the transmission coefficient $S_{21}$ are measured [10] on a calibrated network analyzer and the resonant frequencies are noted. Table 4.1 presents the measured as well as the computed resonant frequencies using three different models. The indexes $m_y$ and $n_z$ appearing in the first column of the table are the order of resonance. When $m_y = 0$ and $n_z = 1, 2, \ldots$, the resonance appears in the longitudinal $z$-direction with negligible field variation in the transverse $y$-direction. When $m_y = 1$ and $n_z = 1$, the resonance has one half-wave variation in both $y$- and $z$-directions. In comparing the resonant frequencies predicted by the patch antenna model and the MSL model with the measured resonant frequencies, the MSL model is observed to have much better agreement.

In a second experiment, the resonant frequencies are measured [10] for a FW-CBCPW having notches cut in the ground plane as shown in Figure 4.9. The dimensions $W_p$ and $W_c$ are also given in Figure 4.9. The measurements show that the slit causes a shift in the resonant frequencies. This experiment also proves that by providing notches in the ground plane, the MSL modes cannot be suppressed or eliminated.
TABLE 4.1 Measured and Modeled Resonant Frequencies for the FW-CBCPW Shown in Figure 4.9

<table>
<thead>
<tr>
<th>Resonance Number and Indexes, ( m_p n_z )</th>
<th>Measurement, GHz</th>
<th>Patch Antenna Model, GHz</th>
<th>Microstrip-like Model, ( m_p=0, 1 ) ( \beta_{MSL} l=n_z \pi, \frac{GHz}{GHz} )</th>
<th>Three-Dimensional Space Domain Integral Equation Model, GHz</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 (0.1)</td>
<td>2.71</td>
<td>2.61</td>
<td>2.74</td>
<td>2.76</td>
</tr>
<tr>
<td>2 (0.2)</td>
<td>5.38</td>
<td>5.22</td>
<td>5.40</td>
<td>5.44</td>
</tr>
<tr>
<td>3 (1.1)</td>
<td>7.65</td>
<td>8.23</td>
<td>7.71</td>
<td>7.75</td>
</tr>
<tr>
<td>4 (0.3)</td>
<td>8.01</td>
<td>7.83</td>
<td>8.04</td>
<td>8.08</td>
</tr>
<tr>
<td>5 (1.2)</td>
<td>9.07</td>
<td>9.39</td>
<td>9.21</td>
<td>9.22</td>
</tr>
<tr>
<td>6 (0.4)</td>
<td>10.61</td>
<td>10.44</td>
<td>10.67</td>
<td>10.71</td>
</tr>
<tr>
<td>7 (1.3)</td>
<td>10.94</td>
<td>11.06</td>
<td>11.27</td>
<td>11.08</td>
</tr>
</tbody>
</table>

Source: From Reference [10], © IEEE.

REFERENCES


CHAPTER 5

Coplanar Waveguide Suspended inside a Conducting Enclosure

5.1 INTRODUCTION

In this chapter the characteristics of a coplanar waveguide (CPW) suspended inside a conducting metal enclosure are presented. By taking the enclosure into consideration, the inevitable package that is present in practice and its influence is studied and modeled.

Section 5.2 commences with a discussion on quasi-static TEM iterative techniques to analyze suspended CPW and presents computed as well as experimental results on effective dielectric constant $\varepsilon_{\text{eff}}$ and characteristic impedance $Z_0$. These characteristics are compared with those obtained by full-wave analysis in Section 5.3. In addition to these the effects are presented of shielding and conductor thickness on the guide wavelength ratio $\lambda_g/\lambda_0$, where $\lambda_g$ and $\lambda_0$ are the guide wavelength and the free space wavelength, respectively, and on $Z_0$. The section concludes with an estimate for the dispersion free bandwidth and the minimum width of a picosecond pulse that can propagate on the line without distortion. Experimental results are also presented to validate the analysis.

Section 5.4 considers a CPW suspended inside a nonsymmetrical split block type of housing. This type of construction has the advantage of simplifying assembly by soldering or epoxying the circuit to one-half of the housing. Critical mechanical tolerances and contacts at mounting grooves can be avoided by this method of assembly. The influences of a nonsymmetrical shielding enclosure on the dominant and higher-order modes, on the cutoff frequency of the first higher-order mode, and on $Z_0$ are presented. The substrate mounting recess dimensions are very critical at higher millimeter
wave frequencies. Hence the impact of the groove dimensions on the cutoff frequency of the first higher order mode is presented.

Last, in Section 5.5, the $\lambda_0/\lambda_0$ and $Z_0$ of a CPW on a double-layer substrate and also of a CPW sandwiched between two dielectric substrates are presented. These additional layers are necessary for providing protection from mechanical or chemical damage to circuits exposed to the environment and also as an additional means to adjust the propagation characteristics.

The CPW in this chapter is assumed to be symmetric and on an isotropic homogeneous dielectric substrate of arbitrary thickness and relative permittivity. Further the substrate metalization and the metal enclosure are assumed to have perfect conductivity.

5.2 QUASI-STATIC TEM ITERATIVE TECHNIQUE TO DETERMINE $\varepsilon_{\text{eff}}$ AND $Z_0$ OF SUSPENDED CPW

A CPW suspended inside a conducting enclosure is shown in Figure 5.1(a). This structure has been analyzed by the use of relaxation method in [1] to [3]. In the relaxation method, the characteristics of the structure is determined by numerically solving the two-dimensional Laplace equation. In [1] and [2], the cross section of the structure is assumed to be symmetric about the $y$-axis. This simplifies the computational task, since it is sufficient to solve either the left half or the right half of the structure. Further, simplification is possible if the thickness $t$ of the substrate metallization is assumed to be far less than the substrate thickness $h$, in which case it is set equal to zero.

5.2.1 Computed Quasi-static Characteristics and Experimental Validation

The effect of the metal side walls and the top and bottom metal covers on the propagation characteristics is first considered. Figure 5.2 shows the variation of the computed reciprocal of the effective dielectric constant $\varepsilon_{\text{eff}}$ and the characteristic impedance $Z_0$ as a function of the normalized side wall separation [2]. While carrying out these computations, the heights of the metal top and bottom covers, the substrate thickness and dielectric constant, the strip width and the slot width, are all held fixed. As seen from this figure the characteristics saturates when the ratio $g/(W + S/2)$ is greater than 1.0.

Figure 5.3 shows the variation of the computed reciprocal of the $\varepsilon_{\text{eff}}$ and $Z_0$ as a function of the normalized height of the top and bottom metal covers [2]. While carrying out these computations, the side wall separation, the substrate thickness and dielectric constant, the strip width, and the slot width, are all held fixed. As seen from this figure the effect of $H$ is small on the characteristics for $H/H$ less than 0.142.

In Figure 5.4 the computed reciprocal $\varepsilon_{\text{eff}}$ and the $Z_0$ are presented as function of the normalized slot width with the normalized center conductor strip width as a parameter [2]. The dimensions of the shielding enclosure, the
FIGURE 5.1  Shielded coplanar waveguide configurations: (a) Suspended; (b) covered; (c) grounded; (d) multilayer.
FIGURE 5.1 Shielded coplanar waveguide configurations: (a) Suspended; (b) covered; (c) grounded; (d) multilayer.
FIGURE 5.2  Computed reciprocal of the effective dielectric constant and characteristic impedance as a function of the side wall separation with the normalized slot width as a parameter: \( H = 4.3 \) mm, \( h = 0.61 \) mm, \( \varepsilon_r = 9.4 \), \( h_1 = h_2 \), \( t = 0 \), \( S/H = 0.43 \). (From Reference [2], © 1975 IEEE.)

FIGURE 5.3  Computed reciprocal of the effective dielectric constant and characteristic impedance as a function of the top and bottom metal cover separation: \( 2B = 10.7 \) mm, \( h = 0.61 \) mm, \( \varepsilon_r = 9.4 \), \( h_1 = h_2 \), \( t = 0 \), \( S/2B = 0.18 \), \( W/2B = 0.06 \). (From Reference [2], © 1975 IEEE.)
substrate thickness and dielectric constant are all held fixed while carrying out the computations. In Figure 5.5 the computed reciprocal $\varepsilon_{\text{eff}}$ and $Z_0$ are presented as a function of the normalized center conductor strip width with the normalized slot width as a parameter [2].

To experimentally validate the computed results, a CPW is fabricated on an alumina substrate ($\varepsilon_r = 9.4$) with gold-plated Cr-Au thin film. The characteristic impedance of the line is measured by a time domain reflectometer (TDR). The measured data are indicated by circular dots in Figures 5.4 and 5.5. The maximum difference between the measured and the calculated values is about 3 percent [2]. This is due to the uncertainty in the value of the substrate relative dielectric constant and also to experimental and measurement errors.

5.3 FREQUENCY-DEPENDENT NUMERICAL TECHNIQUES FOR DISPERSION AND CHARACTERISTIC IMPEDANCE OF SUSPENDED CPW

At frequencies below about 3 GHz, the quasi-static analysis provides sufficiently accurate results, however, as the frequency increases the deviation from quasi-static behavior is significant. Hence in this section the frequency
dependent characteristics will be discussed. The frequency dependent analysis of the structure shown in Figure 5.1(a) can be simplified by considering the even mode and the odd mode of propagation as explained in Chapter 2, Section 2.4.

In the literature several researchers have analyzed this structure using the hybrid-mode analysis [4], [5], the method of lines [6] to [8], integral equation technique [9], [10], transverse resonance method [11], [12], spectral domain method [13] to [18], modal analysis [19], and finite difference time domain method [20]. As an example, Figure 5.6 compares, the frequency dependent $Z_0$ defined as

$$Z_0 = \frac{W/H}{\sqrt{\varepsilon_{eff}}}$$

and $Z_0$ [4]. The deviation from quasi-static behavior is significant and clearly noticeable. The computations were carried out using the hybrid-mode technique.

5.3.1 Effect of Shielding on the Dispersion and Characteristic Impedance

Figure 5.7 shows the computed guide wavelength ratio $\lambda_g / \lambda_0$ as a function of the reciprocal of the free space wavelength, with the height of the shield as a parameter [13]. The computations were carried out using the spectral domain technique. It is observed that as the height of the enclosure increase, the dispersion characteristics approach that of an unshielded CPW [21]. Further, as the frequency increases, the dispersion curves converge upon each other, which is consistent with the decreasing effect of the shielding enclosure.

An useful variant of the above structure is the covered CPW. The covered CPW has the lateral wall separation $2B$ far greater than the height $H$ of the
FIGURE 5.6 Comparison between the computed frequency dependent $\varepsilon_{\text{eff}}$ and $Z_0$ with the quasi-static $\varepsilon_{\text{eff}}$ and $Z_0$: $S/h = 0.4$, $(S + 2W)/h = 2.4$, $(S + 2W + 2g)/h = 15$, $(h_1 + t)/h = 14.5$, $h_2/h = 14.5$, $t = 0$, $\varepsilon_r = 9.6$. (From Reference [4], © IEE.)

FIGURE 5.7 Computed guide wavelength ratio as a function of the reciprocal of the free space wavelength with the normalized height of the shield: $2B/H = 2$, $S/h = 1$, $W/h = 0.25$, $\varepsilon_r = 11$, $h_1 = h_2$, $t = 0$. (From Reference [13], © 1977 IEEE.)
shield. The covered CPW for all practical purpose is considered as a laterally open structure and is shown in Figure 5.1(b). The computed $\lambda_g/\lambda_0$ and $Z_0$ as a function of the reciprocal of the free space wavelength with the normalized slot width as a parameter [14] are shown in Figure 5.8(a) and (b). These characteristics are computed using the spectral domain technique.

5.3.2 Experimental Validation of Dispersion

In order to validate the computed $\lambda_g/\lambda_0$ for the covered CPW, the guide wavelength is measured for a CPW fabricated [14] on a alumina substrate of thickness 0.65 mm and $\varepsilon_r$ equal to 9.7. The method relies on loosely coupled short-circuited resonating slots [14]. This method of measuring is not well suited for very narrow or very wide slots because, in the former case, the coupling probes have to be positioned extremely close to the slots, whereas in the later case the $Q$-factors of the resonances are rather low. The measured results [14] are shown by circular dots in Figure 5.8(a).

To validate the computed $\lambda_g/\lambda_0$ for the suspended CPW, the $S$-parameters are measured [7] for two shielded CPWs having identical strip and slot widths but different line lengths. The measurements are carried out by attaching two coaxial launchers with very similar characteristics to the lines and measuring the $S$-parameters on a personal computer controlled automatic network analyzer. After suitable algebraic manipulations, the $S$-parameters of the CPW with length equal to the difference between the two line lengths are obtained [24]. This procedure is conveniently handled by a software that resides on the personal computer. From the $S$-parameters the propagation constant $\gamma$ of the CPW line is obtained. Measurements made on two CPWs with the following parameters: $\varepsilon_r = 10$, $\tan \delta_e = 0.002$, $h = 0.635$ mm, $h_1 = h_2 = 20$ mm, $2B = 12$ mm, $W = 0.5$ mm, and $S = 2$ mm and 4 mm, over the frequency range of 1 to 15 GHz are observed to be in good agreement with the computed values [7] using the method of lines.

5.3.3 Effect of Conductor Thickness on the Dispersion and Characteristic Impedance

The computed frequency dependent $\varepsilon_{eff}$ and $Z_0$ as a function of the reciprocal of the free space wavelength with the conductor thickness as a parameter [4] for the shielded suspended CPW is shown in Figure 5.9. The computations are carried out using the hybrid-mode technique. The $Z_0$ presented here is based on the power-voltage definition. Both $\varepsilon_{eff}$ and $Z_0$ decrease as the thickness of the conductor increases. The decrease in $\varepsilon_{eff}$ is because of field lines concentrating in the air-filled slot region formed by the thick metal coating. The decrease in $Z_0$ is because of the corresponding fractional increase in the line capacitance. Also in Figure 5.9 is the quasi-static value to which the frequency dependent characteristic converges in the low-frequency limit.

The effect of the metal coating thickness on $\varepsilon_{eff}$ and $Z_0$ of a shielded suspended CPW with different substrate dielectric constant $\varepsilon_r$ [4] is shown in
5.3.4 Modal Bandwidth of a Suspended CPW

To understand modal bandwidth [16], first of all consider the shielded grounded CPW shown in Figure 5.1(c). The general behavior of the propagation constant $\beta$ with frequency along this transmission line typically shows an increasing trend as illustrated by curve $A$ in Figure 5.11 [16]. The free space propagation constant is denoted as $\beta_0$. The grounded CPW structure can also
be considered as a shielded grounded slotline with an added center strip conductor. On this slotline the propagation constant for the dominant mode increases with frequency as shown by curve B in Figure 5.11. Further this dominant mode has a cutoff frequency of $f_c$. The added center strip conductor taken together with the two side strip conductors forms a two-conductor strip transmission line, such as a grounded CPW, and gives rise to a quasi-TEM propagation mode as the dominant mode. At low frequencies when quasi-TEM approximation is assumed, the normalized propagation constant is represented by $\beta_{\text{TEM}}/\beta_0 = \sqrt{\varepsilon_{\text{eff}}}$ as shown by curve C in Figure 5.11. At extremely high frequency, the electromagnetic fields are concentrated in the dielectric substrate and the normalized propagation constant eventually converges to $\beta/\beta_0 = \sqrt{\varepsilon_{\text{r}}}$. Between the low- and high-frequency extremes, the curve A appears as an asymptote to both the curves B and C.

In Figure 5.12 curve $A_i$ is the computed normalized propagation constant of a shielded grounded CPW [16]. Curves $B_i$ and $C_i$ are the computed normalized propagation constant of the shielded grounded slotline and the quasi-TEM propagation constant of the shielded grounded CPW, respectively [16]. The dimensions of shielded grounded CPW are also presented in Figure

FIGURE 5.9 Computed $\varepsilon_{\text{eff}}$ and $Z_0$ as a function of the reciprocal of the free space wavelength with the conductor thickness as a parameter: $\varepsilon_r = 9.6$, $S/h = 0.4$, $(S + 2W)/h = 2.4$, $(S + 2W + 2q)/h = 15$, $(h_1 + t)/h = 14.5$, $h_2/h = 14.5$. (From Reference [4], copyright © IEE.)
FIGURE 5.10 Computed percentage change in $\varepsilon_{\text{eff}}$ and $Z_0$ of shielded suspended CPW as a function of the normalized conductor thickness with the substrate dielectric constant as a parameter: $S/h = 1.0$, $(S + 2W)/h = 3.0$, $(S + 2W + 2g)/h = 15.0$, $(h_1 + t)/h = 3.0$, $h_2/h = 3.0$, frequency = 0 GHz. (From Reference [4], copyright © IEE.)

FIGURE 5.11 Typical dispersion characteristics of the grounded CPW dominant mode, which is considered as a superposition of the grounded slot line mode and the quasi-TEM mode of the grounded CPW. (From Reference [16], © 1992 IEEE.)
FIGURE 5.12  Computed dispersion characteristics of a shielded grounded CPW ($A_1$) and a shielded suspended CPW ($A_2$): $S = 0.14$ mm, $2B = 2$ mm, $h = 0.2$ mm, $W = 10$ mm, $\varepsilon_r = 12.9$, $t = 0$. For shielded grounded CPW, $h_1 = 2$ mm, and for shielded suspended CPW, $h_1 = h_2 = 1$ mm. (From Reference [16], © 1992 IEEE.)

5.12. This transmission line can be used up to about 30 GHz, that is, when $\beta$ is 3 percent larger than $\beta_{TEM}$ [16].

In Figure 5.12 curves $A_2$ and $B_2$ are the computed normalized propagation constants for the shielded suspended CPW and slotline, respectively [16]. Curve $C_2$ is the computed normalized quasi-TEM propagation constant for the shielded suspended CPW [16]. The dielectric constant, the substrate thickness, the center strip conductor width, and the slot width are identical to those of the shielded grounded CPW. The only difference is the 1 mm thick air layer below the dielectric substrate. In the case of the shielded suspended CPW, the useful frequency range approaches 100 GHz which is several times greater than the range of the shielded grounded CPW [16]. Thus, by providing a very thin air layer below the substrate, the dispersion free bandwidth can be significantly enhanced.

In Chapter 2, Section 2.4, it has been pointed out that the CPW structure can support both the odd mode and the even mode of propagation. In [17] it has been shown that the cutoff frequency of the first higher-order mode, that is, the even mode, is increased by suspending the dielectric substrate inside a conducting enclosure. Thus providing a thin air layer below the substrate also improves the modal bandwidth by increasing the frequency separation between the dominant and the first higher-order mode.
5.3.5 Pulse Propagation on a Suspended CPW

Consider the following Gaussian pulse as the input signal to a CPW [16]:

\[ V(0, t) = V_0 \exp \left[ -4 \ln 2 \left( \frac{t}{\tau} \right)^2 \right], \quad (5.1) \]

where \( \tau \) represents the full width at half maximum (FWHM) of the pulse. The pulse waveform at a propagation distance \( L \) is obtained by taking the inverse Fourier transform of the product of the Fourier transform of the input signal and the propagation factor, \( \exp[-\gamma(f)L] \). Mathematically this can be expressed as [16]

\[ V(L, t) = \mathcal{F}^{-1} \{ \mathcal{F} \{ V(0, t) \} \cdot \exp[-\gamma(f)L] \}, \quad (5.2) \]

where \( \mathcal{F} \) denotes the Fourier transform and \( \gamma(f) \) is the complex frequency-dependent propagation constant whose real and imaginary parts are the attenuation constant \( \alpha(f) \) and the phase constant \( \beta(f) \), respectively. For simplicity the attenuation constant is neglected, and only the phase constant is considered here. The phase constant \( \beta(f) \) is given by the following closed form equation [16]:

\[ \frac{\beta}{\beta_0} = \frac{\sqrt{\varepsilon_r} - \beta_{TEM}/\beta_0}{1 + aF^{-b}} + \frac{\beta_{TEM}}{\beta_0}, \quad (5.3) \]

where \( F = f/f_{TE} \), \( f_{TE} = c/4h\sqrt{\varepsilon_r} - 1 \) is the cutoff frequency for the lowest order TE mode, \( c \) is the velocity of light in free space, \( \beta_{TEM} \) is the propagation constant assuming the quasi-TEM approximation, \( a \) and \( b \) are constants that depend on the type and dimensions of the transmission line. The values of \( a \) and \( b \) are obtained by curve fitting the dispersion data from numerical computations.

Figure 5.13 shows the computer simulation results of a Gaussian pulse propagation along a shielded suspended CPW [16]. The Gaussian pulse at the input has a FWHM of 20 ps with a 10 to 90 percent rise time of 15 ps. The frequency bandwidth of this pulse is approximately 40 GHz, at which point the spectral amplitude drops to 10 percent of the peak value. The shielded suspended CPW has a dispersion free bandwidth of about 100 GHz, as discussed in the previous section, and therefore the input pulse remains unaltered with the rise time still holding at 15 ps even after traveling a distance of 30 mm.

To obtain an expression for the minimum pulse width supported on such a transmission line, the Fourier transform of Eq. (5.1) is taken [16]:

\[ V(0, \omega) = \sqrt{\frac{\pi}{4 \ln 2}} \quad V_0 \tau \exp \left[ -\frac{\omega^2 \tau^2}{16 \ln 2} \right], \quad (5.4) \]
Let $f_{0.1}$ be the frequency at which the spectral amplitude is 10 percent of the peak value, then Eq. (5.4) gives [16]

$$f_{0.1} = \frac{2\sqrt{\ln 2 \cdot \ln 10}}{\pi \tau}.$$  \hspace{1cm} (5.5)

Further let $f_{\text{TEM}}$ be the frequency at which $\beta$ in Eq. (5.3) is 3 percent larger than $\beta_{\text{TEM}}$. It is given by [16]

$$f_{\text{TEM}} = \left( \frac{\sqrt{\varepsilon_r - 1.03\beta_{\text{TEM}}/\beta_0}}{0.03a\beta_{\text{TEM}}/\beta_0} \right)^{-1/b} f_{\text{TE}}.$$  \hspace{1cm} (5.6)

This frequency is considered as the upper limit of the usable frequency band. It thus defines the bandwidth of the CPW. Over this frequency range the dispersion is negligible. Since 99 percent of a pulse energy is contained in frequencies less than $f_{0.1}$, we may regard that the pulse will propagate without dispersion if $f_{0.1}$ does not exceed $f_{\text{TEM}}$. We thus obtain the minimum FWHM
of the pulse as follows [16]:

$$\tau_{\text{min}} = \frac{2\sqrt{\ln 2 \cdot \ln 10}}{\pi f_{\text{TEM}}}.$$  \hspace{1cm} (5.7)

The $f_{\text{TEM}}$ for the shielded suspended CPW of Figure 5.12 is 76.2 GHz and $\tau_{\text{min}}$ is 10.6 ps.

5.3.6 Pulse Distortion — Experimental Validation

The picosecond pulse required for this experiment is generated optoelectronically. In the experiment a picosecond laser pulse is used to excite a photoconductive switch. The filtered output waveform of the switch is a Gaussian-like pulse and is coupled to the input of the CPW. The output pulse at the end of the CPW is coupled to the sampling head of a digital oscilloscope. The time resolution of the sampling head is about 8.8 ps. The Gaussian-like input pulse in the experiment has a rise time of 58 ps and a FWHM of 52 ps [16]. The shielded suspended CPW is fabricated on a DI-CLAD 810 dielectric substrate manufactured by Arlon and is 1.27 mm thick and has a dielectric constant of 10.5. The dimensions of the CPW are $S = 1.2$ mm, $W = 0.5$ mm, $2B = 20$ mm, $h_1 = h_2 = 2.7$ mm [16]. To support the dielectric substrate, 1 mm deep grooves are milled in the inner walls of the shielding enclosure. The measured FWHM of the pulse after traveling 60 mm is 65 ps [16]. The rise time of the leading edge of the pulse changed only slightly after propagating 60 mm [16]. This experiment demonstrates that a shielded suspended CPW is able to effectively minimize pulse distortion.

5.4 DISPERSION AND HIGHER-ORDER MODES OF A SHIELDED GROUNDED CPW

A shielded grounded CPW is shown in Figure 5.1(c). In the literature this structure is analyzed using the method of lines [8], the transverse resonance method [12], and the spectral domain method [15] and [16]. In [8] the dispersion characteristics are computed for the shielded grounded coplanar structure, assuming the same dimensions as those in [16] and a magnetic wall along the plane of symmetry. Figure 5.14 shows the computed characteristics.

The propagating mode on this structure is considered as a superposition of a TEM mode and slotline mode similar to a suspended CPW discussed earlier in Section 5.3.4. In Figure 5.14, the quasi-TEM dominant mode and the first higher-order mode are designated as curve $A$ and curve $C$, respectively. The dominant mode of the resulting slotline structure when the center strip conductor of the CPW is removed is designated as curve $B$. The numerical results represented by curve $A$ and curve $B$ above are in good agreement [8] with the spectral domain computations [16].
FIGURE 5.14 The quasi-TEM dominant mode (A) and the first higher-order mode (C) dispersion characteristics of a shielded grounded CPW: $S = 0.14 \text{ mm}$, $2B = 2 \text{ mm}$, $h = 0.2 \text{ mm}$, $W = 0.28 \text{ mm}$, $h_1 = 2 \text{ mm}$, $\varepsilon_r = 12.9$, $t = 0$. (From Reference [8], copyright © IEE.)

5.5 DISPERSION, CHARACTERISTIC IMPEDANCE, AND HIGHER-ORDER MODES OF A CPW SUSPENDED INSIDE A NONSYMMETRICAL SHIELDING ENCLOSURE

A CPW suspended inside a nonsymmetrical shielding enclosure is shown in Figure 5.15. This structure is analyzed using the transverse resonance technique in [11], the spectral domain technique in [18] and the modal analysis method in [19]. The computed dispersion characteristics [11], for the dominant mode as well as the first two higher order modes are shown in Figure 5.16. The theoretical analysis takes into consideration the finite conductor thickness as well as the groove dimensions. However, their effect is very small on the dispersion characteristics in the frequency range considered. The characteristic is almost a straight line and therefore the dispersion is almost negligible over the frequency range considered. Figure 5.17(a) and (b) shows the computed $Z_0$ as a function of the normalized center conductor strip width with the normalized height of the shielding and normalized separation between the CPW ground planes as parameters, respectively [22]. From this figure it is observed that a wide range of characteristic impedances from about 25 $\Omega$ to over 200 $\Omega$ can be realized by appropriately choosing the geometry.
FIGURE 5.15  Schematic of a nonsymmetrically shielded coplanar waveguide.

The cutoff frequency for the first higher-order mode discussed earlier is computed as a function of the normalized center conductor strip width with the normalized height of the housing as a parameter. It is observed that the cutoff frequency is insensitive to either of these parameters [22] as shown in Figure 5.18. In fact it is approximately equal to the cutoff frequency of the fundamental mode of the rectangular waveguide of width $2B_2$.

FIGURE 5.16  Computed and experimentally measured propagation constant as a function of the frequency for the dominant and the first two higher-order modes. Circular dots are experimental data; $2B_1 = 15.8\,\text{mm}$, $2B_2 = 22.86\,\text{mm}$, $h_1 = h_2 = B_2$, $h = 0.254\,\text{mm}$, $t = 0.035\,\text{mm}$, $S = 4.76\,\text{mm}$, $W = 1.57\,\text{mm}$, $\varepsilon_r = 2.2$. (From Reference [11], © 1989 IEEE.)
FIGURE 5.17 Computed characteristic impedance as a function of the center conductor strip width: $2B_1 = 15.8$ mm, $2B_2 = 22.86$ mm, $h_2 = 11.43$ mm, $h = 0.254$ mm, $t = 0.035$ mm, $\varepsilon_r = 2.2$, $f = 4$ GHz. (a) With $h_1$ as a parameter for $(S + 2W)/2B_1 = 0.5$; (b) with $S + 2W$ as a parameter for $h_1/2B_2 = 0.1$. (From Reference [22], © 1989 IEEE.)

FIGURE 5.18 Computed normalized cutoff frequency of the first higher-order mode as a function of the center conductor strip width with the normalized height of the shield on a parameter: $2B_1 = 15.8$ mm, $2B_2 = 22.86$ mm, $h_2 = 11.43$ mm, $h = 0.254$ mm, $t = 0.035$, $\varepsilon_r = 2.2$, $(S + 2W)/2B_1 = 0.5$. (From Reference [22], © 1989 IEEE.)
The effect of the mounting recess dimensions are significant at higher millimeter wave frequencies. As an example, in Figure 5.19 the computed cutoff frequency of the first higher-order mode is shown as a function of the recess depth [18]. It is also interesting to observe that the cutoff frequency depends on the type of mounting structure. For example, in the case of the groove and the inverse pedestal, the cutoff frequency decreases as the recess dimension increases. However, in the case of the pedestal, the cutoff frequency initially increases and beyond a certain recess dimension it decreases. Therefore there is an optimum choice of the pedestal dimensions for wide bandwidth.

5.5.1 Experimental Validation of the Dispersion Characteristics

To validate the computed results, a measurement technique utilizing a resonant cavity is used [11]. The cavity is formed by two rectangular waveguides that share a common broad wall which is formed by the suspended CPW substrate. The length $L$ of the cavity is about five wavelengths at the center frequency, which is about 15 cms. Further the cavity is terminated by a short circuit at either ends. A two-port resonator is realized from this cavity by introducing two coaxial launchers. The coaxial launchers are oriented perpendicular to the suspended CPW substrate and enters the cavity from the two opposite broad walls as shown in Figure 5.20. The center conductor of the coaxial launchers are shorted to the cavity end walls and a part of the outer conductor is exposed to provided a weak magnetic coupling. The magnetic-field line trajectories at resonance are such that they loop around the center conductors of the launchers and are also normal to the plane of the suspended CPW substrate.
Thus transverse magnetic fields are excited on the CPW circuit. This orientation of the magnetic fields allows a magnetic wall to be placed along the plane of symmetry analogous to a conventional CPW discussed in Chapter 2. The resonant frequencies corresponding to different mode number \( i \) and longitudinal order \( n \) are determined from the broadband swept frequency transmission measurements. The propagation constant \( \beta_i \) of mode \( i \) at frequency \( f_{ni} \) is determined from [11]

\[
\frac{\beta_i}{k_o} = \frac{nc}{2Lf_{ni}}.
\]

(5.8)

where \( k_o = 2\pi/\lambda_0 \) and \( \lambda_0 \) is the free space wavelength. The velocity of light in free space is denoted as \( c \). The experimentally determined propagation constant is superimposed on the computed results in Figure 5.16 and is observed to be in good agreement [11].

### 5.6 Dispersion and Characteristic Impedance of Suspended CPW on Multilayer Dielectric Substrate

A suspended CPW on a multilayer dielectric substrate is shown in Figure 5.1(d). The preceding generalized structure can be reduced to two useful practical structures, namely suspended CPW on a double-layer substrate and on a sandwiched substrate. These two structures are analyzed in [23], and their computed dispersion and characteristic impedance are presented here. Figures 5.21(a) and 5.22(a) show the \( \lambda_g/\lambda_0 \) and \( Z_0 \) as a function of the normalized
FIGURE 5.21 Computed guide wavelength ratio and characteristics impedance for CPW on suspended double-layer dielectric substrate: \(W/(h + h_3) = 0.25\), \(h = 3.2\) mm, \(h_3 = 5.0\) mm, \(B = H\), \(h_1 = h_4\), \(\varepsilon_r = 2.55\), \(\varepsilon_{r3} = 2.62\), \(t = 0\), \(h_2 = 0\). (a) Function of the normalized substrate thickness with the normalized height of the shielding enclosure as a parameter, \(S/(h + h_3) = 1.0\); (b) function of the frequency with the normalized slot width as a parameter, \((h + h_3)/H = 0.1\).
FIGURE 5.22  Computed guide wavelength ratio and characteristic impedance for CPW on suspended sandwiched dielectric substrate: $h_2 = h$, $W/h = 0.25$, $B = H$, $h_1 = h_4$, $h_3 = 0$, $t = 0$, $\varepsilon_r = \varepsilon_{r,2} = 9.6$. (a) Function of the normalized substrate thickness with the normalized height of the shielding enclosure as a parameter, $S/h = 1.0$; (b) function of the frequency with the normalized slot width as a parameter, $h/H = 0.1$. 
substrate thickness with the normalized height of the shielding enclosure as a parameter for the two structures, respectively. It is observed that the characteristics are almost insensitive to the height of the enclosure. In Figures 5.21(b) and 5.22(b), $\lambda_g/\lambda_0$ and $Z_0$ for the two structures are plotted as a function of the frequency with the normalized slot width as a parameter.

It is observed that as the slot width increases, the ratio $S/(S + 2W)$ decreases; consequently the characteristic impedance increases and the guide wavelength ratio decreases. For large slot width, the $\lambda_g/\lambda_0$ is almost constant with frequency, indicating that the structure is dispersion free.

REFERENCES


REFERENCES


CHAPTER 6

Coplanar Striplines

6.1 INTRODUCTION

The coplanar stripline (CPS) consists of a dielectric substrate with two parallel strip conductors separated by a narrow gap. This basic structure is referred to as the conventional CPS. The advantages of CPS are as follows: (1) Both series as well as shunt mounting of devices is possible. (2) The CPS is a balanced transmission line. Hence its applications include balanced mixers and feed network work for printed dipole antennas. The main disadvantage of the CPS is that because it lacks a ground plane, the line can support besides the fundamental CPS mode two other parasitic modes, namely the TE_{0} and TM_{0} dielectric slab waveguide modes. These parasitic modes do not have a cutoff frequency. The TE_{0} and TM_{0} modes have their electric fields predominantly parallel and perpendicular to the dielectric–air interface, respectively. The electric field of the fundamental CPS mode is predominantly parallel to the dielectric-air interface and hence strongly couples to the TE_{0} parasitic mode at discontinuities.

In Section 6.2 analytical expressions for effective dielectric constant and characteristics impedance for CPS and CPS variants are presented. In deriving the analytical expressions using conformal mapping technique, the CPS is assumed to be on an isotropic homogeneous dielectric of arbitrary thickness and relative permittivity. Further the metallization is assumed to have perfect conductivity and zero thickness. The variants considered are the asymmetric CPS (ACPS), the CPS with a infinitely wide ground plane (CPSWG), and the CPS with isolating ground planes (CPSIG). The advantage of the asymmetric CPS over conventional CPS is the flexibility to adjust the propagation parameters by changing the width of one of the strips while keeping the widths of the other strip and the gap fixed. The CPS with isolating ground planes has several advantages. First, line-to-line coupling is reduced because of the isolation provided by the ground planes. Second, the parasitic TE_{0} dielectric slab waveguide mode discussed earlier is eliminated. Third, flexibility in
obtaining lower characteristic impedance is added by the possibility of adjusting the outer slot width.

In Section 6.3 synthesis formulas to determine the slot width and the strip conductor width of conventional CPS are presented. Finally in Section 6.4 a few novel variants of the CPS, namely micro-coplanar stripline and CPS with a groove, are discussed.

6.2 ANALYTICAL EXPRESSIONS BASED ON QUASI-STATIC TEM CONFORMAL MAPPING TECHNIQUES TO DETERMINE EFFECTIVE DIELECTRIC CONSTANT AND CHARACTERISTIC IMPEDANCE

6.2.1 Coplanar Stripline on a Multilayer Dielectric Substrate

A coplanar stripline (CPS) sandwiched between multilayer dielectric substrates is shown in Figure 6.1. The strip and slot widths are indicated as $W$ and $S$, respectively. On this structure a quasi-static TEM mode is assumed to propagate. For the quasi-static TEM mode, the effective dielectric constant $\varepsilon_{\text{eff}}$, the phase velocity $v_p$, and the characteristic impedance $Z_0$ are given by Eqs. (4.1), (4.2), and (4.3), respectively. Since these quantities are related to the

![FIGURE 6.1 Schematic of a coplanar stripline (CPS) on a multi-layer dielectric substrate.](image)
capacitance of structure, the first step is to determine the capacitance per unit length. This is accomplished by the method of superposition of partial capacitances as described in Section 4.2.1. Hence the capacitance per unit length of the CPS shown in Figure 6.1 is expressed as [1]

\[ C_{\text{CPS}} = C_0 + C_1 + C_2 + C_3 + C_4 + C_5. \]  

(6.1)

The configuration of these capacitances are similar to that shown in Figures 4.2(a) to (f). The capacitance \( C_0 \) per unit length of the CPS in the absence of all dielectric substrates is expressed as [1]

\[ C_0 = \varepsilon_0 \frac{K(k)}{K(k')}, \]  

(6.2)

where \( K \) is the complete elliptical integral of the first kind. The arguments \( k \) and \( k' \) are dependent on the geometry of the CPS and are given by [1]

\[ k = \sqrt{1 - \left(\frac{a}{b}\right)^2} \]  

(6.3)

and

\[ k' = \sqrt{1 - k^2} = \frac{a}{b} = \frac{S}{S + 2W}. \]  

(6.4)

The next step is to determine the capacitances \( C_1 \) to \( C_5 \). This can be accomplished by the conformal mapping technique as described Section 4.2.1 and through the application of Eq. (4.1), which yields the \( \varepsilon_{\text{eff}} \). A more direct and simple procedure to obtain the \( \varepsilon_{\text{eff}} \) is through the application of the duality principle. The duality principle as described in [2] and [3] states that the \( \varepsilon_{\text{eff}} \) of complementary structures are identical. The CPS and the conventional CPW with infinitely wide top ground planes are considered as dual structures. Hence their effective dielectric constants are identical. Strictly this is true when the respective substrates are infinitely thick. However, the computed results in [4] indicate that the \( \varepsilon_{\text{eff}} \) of the two transmission lines are approximately the same for substrate thickness equal to or greater than five times the \( b \) dimension. In most applications involving microwave integrated circuits this requirement is met. Hence the expression for CPS effective dielectric constant \( \varepsilon_{\text{eff}}^{\text{CPS}} \) is derived using the duality principle. Accordingly the dimension \( c \) in Eq. (4.17) is set equal to infinity, which results in the following expression [1]:

\[ \varepsilon_{\text{eff}}^{\text{CPS}} = \frac{C_{\text{CPS}}}{C_0} \]

\[ = 1 + \frac{1}{2} (\varepsilon_{r1} - 1) \frac{K(k)K(k')}{K(k')K(k')} \]
Where \( \varepsilon_{ri} \) \((i = 1, 2, 3, 4, 5)\) is the relative permittivity of the dielectric substrate and \( K \) is the complete elliptical integral of the first kind. The arguments \( k \) and \( k' \) are given by Eqs. (6.3) and (6.4), respectively. The arguments \( k_i \) and \( k'_i \) are defined as follows:

\[
k_i = \sqrt{1 - \frac{\sinh^2(\pi a/2h_i)}{\sinh^2(\pi b/2h_i)}}, \quad i = 1, 2, 3, 4, 5.
\]

and

\[
k'_i = \sqrt{1 - k_i^2},
\]

where \( h_i \) is the dielectric substrate thickness as indicated in Figure 6.1.

The phase velocity and characteristic impedance from Eqs. (4.2), (4.3), and (6.5) are

\[
v_{ph}^{CPS} = \frac{c'}{\sqrt{\varepsilon_{eff}^{CPS}}},
\]

\[
Z_0^{CPS} = \frac{120\pi}{\sqrt{\varepsilon_{eff}^{CPS}}} \frac{K(k')}{K(k)}.
\]

where \( c' \) is the velocity of light in free space.

### 6.2.2 Coplanar Stripline on a Dielectric Substrate of Finite Thickness

A coplanar stripline on a dielectric substrate of finite thickness is shown in Figure 6.2. The \( \varepsilon_{eff}^{CPS} \) for this transmission line is easily obtained by setting \( \varepsilon_{r1} = \varepsilon_{r2} = \varepsilon_{r3} = \varepsilon_{r4} = 1 \) in Eq. (6.5). With this substitution and simplification the new expression is as follows:

\[
\varepsilon_{eff}^{CPS} = 1 + \frac{1}{2} (\varepsilon_{r5} - 1) \frac{K(k) K(k'_s)}{K(k')} K(k_s).
\]

\( (6.10) \)
FIGURE 6.2 Schematic of a CPS on a dielectric substrate of finite thickness.

where $K$ is the complete elliptical integral of the first kind. The arguments $k$, $k'$, $k_5$, and $k'_5$ are given by Eqs. (6.3), (6.4), (6.6), and (6.7), respectively.

From duality principle discussed in the previous section, Eq. (6.10) is identical to that given in [5] for CPW. Therefore the computed $\varepsilon_{\text{eff}}^{\text{CPS}}$ is the same as $\varepsilon_{\text{eff}}^{\text{CPW}}$ which is shown in Figure 2.6(a) in Section 2.2.3.

The characteristic impedance $Z_0^{\text{CPS}}$ computed from Eqs. (6.9) and (6.10) is shown in Figure 6.3. Since CPS and CPW are complementary structures, the

FIGURE 6.3 Computed characteristic impedance of CPS as a function of $S/(S + 2W)$, with the normalized substrate $h_5/b$ as a parameter. $\varepsilon_{15} = 10.0$, $t = 0$. (From Reference [5], copyright © IEE.)
product of $Z_0^{\text{CPS}}$ and $Z_0^{\text{CPW}}$ is a constant and is expressed as [2]

$$Z_0^{\text{CPS}} Z_0^{\text{CPW}} = \frac{\eta^2}{4e_{\text{eff}}^{\text{CPS}}} = \frac{\eta^2}{4e_{\text{eff}}^{\text{CPW}}}$$  \hspace{1cm} (6.11)

where $\eta$ is the intrinsic impedance of the medium and is equal to $376.73 \Omega \approx 120\pi$.

6.2.3 Asymmetric Coplanar Stripline on a Dielectric Substrate of Finite Thickness

In an asymmetric coplanar stripline (ACPS) one strip conductor is wider than the other, as shown in Figure 6.4. The strip widths $W_1$ and $W_2$ and the separation $S$ between them are indicated in the same figure. The capacitance per unit length of the line in the absence of the dielectric substrate is given by the expression [6]

$$C_0^{\text{ACPS}} = 2\varepsilon_0 \frac{K(k')}{K(k)},$$  \hspace{1cm} (6.12)

where $\varepsilon_0$ is the permittivity of free space and $K$ is the complete elliptic integral of the first kind. The arguments $k$ and $k'$ are [6]

$$k = \sqrt{\frac{(2a)(b_1 + b_2)}{(a + b_1)(a + b_2)}},$$  \hspace{1cm} (6.13)

$$k' = \sqrt{1 - k^2} = \sqrt{\frac{(b_1 - a)(b_2 - a)}{(a + b_1)(a + b_2)}},$$  \hspace{1cm} (6.14)

FIGURE 6.4 Schematic of asymmetric coplanar stripline (ACPS) on a dielectric substrate of finite thickness.
where
\[
a = S/2 \\
b_1 = a + W_1 \\
b_2 = a + W_2.
\]

The characteristic impedance of the line in the absence of the dielectric substrate is defined as [6]

\[
Z_{0(\text{air})}^{\text{ACPS}} = \left( \frac{L}{C_0^{\text{ACPS}}} \right)^{1/2}, \tag{6.15}
\]

where \( L \) is the inductance per unit length of the line and is given by

\[
L = \frac{1}{(c')^2 C_0^{\text{ACPS}}} \tag{6.16}
\]

where \( c' \) is the velocity of light in free space. Substituting Eqs. (6.12) and (6.16) into Eq. (6.15) and simplifying gives [6]

\[
Z_{0(\text{air})}^{\text{ACPS}} = 60\pi \frac{K(k)}{K(k')} . \tag{6.17a}
\]

In the presence of the dielectric substrate, the expression above has to be modified to take into account the ACPS effective dielectric constant \( \varepsilon_{\text{eff}}^{\text{ACPS}} \). Thus the characteristic impedance in the presence of a dielectric substrate is

\[
Z_0^{\text{ACPS}} = \frac{60\pi}{\sqrt{\varepsilon_{\text{eff}}^{\text{ACPS}}}} \frac{K(k)}{K(k')} . \tag{6.17b}
\]

The \( \varepsilon_{\text{eff}}^{\text{ACPS}} \) is given below for two cases, namely infinitely thick substrate and finite thickness substrate. The \( \varepsilon_{\text{eff}}^{\text{ACPS}} \) in the case of an infinitely thick substrate is [7]

\[
\varepsilon_{\text{eff}}^{\text{ACPS}} = \frac{(\varepsilon_r + 1)}{2} , \tag{6.18}
\]

where \( \varepsilon_r \) is the relative permittivity of the dielectric substrate.

The \( \varepsilon_{\text{eff}}^{\text{ACPS}} \) in the case of a finite thickness substrate is [6]

\[
\varepsilon_{\text{eff}}^{\text{ACPS}} = 1 + \frac{\varepsilon_r - 1}{2} \frac{K(k)}{K(k')} \frac{K(k')}{K(k_2)} , \tag{6.19}
\]

where \( \varepsilon_r \) is the relative permittivity of the dielectric substrate, \( K \) is the complete
elliptic integral of the first kind and the arguments $k$ and $k'$ are given by Eqs. (6.13) and (6.14), respectively. The arguments $k_2$ and $k'_2$ are [6]

$$k_2 = \frac{\left\{\exp[2\pi(b_1 + a)/h] - \exp[2\pi(b_1 - a)/h]\right\}\{\exp[2\pi(b_1 + b_2)/h] - 1\}}{\sqrt{\{\exp[2\pi(b_1 + b_2)/h] - \exp[2\pi(b_1 - a)/h]\}\{\exp[2\pi(b_1 + a)/h] - 1\}}},$$  \hspace{1cm} (6.20)

$$k'_2 = \sqrt{1 - k_2^2},$$  \hspace{1cm} (6.21)

where $h$ is the substrate thickness.

Equation 6.17(b) reduces to Eq. (6.9) when the two strip conductors are symmetric, that is, when $b_1 = b_2 = b$. To demonstrate that this happens, the following transformation rules for elliptic integrals are considered:

$$K(k) = (1 + k_s)K(k_s),$$  \hspace{1cm} (6.22)

$$K(k') = \frac{1 + k_s}{2} K(k'_s),$$  \hspace{1cm} (6.23)

where the arguments $k_s$ and $k'_s$ correspond to the symmetric case and

$$k'_s = \sqrt{1 - k_s^2},$$  \hspace{1cm} (6.24)

$$k = \frac{2\sqrt{k_s}}{1 + k_s},$$  \hspace{1cm} (6.25)

$$k' = \frac{1 - k_s}{1 + k_s}.$$  \hspace{1cm} (6.26)

On substituting $b_1 = b_2 = b$ into Eqs. (6.13) and (6.15), we obtain

$$k = \frac{2\sqrt{a/b}}{1 + (a/b)},$$  \hspace{1cm} (6.27)

$$k' = \frac{1 - (a/b)}{1 + (a/b)}.$$  \hspace{1cm} (6.28)

By equating Eqs. (6.27) and (6.28) to Eqs. (6.25) and (6.26) respectively, we obtain

$$k_s = \frac{a}{b},$$  \hspace{1cm} (6.29)

$$k'_s = \sqrt{1 - \left(\frac{a}{b}\right)^2}.$$  \hspace{1cm} (6.30)

The next step is to replace $k_s$ and $k'_s$ in Eqs. (6.22) and (6.23), respectively, by
the quantities above and then to substitute Eqs. (6.22) and (6.23) into Eq. (6.17b). Equation (6.17b), when simplified, reduces to Eq. (6.9).

### 6.2.4 Coplanar Stripline with Infinitely Wide Ground Plane on a Dielectric Substrate of Finite Thickness

A coplanar stripline with infinitely wide ground plane (CPSWG) is shown in Figure 6.5. The strip width $W$ and the separation $S$ between the strip and the ground are also indicated in the same figure. The capacitance per unit length of the line in the absence of the dielectric substrate is \[ C_{0}^{\text{CPSWG}} = 2\varepsilon_0 \frac{K(k_3')}{K(k_3)} \] (6.31)

where $K$ is the complete elliptic integral of the first kind and the arguments $k_3$ and $k_3'$ are obtained by $b_1 \to \infty$ and $b_2 = b$ in Eqs. (6.13) and (6.14), respectively. Thus

\[
k_3 = \sqrt{\frac{2a}{a + b}}
\]
(6.32)

\[
k_3' = \sqrt{1 - k_3^2} = \frac{(b - a)}{(b + a)}
\]
(6.33)

where the strip and slot widths are $2a$ and $(b - a)$, respectively.

**FIGURE 6.5** Schematic of coplanar stripline with infinitely wide ground plane (CPSWG) on a dielectric substrate of finite thickness.
The characteristic impedance in the absence of the dielectric substrate is derived as in Section 6.2.3, and it is written as

\[
Z_{0\text{(air)}}^\text{CPSWG} = 60\pi \frac{K(k'_3)}{K(k_3)},
\]

(6.34)

In the presence of a dielectric substrate, the expression above is modified by the effective dielectric constant \(\varepsilon_{\text{eff}}^\text{CPSWG}\). The \(\varepsilon_{\text{eff}}^\text{CPSWG}\) determined by the method of superposition of partial capacitances is [6]

\[
\varepsilon_{\text{eff}}^\text{CPSWG} = 1 + \frac{\varepsilon_r - 1}{2} \frac{K(k_3) K(k'_4)}{K(k'_3) K(k_4)},
\]

(6.35)

where \(\varepsilon_r\) is the relative permittivity of the dielectric substrate and \(K\) is the complete elliptic integral of the first kind. The arguments \(k_3\) and \(k'_3\) are given by Eqs. (6.32) and (6.33), respectively. The arguments \(k_4\) and \(k'_4\) are given by [6]

\[
k_4 = \sqrt{\frac{\exp(2\pi a/h) - 1}{\exp[\pi(b + a)/h] - 1}},
\]

(6.36)

\[
k'_4 = \sqrt{1 - k^2_4} = \sqrt{\frac{\exp[\pi(b + a)/h] - \exp(2\pi a/h)}{\exp[\pi(b + a)/h] - 1}},
\]

(6.37)

where \(h\) is the dielectric substrate thickness. The corresponding characteristic impedance is given by

\[
Z_{0\text{CPSWG}}^\text{CPSWG} = \frac{60\pi}{\sqrt{\varepsilon_{\text{eff}}^\text{CPSWG}}} \frac{K(k'_3)}{K(k_3)}.
\]

(6.38)

### 6.2.5 Coplanar Stripline with Isolating Ground Planes on a Dielectric Substrate of Finite Thickness

This configuration of the coplanar stripline has additional ground planes symmetrically located on either side of the balanced pair of signal lines as shown in Fig. 6.6. This variant of the conventional CPS is known as the coplanar stripline with isolating ground planes (CPSIG) [8]. The effective dielectric constant \(\varepsilon_{\text{eff}}^\text{CPSIG}\) is given by the expression [8]

\[
\varepsilon_{\text{eff}}^\text{CPSIG} = 1 + \left(\frac{\varepsilon_r - 1}{2}\right) \frac{K(k'_1) K(k'_4)}{K(k'_1) K(k_4)},
\]

(6.39)
FIGURE 6.6 Schematic of coplanar stripline with isolating ground planes on a dielectric substrate of finite thickness.

where $\varepsilon_r$ is the relative permittivity of the dielectric substrate and $K$ is the complete elliptic integral of the first kind. The arguments $k$, $k'$, $k_1$, and $k'_1$ are given by [8]

\begin{align}
  k &= \frac{a}{b} \sqrt\frac{1 - (b/c)^2}{1 - (a/c)^2}, \\
  k' &= \sqrt{1 - k^2}, \\
  k_1 &= \frac{\sinh(\pi a/2h)}{\sinh(\pi b/2h)} \sqrt\frac{1 - \frac{\sinh^2(\pi b/2h)}{\sinh^2(\pi c/2h)}}{1 - \frac{\sinh^2(\pi a/2h)}{\sinh^2(\pi c/2h)}}, \\
  k'_1 &= \sqrt{1 - k_1^2},
\end{align}

where $h$ is the dielectric substrate thickness. The strip and slot widths are $b-a$ and $2a$, respectively. The separation between the ground planes is $2c$. The characteristic impedance is given by [8]

\begin{equation}
  Z_0^{\text{cpsig}} = \frac{120\pi}{\sqrt{\varepsilon_{\text{eff}}}} \frac{K(k)}{K(k')}.
\end{equation}
6.3 COPLANAR STRIPLINE SYNTHESIS FORMULAS TO DETERMINE THE SLOT WIDTH AND THE STRIP CONDUCTOR WIDTH

A CPS with zero thickness conductors on a dielectric of relative permittivity $\varepsilon_r$ is shown in Figure 6.7. In this figure, the strip and slot widths are denoted as $W$ and $S$ respectively. For this CPS accurate closed form synthesis formulas are available in the literature [9]. These formulas are based on function approximation and curve fitting quasi-static analysis results. The application range of these formulas encompass most CPS circuit design, including monolithic microwave integrated circuits. The accuracy of these formulas is better than 1 percent when compared with the spectral domain [10] results. The expression for the slot width $S$ will be first presented.

**Synthesis Formula for Slot Width $S$**

When

$$\frac{W}{h} \leq \frac{10}{1 + \ln \varepsilon_r} \quad \text{and} \quad \frac{S}{h} \leq \frac{10}{3(1 + \ln \varepsilon_r)}, \quad (6.45)$$

the separation or the slot width $S$ can be expressed as

$$S = W \times G(\varepsilon_r, h, Z_0, W) \quad (6.46)$$

with

$$G = \left[ \frac{1}{8} \exp \left( \frac{60\pi^2}{Z_0^{0.5}} \right) - \frac{1}{2} \right]^{-1} \quad \text{for} \quad Z_0 \leq \frac{60\sqrt{2}\pi}{(\varepsilon_r + 1)^{0.5}}, \quad (6.47a)$$

$$G = \frac{1}{4} \exp \left( \frac{Z_0^{0.5}}{120} \right) + \exp \left( -\frac{Z_0^{0.5}}{120} \right) - 1 \quad \text{for} \quad Z_0 > \frac{60\sqrt{2}\pi}{(\varepsilon_r + 1)^{0.5}}, \quad (6.47b)$$
where the effective dielectric constant \( \varepsilon_{\text{eff}} \) is given by

\[
\varepsilon_{\text{eff}} = \varepsilon_{\text{eff}}(\varepsilon_r, h, Z_0, W) = T_1 \times \left( 1 + \frac{\varepsilon_r - 1}{Z_0(\varepsilon_r + 1)^{0.5}} T_2 \right)
\]

(6.48)

with

\[
T_1 = 1 + \tanh \left\{ \frac{Z_0^2 \varepsilon_r^7}{720 \pi^3 (\varepsilon_r + 1)^8} \times \exp \left[ \left( 1 + 0.0004 \varepsilon_r \frac{Z_0}{h} \right) \ln \left( \frac{W}{h} \right) \right] \right\}
\]

(6.49)

and

\[
T_2 = 84.85 \ln \left( \frac{2}{1 + g} \frac{1 + g}{1 - g} \right) \quad \text{for} \quad 0.841 \leq g \leq 1,
\]

(6.50a)

\[
T_2 = \frac{837.5}{\ln \left( \frac{2}{1 + (1 - g^4)^{0.25}} \frac{1 - (1 - g^4)^{0.25}}{1 - (1 - g^4)^{0.25}} \right)} \quad \text{for} \quad 0 < g \leq 0.841,
\]

(6.50b)

\[
g = \left\{ \begin{array}{ll}
\exp \left( \frac{\pi(1 + Q)W}{2h} \right) - \exp \left( \frac{\pi W}{2h} \right) \bigg/ 0.5,

\exp \left( \frac{\pi(2 + Q)W}{2h} \right) - 1
\end{array} \right\},
\]

(6.51)

\[
Q = G|_{\varepsilon_{\text{eff}}}^{\varepsilon_{\text{eff}}+1}.
\]

(6.52)

**Synthesis Formula for Strip Conductor Width W**

When

\[
\frac{S}{h} \leq \frac{10}{3(1 + \ln \varepsilon_r)} \quad \text{and} \quad \frac{W}{h} \leq \frac{10}{1 + \ln \varepsilon_r}
\]

(6.53)

the strip conductor width \( W \) can be expressed as

\[
W = \frac{S}{G(\varepsilon_r, h, Z_0, W)}
\]

(6.54)

with

\[
G = \left[ \frac{1}{8} \exp \left( \frac{60 \pi^2}{Z_0 \varepsilon_{\text{eff}}^{0.5}} \right) - \frac{1}{2} \right]^{-1} \quad \text{for} \quad Z_0 \leq \frac{60 \sqrt{2} \pi}{(\varepsilon_r + 1)^{0.5}},
\]

(6.55a)
\[ G = \frac{1}{4} \exp \left( \frac{Z_0 \varepsilon_{\text{eff}}^{0.5}}{120} \right) + \exp \left( - \frac{Z_0 \varepsilon_{\text{eff}}^{0.5}}{120} \right) - 1 \quad \text{for} \quad Z_0 > \frac{60\sqrt{2}\pi}{(\varepsilon_r + 1)^{0.5}}. \] (6.55b)

In the expressions above, \( \varepsilon_{\text{eff}} \) is given by

\[ \varepsilon_{\text{eff}} = \varepsilon_{\text{eff}}(\varepsilon_r, h, Z_0, S) = T_1 \times \left( 1 + \frac{\varepsilon_r - 1}{Z_0(\varepsilon_r + 1)^{0.5}} T_2 \right) \] (6.56)

with

\[ T_1 = \text{sech} \left\{ \frac{\pi \varepsilon_r^5}{(\varepsilon_r + 1)^6} \left( \frac{60}{Z_0} \right)^2 \times \exp \left[ \left( 1 + \varepsilon_r \left( \frac{Z_0}{121} \right)^4 \frac{S}{Qh} \right) \ln \left( \frac{S}{Qh} \right) \right] \right\} \] (6.57)

and

\[ T_2 = 84.85 \ln \left( \frac{2 \left( 1 + g \right)}{1 - g} \right) \quad \text{for} \quad 0.841 \leq g \leq 1, \] (6.58a)

\[ T_2 = \frac{837.5}{\ln \left( 2 \frac{1 + \left( 1 - g^4 \right)^{0.25}}{1 - \left( 1 - g^4 \right)^{0.25}} \right)} \quad \text{for} \quad 0 < g \leq 0.841, \] (6.58b)

\[ g = \left( \frac{\exp \left( \frac{\pi(1 + 1/Q)S}{2h} \right) - \exp \left( \frac{\pi S}{2Qh} \right) \right)^{0.5}}{\exp \left( \frac{\pi(1 + 2/Q)S}{2h} \right) - 1} \right), \] (6.59)

\[ Q = G \big|_{\varepsilon_{\text{eff}} = \varepsilon_r + 1}. \] (6.60)

### 6.4 NOVEL VARIANTS OF THE COPLANAR STRIPLINE

#### 6.4.1 Micro-coplanar Stripline

The geometry of the micro-coplanar stripline (MCPS) [11] is shown in Figure 6.8. In the MCPS a very thin dielectric spacer layer separates the two strip conductors. The spacer layer and the strip conductors are supported from below by a dielectric substrate.

The MCPS has several advantages, some of which are discussed here: (1) The dimensions of the strip conductors as well as the spacer layer are on the order of few microns for a 50\( \Omega \) transmission line. Thus the transmission line is very compact, resulting in small amount of parasitics when combined with active devices. (2) The strip conductors are on two levels, thus making vertical as well as horizontal integration possible. This feature is useful in applications,
FIGURE 6.8 Micro-coplanar stripline (MCPS) configuration. (a) Strips overlap; (b) strip edges are even; (c) strips are separated.
FIGURE 6.9 Micro-coplanar stripline: (a) Effective dielectric constant and (b) characteristic impedance. $h = 200 \mu m$, $h_z = 1.35 \mu m$, $\varepsilon_{r1} = 3.1$, $\varepsilon_{r2} = 11.7$, $W = 10 \mu m$, $t_1 = t_2 = 0.45 \mu m$. 
Figure 6.10  Coplanar stripline with a Groove.

Figure 6.11  Computed characteristic impedance: (a) Conventional CPS, \( \varepsilon_r = 35.2, \) \( S = 5 \mu m, \) and \( t = 3 \mu m; \) (b) CPS with a groove, \( \varepsilon_r = 35.2, \) \( S = 5 \mu m, \) \( W = 8 \mu m, \) \( t = 3 \mu m. \) (From Reference [17] © 1980 IEEE.)
such as mixers using broadside couplers with tight coupling and wide bandwidth. (3) The spacer layer is very thin, hence making it possible to realize large capacitances in a small area. This feature is particularly desirable in the design of compact low-pass and band-pass filters. (4) The two strip conductors form a balanced line, making the MCPS an ideal line for feeding integrated antennas, such as patches, bow ties, and dipoles.

The MCPS is modeled using the well-known FDTD technique [12], [13], [14]. The model assumes a high resistivity silicon wafer ($\varepsilon_r = 11.7$) as the substrate and spin-on-glass (SOG) [15] ($\varepsilon_r = 3.1$) as the spacer layer. In addition the model takes into consideration the finite thickness of the substrate, spacer layer, and the strip conductors. The computed $\varepsilon_{\text{eff}}$ and $Z_0$ are presented in Figure 6.9. The figure shows that $\varepsilon_{\text{eff}}$ and $Z_0$ are small when the two strip conductors fully overlap each other. As the overlap decreases and the strip conductors separate, the $\varepsilon_{\text{eff}}$ and $Z_0$ increase. Thus a very wide range of impedances can be realized.

### 6.4.2 Coplanar Stripline with a Groove

A CPS with a groove of depth $D$ in the dielectric substrate between the strip conductors is shown in Figure 6.10. This variant of the CPS was first investigated in connection with travelling wave electrooptic modulators on LiNbO$_3$ ($\varepsilon_r \approx 35$) substrate [16]. For a desired characteristic impedance $Z_0$, separation $S$ between the two strips and strip conductor thickness $t$, this variant of the CPS has a much wider strip width $W$ than a conventional CPS. This characteristic is evident when the computed $Z_0$ in Figure 6.11(a) for conventional CPS is compared with Figure 6.11(b) for CPS with a groove [17]. As an example, for a $Z_0$, $S$, and $t$ equal to 50 $\Omega$, 5 $\mu$m, and 34 $\mu$m, respectively, for conventional CPS $W$ is less than 3.75 $\mu$m while for the variant with a groove depth $D$ of about 2 $\mu$m, $W$ is 8 $\mu$m. Hence the CPS with a groove has potentially lower attenuation due to conductor losses. A second advantage of the groove is the lower $\varepsilon_{\text{eff}}$. Hence in traveling wave electrooptic modulators the velocity mismatch between the microwave signal and the optical signal is reduced, resulting in a wider bandwidth.

### REFERENCES


CHAPTER 7

Microshield Lines and Coupled Coplanar Waveguide

7.1 INTRODUCTION

This chapter is broadly divided into two types of transmission lines, microshield lines and coupled coplanar waveguides. Section 7.2 presents analytical equations to compute the characteristic impedance of microshield lines of various shapes. Section 7.3 presents analytical equations to compute the even-and odd-mode characteristics of edge coupled coplanar waveguides without a lower ground plane. Section 7.4 is devoted to conductor-backed edge coupled coplanar waveguides. Last, Section 7.5 presents the broadside coupled coplanar waveguides.

7.2 MICROSHIELD LINES

A microshield line [1] consists of a center strip conductor with two adjacent coplanar ground planes supported on a dielectric membrane and backed by a metalized shielding cavity. Figure 7.1(a) gives an example of a rectangular microshield line. In some applications an additional shielding metal cover may be present on the top side. Figure 7.1(b) shows a technique for fabricating a microshield line by attaching together two silicon wafers. The first wafer supports a membrane with a coplanar waveguide on the top surface. This wafer is anisotropically etched from below to form a cavity and the walls of the cavity are metalized. Since the membrane is very thin, the overlap capacitances between the top ground planes and cavity side walls are very large. Hence at microwave frequencies the overlap region behaves as a virtual short circuit to the propagating mode. The second wafer is metalized on the top surface and form the bottom wall of the cavity. This structure is therefore considered as an evolution of the microstrip line and the channelized coplanar waveguide discussed in Section 3.5, Chapter 3.
FIGURE 7.1  Rectangular microshield line: (a) Analytical model; (b) practical realization.

In the microshield line the effect of the membrane on the electromagnetic wave propagation is negligible, and the wave number $k$ is approximately the same in the regions above and below the center strip. The propagation constant $\gamma$ of the microshield line therefore satisfies the condition

$$\gamma^2 + k^2 = 0$$

for a true TEM-wave [2]. This suggest that the wave propagation on the microshield line can be modeled as a pure TEM-mode. The dimensions of the rectangular cavity in the example above are such that no higher-order modes are excited at the desired operating frequency.

In the sections that follow an expression for the total capacitance of microshield lines with lower cavity of different shapes are presented. The total capacitance per unit length of the microshield line is the sum of the capacitance of the upper air region and the lower shielding cavity region. These capacit-
tances are determined by a sequence of conformal mappings. In the conformal mapping technique all the metallic conductors of the structure are assumed to have negligible thickness and perfect conductivity. The width of the ground planes on either sides of the center strip conductor are considered to be infinite. The air-dielectric interface in the slot regions on either sides of the center strip conductor is assumed to behave as a perfect magnetic wall. Knowing the capacitance of the transmission line, the propagation parameters, such as effective dielectric constant \( \varepsilon_{\text{eff}} \) and characteristic impedance \( Z_0 \), are determined. Microshield lines with a rectangular shape, a \( V \)-shape, an elliptic shape, and a circular shape shielding cavities are considered in the subsequent sections.

### 7.2.1 Rectangular Shaped Microshield Line

A microshield line with a center strip conductor of width \( 2a \) symmetrically located between two finite ground planes separated by a distance \( 2b \) and backed by a rectangular shaped metalized cavity is shown in Figure 7.1(a). The width and depth of the cavity at any transverse section is \( L \) and \( h \), respectively. The cavity is assumed to be filled with a dielectric of relative permittivity \( \varepsilon_r \). To determine the \( \varepsilon_{\text{eff}} \) and \( Z_0 \) of the line, the capacitance of the structure is obtained using the Schwartz-Christoffel transformation. The total capacitance \( C_t \) per unit length is the sum of the capacitance \( C_a \) of the upper half-plane consisting of the air region and the capacitance \( C_{CR} \) of the lower half-plane consisting of the rectangular cavity. That is,

\[
C_t = C_a + C_{CR}. \tag{7.2}
\]

The capacitance \( C_a \) is determined in a manner similar to that in Section 4.2.1 and is one-half of that given by (4.5). Hence

\[
C_a = 2\varepsilon_0 \frac{K(k')}{K(k)}, \tag{7.3}
\]

where \( K(k_1) \) and \( K(k'_1) \) are the complete elliptic integrals of the first kind and the arguments \( k \) and \( k' \) are dependent on the geometry of the line and are given by

\[
k_1 = \frac{c}{b} \sqrt{\frac{b^2 - a^2}{c^2 - a^2}}, \tag{7.4}
\]

\[
k'_1 = \sqrt{1 - k^2} = \frac{a}{b} \sqrt{\frac{c^2 - b^2}{c^2 - a^2}}, \tag{7.5}
\]

where the widths \( a, b, \) and \( c \) are as indicated in Figure 7.1(a). If the ground planes extend to infinity on either sides and in the presence of a top metal cover
at a height $h_1$, the capacitance $C_a$ is determined in a manner similar to that in Section 2.2.1 and is given by

$$C_a = 2\varepsilon_0 \frac{K(k_1)}{K(k_1')}, \quad (7.6)$$

where

$$k_1 = \frac{\tanh(\pi S/4h_1)}{\tanh[\pi(S + 2W)/4h_1]}, \quad (7.7)$$

$$k_1' = \sqrt{1 - k_1^2}. \quad (7.8)$$

The capacitance $C_{CR}$ is given by [3], [4] as

$$C_{CR} = 2\varepsilon_0 \varepsilon_r \frac{K(k_2)}{K(k_2')} = 2\varepsilon_0 \varepsilon_r \frac{K(t_a/t_b)}{K(t_a/t_b)}, \quad (7.9)$$

where $t_a$, $t_b$, and $t_c$ are related to the geometry of the structure through the following set of equations:

$$\frac{F(\arcsin(t_a/t_c), t_c)}{K(t_c)} = \frac{2a}{L}, \quad (7.10)$$

$$\frac{F(\arcsin(t_b/t_c), t_c)}{K(t_c)} = \frac{2b}{L}, \quad (7.11)$$

$$t_c = \sqrt{1 - \left(\frac{\exp(2\pi/2h)}{\exp(2\pi/L) + 2}\right)^4} \quad \text{for } 0 < \frac{L}{2h} < 1, \quad (7.12)$$

$$t_c = \left(\frac{\exp(2\pi/L)}{\exp(2\pi/2h) + 2}\right)^2 \quad \text{for } 1 < \frac{L}{2h} < \infty. \quad (7.13)$$

In the equations above $K(t_c)$ is the complete elliptic integral of the first kind, and $F(\arcsin(t_a/t_c), t_c)$ and $F(\arcsin(t_b/t_c), t_c)$ are the incomplete elliptic integrals of the first kind written in the Jacobi’s notation. The functions $F(\arcsin(t_a/t_c), t_c)$ and $F(\arcsin(t_b/t_c), t_c)$ are evaluated for the values of $t_a/t_c$ and $t_b/t_c$ using the analytical formulas [4] presented below. While evaluating $t_a/t_c$, the subscript $x$ as well as the factor $x$ in the equations below are set equal to $a$. In a similar manner $t_b/t_c$ is evaluated with $x = b$.

For $0 \leq 2x/L \leq \delta_1 = [1/S(t_c)] \arcsin(t_c)$, \n
$$\frac{x}{t_c} = \sin \left\{ \frac{1}{t_c} \sin \left[ \frac{2x}{L} S(t_c) \right] \right\}. \quad (7.14)$$
For $\delta_1 \leq 2x/L \leq \delta_2 = 1 - [1/S(t_c)] \arcsinh(t_c \zeta/\sqrt{1 - t_c^2}),$

\[
\frac{t_x}{t_c} = \sin \left\{ \frac{\pi}{4} + \frac{1}{2\zeta} \left( \frac{1 - \psi^2}{t_c^2} - \frac{1}{2} \right) \right\},
\]

\[
\psi = \sqrt{1 - \frac{t_c^2}{2} \left( 1 - \zeta \xi \right) - t_c \xi S(t_c) \left\{ \frac{2x}{L} - \delta_1 \right\}}.
\]

For $\delta_2 \leq 2x/L \leq 1,$

\[
\frac{t_x}{t_c} = \cos \left\{ \sqrt{1 - t_c^2} \sinh \left[ \left( 1 - \frac{2x}{L} \right) S(t_c) \right] \right\},
\]

where

\[
\zeta = \frac{\pi}{4} - \frac{\xi}{4},
\]

\[
\xi = \sqrt{\pi^2 - 8},
\]

\[
S(t_c) = \arcsin(t_c \zeta) + \arcsinh(t_c \zeta/\sqrt{1 - t_c^2})
\]

\[
+ \frac{1}{\xi t_c} \left\{ \sqrt{1 - \frac{t_c^2}{2} \left( 1 - \zeta \xi \right)} - \sqrt{1 - \frac{t_c^2}{2} \left( 1 + \zeta \xi \right)} \right\}.
\]

The effective dielectric constant $\varepsilon_{\text{eff}}$ and the characteristic impedance $Z_0$ of the line, as defined in Section 2.2.1, are given by

\[
\varepsilon_{\text{eff}} = \frac{C_t}{C_a + C_{\text{CR}} \text{ (with } \varepsilon_r = 1)},
\]

\[
Z_0 = \frac{1}{c' [C_a + C_{\text{CR}} \text{ (with } \varepsilon_r = 1)]^{\varepsilon_{\text{eff}}}}.
\]

where $c'$ is the speed of light in free space. For a membrane supported line, the $\varepsilon_{\text{eff}} \approx 1.0,$ and hence

\[
Z_0 = \frac{1}{c' [C_a + C_{\text{CR}} \text{ (with } \varepsilon_r = 1)]}.
\]

Figure 7.2(a) shows the computed $Z_0$ as a function of the slot width $W$ with the center strip width $S$ as a parameter [3]. Figure 7.2(b) shows the computed $Z_0$ as a function of the normalized ground plane width $c'/b$ with the strip width $S$ as a parameter [3]. From this figure it is inferred that the finite extent ground planes have negligible effect on $Z_0$ as long as $c'/b > 2.$
7.2.2 V-Shaped Microshield Line

An asymmetric microshield line with a center strip conductor of width $S$ separated from two adjacent ground planes by a distance $W_1$ and $W_2$, respectively, and backed by a V-shaped metalized cavity is shown in Figure 7.3. At any transverse section along the line, the strip conductor, the ground planes and the V-shaped cavity walls form an inverted isosceles triangle with a base of width $L$ and an apex angle of $2\theta$. The cavity is assumed to be filled with a
FIGURE 7.3 V-shaped microshield line.

dielectric of relative permittivity $\varepsilon_r$. To determine the $\varepsilon_{\text{eff}}$ and $Z_0$ of the line, the capacitance of the structure is first obtained using the Schwartz-Christoffel transformation. The total capacitance $C_t$ per unit length is the sum of the capacitance $C_a$ of the upper half-plane consisting of the air region and the capacitance $C_{CV}$ of the lower half-plane consisting of the V-shaped cavity. That is,

$$C_t = C_a + C_{CV}. \quad (7.24)$$

The capacitance $C_a$ is given by [5]

$$C_a = \varepsilon_0 \frac{K(k_1)}{K(k_1)}, \quad (7.25)$$

where $K(k)$ is the complete elliptic integral of the first kind and the arguments $k$ and $k'$ are dependent on the geometry of the line. They are given by [5]

$$k_1 = \sqrt{\frac{S(S+W_1+W_2)}{(S+W_1)(S+W_2)}}, \quad (7.26)$$

$$k'_1 = \sqrt{1-k_1^2}. \quad (7.27)$$

The capacitance $C_{CV}$ is given by [5]

$$C_{CV} = \varepsilon_0\varepsilon_r \frac{K(k_2)}{K(k_2)}, \quad (7.28)$$

where

$$k_2 = \sqrt{\frac{2t_E(t_D-t_c)}{(t_E+t_D)(t_E-t_D)}}. \quad (7.29)$$
The function $t_x$ ($x$ equals to $C$, $D$, or $E$) depends on the value of $Z_x/Z_B$ ($x$ equals to $C$, $D$, or $E$) and is evaluated using the equations given below [5]:

\[
\begin{align*}
\frac{Z_E}{Z_B} &= \frac{W_2 + W_1 + S}{L}, \\
\frac{Z_C}{Z_B} &= \frac{W_2 - W_1 - S}{L}, \\
\frac{Z_D}{Z_B} &= \frac{W_2 - W_1 + S}{L},
\end{align*}
\]

(7.30)
(7.31)
(7.32)

\[
\psi = 1 + \frac{\pi}{4} - \sqrt{2} + \frac{\sqrt{2}}{1 - (2\theta/\pi)} \left[ 1 - \left( 1 - \frac{1}{\sqrt{2}} \left( \frac{1 - (\pi/4)}{\sqrt{2} - 1} \right)^{1 - (2\theta/\pi)} \right) \right].
\]

(7.33)

For $0 \leq Z_x/Z_B \leq [1 + (\pi/4) - \sqrt{2}]/\psi$,

\[
t_x = \sin \left( \psi \frac{Z_x}{Z_B} \right).
\]

(7.34)

For

\[
\frac{1 + (\pi/4) - \sqrt{2}}{\psi} \leq \frac{Z_x}{Z_B} \leq 1 - \frac{1}{\psi[1 - (2\theta/\pi)]} \left[ 1 - \left( \frac{\pi/4}{\sqrt{2} - 1} \right)^{1 - (2\theta/\pi)} \right]
\]

\[
t_x = \sin \left\{ 1 + \frac{\pi}{4} - \sqrt{2} \left[ 1 - \frac{1 - (2\theta/\pi)}{\sqrt{2}} \left( \psi \frac{Z_x}{Z_B} - 1 - \frac{\pi}{4} + \sqrt{2} \right) \right]^{1/[1 - (2\theta/\pi)]} \right\}
\]

(7.35)

For $1 - \{1/\psi[1 - (2\theta/\pi)]\}^2$ \{[1 - $(\pi/4)]/\sqrt{2} - 1\}^{1 - (2\theta/\pi)} \leq Z_x/Z_B \leq 1$,

\[
t_x = \cos \left\{ \left[ \psi \left( 1 - \left( \frac{2\theta}{\pi} \right) \right) \left( 1 - \frac{Z_x}{Z_B} \right) \right]^{1/[1 - (2\theta/\pi)]} \right\}.
\]

(7.36)

The $\varepsilon_{\text{eff}}$ and $Z_0$ of the line are given by [5]

\[
\varepsilon_{\text{eff}} = \frac{C_t}{C_a + C_{\text{CV}}} \quad \text{(with $\varepsilon_r = 1$)}
\]

(7.37)

\[
= 1 + q(\varepsilon_r - 1),
\]

(7.38)
where the filling factor $q$ is [5]

$$
q = \frac{K(k_2)}{K'(k_2)} \frac{K(k_1)}{K'(k_1) + K'(k_2)}
$$

(7.39)

and

$$
Z_0 = \frac{1}{c'[C_a + C_{CV} (\text{with } \varepsilon_r = 1)]\sqrt{\varepsilon_{\text{eff}}}}
$$

(7.40)

and where $c'$ is the velocity of light in free space. After substituting for $C_a$ and $C_{CV}$ and simplifying [5],

$$
Z_0 = \frac{120\pi}{\sqrt{\varepsilon_{\text{eff}}}} \frac{1}{K(k_1) + K'(k_2)}.
$$

(7.41)

The computed $\varepsilon_{\text{eff}}$ and $Z_0$ [5] are presented in Figure 7.4. The analysis and computed characteristics of coupled coplanar waveguides with V-shaped microshields can be found in [6] and [7].

**FIGURE 7.4** Computed characteristic impedance and effective dielectric constant of a V-shaped microshield line, $W_1 = W_2$, $\theta = 30^\circ$, $\varepsilon_r = 2.55$, $L = S + W_1 + W_2$. (From Reference [5], © IEEE 1995.)
7.2.3 Elliptic Shaped Microshield Line

An elliptic shaped microshield line is shown in Figure 7.5. The capacitance $C_a$ of the upper half-plane for a structure with finite-size ground planes and in the absence of a top metal cover is given by Eq. (7.3). When a top metal cover is present and the ground planes are infinite, $C_a$ is given by Eq. (7.6). The capacitance of the lower half-plane consisting of the elliptic shaped cavity filled with a dielectric of relative permittivity $\varepsilon_r$ is [8]

$$C_{CE} = \pi \varepsilon_0 \varepsilon_r \left[ \ln \frac{b + h_2}{a} + \ln(1 - B') \right]^{-1}, \quad (7.42)$$

where

$$B' = \left( \frac{\sqrt{b^2 - h_2^2} - a}{2h_2a} \right). \quad (7.43)$$

The total capacitance $C_t$ per unit length is

$$C_t = C_a + C_{CE}. \quad (7.44)$$

The $\varepsilon_{eff}$ and $Z_0$ of the line are given by Eqs. (7.21) and (7.22) with $C_{CR}$ replaced by $C_{CE}$. An example of the computed $Z_0$ [8] as a function of the slot width for a particular geometry is shown in Figure 7.6.

7.2.4 Circular Shaped Microshield Line

A microshield line with a circular shaped cavity is shown in Figure 7.7. In a manner analogous to the elliptic shaped microshield line the capacitance $C_a$ is determined from Eq. (7.3) or Eq. (7.6). By letting $b = h_2$ in Eq. (7.42), the

FIGURE 7.5 Elliptic-shaped microshield line.
FIGURE 7.6 Computed $Z_0$ as a function of the slot width, $\varepsilon_r = 2.55$, $h_1 = 3.0 \text{ mm}$, $h_2 = 400 \mu\text{m}$, $b = 692.82 \mu\text{m}$. (From Reference [8], © IEEE 1994.)

The capacitance $C_{cc}$ of the lower half-plane is determined and is given by [8]

$$C_{cc} = \frac{\pi \varepsilon_0 \varepsilon_r}{\ln(2b/a)}. \quad (7.45)$$

The total capacitance $C_t$ per unit length is

$$C_t = C_a + C_{cc}. \quad (7.46)$$

The $\varepsilon_{eff}$ and $Z_0$ of the line are given by Eqs. (7.21) and (7.22) with $C_{cr}$ replaced

FIGURE 7.7 Circular shaped microshield line.
FIGURE 7.8 Computed $Z_0$ as a function of the slot width, $\varepsilon_r = 2.55$, $h_1 = 3.0\,\text{mm}$, $h_2 = 400\,\mu\text{m}$, $b = 400\,\mu\text{m}$. (From Reference [8], © IEEE 1994.)

by $C_{cc}$. An example of the computed $Z_0$ [8] as a function of the slot width for a particular geometry is shown in Figure 7.8.

7.3 EDGE COUPLED COPLANAR WAVEGUIDE WITHOUT A LOWER GROUND PLANE

When two transmission lines are placed in close proximity, there is a strong interaction between their fields and power is coupled from one line to the other. In general, the amount of coupling is dependent on the distance of separation between the lines and the interaction length. An edge coupled coplanar waveguide with two parallel coupled strip conductors symmetrically located between two ground planes is shown in Figure 7.9. This structure can support two modes of propagation, the even mode and the odd mode. These modes are illustrated in Figure 7.10(a) and (b). In general, any arbitrary excitation of the coupled lines in Figure 7.9 can be considered as a superposition of two appropriate amplitudes of even mode and odd mode. In the succeeding sections expressions for the effective dielectric constant as well as the characteristic impedance for the even mode and the odd mode obtained using the quasi-static conformal mapping technique will be presented.

7.3.1 Even Mode

For the even excitation a magnetic wall is placed along the plane of symmetry in Figure 7.10(a). It then suffices to restrict the analysis to the right half of the
FIGURE 7.9  Edge coupled coplanar waveguides.

FIGURE 7.10  Excitation of coupled coplanar waveguides: (a) Even mode; (b) odd mode.
structure. Through a sequence of conformal mapping steps [9], the right half of the structure is mapped into an ideal parallel plane structure for which the capacitance per unit length is easily obtained. The mapping functions and the transformed configurations are presented in Figure 7.11(a) to (g). In this figure, the mapping function

\[ t = \text{sn}(\zeta, k) \]  

(7.47)
is an elliptic sine function of a complex variable $\zeta$ to modulus $k$. The following elliptic sine function identities are also helpful in the transformation process:

\[
\begin{align*}
\text{sn}(0, k) &= 0 \\
\text{sn}(K(k), k) &= 1, \\
\text{sn}(K(k) + jK'(k), k) &= \frac{1}{k} \\
\text{sn}(-K(k) + jK'(k), k) &= -\frac{1}{k} \\
\text{sn}(jK'(k), k) &= \pm \infty,
\end{align*}
\]

where $K(k)$ and $K'(k)$ are the complete elliptic integrals of the first kind and $k'$ is the complementary modulus. These integrals and modulus are related as follows:

\[
\begin{align*}
K'(k) &= K(k'), \\
k' &= \sqrt{1 - k^2}.
\end{align*}
\]

The total even-mode capacitance $C_{t,e}$ per unit length is the sum of the partial capacitances $C_{a,e}$ and $C_{d,e}$, as explained in Section 2.2.1. That is,

\[
C_{t,e} = C_{a,e} + C_{d,e},
\]

where $C_{a,e}$ is the partial capacitance in the absence of the dielectric layer and $C_{d,e}$ is the partial capacitance assuming that the electric field exists only in the dielectric layer of thickness $h$ and relative dielectric constant $\varepsilon_r - 1$. The partial capacitance $C_{a,e}$ is given by \[9\]

\[
C_{a,e} = 2\varepsilon_0 \frac{K(\delta k_1)}{K'(\delta k_1)},
\]

where

\[
\begin{align*}
\delta &= \left\{ \frac{(1 - r^2)}{(1 - k_1^2 r^2)} \right\}^{1/2}, \\
r &= \frac{d}{d + 2S}, \\
k_1 &= \frac{d + 2S}{d + 2S + 2W},
\end{align*}
\]
and $K(\delta k)$ and $K'(\delta k)$ are the complete elliptic integrals of the first kind with modulus $\delta k$. The partial capacitance $C_{d,e}$ is given by [9]

$$C_{d,e} = \varepsilon_0 (\varepsilon_r - 1) \frac{K(\psi k_2)}{K'(\psi k_2)}$$

(7.59)

where

$$\psi = \begin{cases} \left( \frac{(1 - r_1^2)}{(1 - k_2^2 r_1^2)} \right)^{1/2}, \\ \frac{\sinh(\pi d/4h)}{\sinh\{((\pi/2h)[(d/2) + S])\}} \end{cases}$$

(7.60)

$$r_1 = \frac{\sinh\{((\pi/2h)[(d/2) + S])\}}{\sinh\{((\pi/2h)[(d/2) + S + W])\}}$$

(7.61)

$$k_2 = \frac{\sinh\{((\pi/2h)[(d/2) + S])\}}{\sinh\{((\pi/2h)[(d/2) + S + W])\}}$$

(7.62)

and $K(\psi k_2)$ and $K'(\psi k_2)$ are the complete elliptic integrals of the first kind with modulus $\psi k_2$. The even-mode effective dielectric constant $\varepsilon_{eff,e}$ based on the definition in Section 2.2.1 is

$$\varepsilon_{eff,e} = \frac{C_{t,e}}{C_{a,e}}$$

(7.63)

$$= 1 + \frac{1}{2} \left( \varepsilon_r - 1 \right) \frac{K(\psi k_2)}{K'(\psi k_2)} \frac{K'(\delta k)}{K(\delta k)}$$

(7.64)

The even-mode phase velocity $v_{ph,e}$ and characteristic impedance $Z_{0,e}$ based on the definition in Section 2.2.1 are

$$v_{ph,e} = c'(\varepsilon_{eff,e})^{-1/2}$$

(7.65)

$$Z_{0,e} = \frac{1}{c' \sqrt{\varepsilon_{eff,e}}}$$

(7.66)

$$= \frac{60\pi}{\sqrt{\varepsilon_{eff,e}}} \frac{K'(\delta k)}{K(\delta k)}$$

(7.67)

where $c'$ is the velocity of light in free space.

### 7.3.2 Odd Mode

For the odd excitement an electric wall is placed along the plane of symmetry in Figure 7.10(b). It then suffices to restrict the analysis to the right half of the structure. Through a sequence of conformal mapping steps [9], the right half
FIGURE 7.12 Conformal mapping transformation for the calculation of capacitance for odd mode. The mapping functions are (a) $z$-plane; (b) $U = \sinh^2(\pi z/2h)$; (c) $U_1$-plane, $U_1 = \log(1 + U)$; (d) $U_2$-plane, $U_2 = U_1 - (U_{1C} + U_{1B})/2$ and $\zeta = (U_{1C} - U_{1B})/2$; (e) $U_3$-plane, $U_3 = \sinh(U_2/2)$; (f) $t = f(U_3)$; (g) $t_1$-plane, $t = \text{sn}(t_1/k_3)$. (From Reference [9], © Ann. Telecommun. 1984.)

of the structure is mapped into an ideal parallel-plate structure for which the capacitance per unit length is easily obtained as in the even-mode case. The mapping functions and the transformed configurations are presented in Figure 7.12(a) to (g).

The total odd-mode capacitance $C_{t,o}$ per unit length is the sum of the partial capacitances $C_{a,o}$ and $C_{d,o}$. That is,

$$C_{t,o} = C_{a,o} + C_{d,o},$$  \hspace{1cm} (7.68)
where \( C_{a,o} \) is the partial capacitance in the absence of the dielectric layer and \( C_{d,o} \) is the partial capacitance, assuming that the electric field exists only in the dielectric layer of thickness \( h \) and relative dielectric constant \( \varepsilon_r - 1 \). The partial capacitance \( C_{a,o} \) is given by [9]

\[
C_{a,o} = 2\varepsilon_0 \frac{K(\delta)}{K'(\delta)}, \tag{7.69}
\]

where \( \delta \) is given by Eq. (7.56) and \( K(\delta) \) and \( K'(\delta) \) are the complete elliptic integrals of the first kind with modulus \( \delta \). The capacitance \( C_{d,o} \) is given by [9]

\[
C_{d,o} = 2\varepsilon_0 (\varepsilon_r - 1) \frac{K(k_3)}{K'(k_3)}, \tag{7.70}
\]

where

\[
k_3 = \frac{C_{11}(1 + \kappa C_{12})}{(C_{12} + \kappa C_{11}^2)}, \tag{7.71}
\]

\[
C_{11} = \frac{1}{2} \left[ \frac{(1 + C_{13})^{1/4}}{(1 + C_{14})} - \frac{(1 + C_{14})^{1/4}}{(1 + C_{13})} \right], \tag{7.72}
\]

\[
C_{13} = \sinh^2 \left[ \frac{\pi}{2h} \left( \frac{d}{2} + S \right) \right], \tag{7.73}
\]

\[
C_{14} = \sinh^2 \left( \frac{\pi d}{4h} \right), \tag{7.74}
\]

\[
C_{12} = \frac{1}{2} \left[ \frac{(1 + C_{15})^{1/2}}{[(1 + C_{13})(1 + C_{14})]^{1/4}} - \frac{(1 + C_{13})(1 + C_{14})^{1/4}}{(1 + C_{15})^{1/2}} \right], \tag{7.75}
\]

\[
C_{15} = \sinh^2 \left[ \frac{\pi}{2h} \left( \frac{d}{2} + S + W \right) \right], \tag{7.76}
\]

\[
\kappa = \frac{1}{(C_{12} - \chi)} \left[ -1 - \frac{C_{12}\chi}{C_{11}^2} - \left\{ \left( \frac{C_{12}^2}{C_{11}^2} - 1 \right) \left( \frac{\chi^2}{C_{11}^2} - 1 \right) \right\}^{1/2} \right], \tag{7.77}
\]

\[
\chi = -\frac{1}{2} \left[ \{(1 + C_{13})(1 + C_{14})\}^{1/4} - \{(1 + C_{13})(1 + C_{14})\}^{-1/4} \right]. \tag{7.78}
\]

The odd-mode effective dielectric constant \( \varepsilon_{\text{eff},o} \) is

\[
\varepsilon_{\text{eff},o} = \frac{C_{1,o}}{C_{a,o}} \tag{7.79}
\]

\[
= 1 + (\varepsilon_r - 1) \frac{K(k_3)}{K'(k_3)} \frac{K'(\delta)}{K(\delta)}. \tag{7.80}
\]
The odd-mode phase velocity \( v_{\text{ph},o} \) and characteristic impedance \( Z_{0,o} \) are

\[
v_{\text{ph},o} = c' \left( \varepsilon_{\text{eff},o} \right)^{-1/2},
\]

\[
Z_{0,o} = \frac{1}{c' C_{a,o} \sqrt{\varepsilon_{\text{eff},o}}}
\]

\[
= \frac{60\pi}{\sqrt{\varepsilon_{\text{eff},o}}} \frac{K'(\delta)}{K(\delta)},
\]

where \( c' \) is the velocity of light in free space.

### 7.3.3 Computed Even- and Odd-Mode Characteristic Impedance and Coupling Coefficient

The computed even- and odd-mode characteristic impedances for the edge-coupled CPWs [9] are presented in Figure 7.13. In this figure, for a given
substrate and for a fixed $W$ and $d + 2S$ as $d$ increases, $S$ proportionately decreases. The decrease in $S$ reduces both the even- and odd-mode capacitances and effective dielectric constants of the structure. The reduction in these parameters is small for the even mode, since the two strip conductors are isolated, as shown in Figure 7.10. Therefore $Z_{0,e}$ marginally increases as $d/(d + 2S)$ increases in Figure 7.13. In the case of the odd mode, the reduction in these parameters is large because the two strip conductors are tightly coupled as shown in Figure 7.10. Therefore $Z_{0,o}$ increases as $d/(d + 2S)$ increases in Figure 7.13.

Further, for a fixed $d$ and $d + 2S$, as $W$ increases, the ratio

$$(d + 2S)/(d + 2S + 2W)$$

decreases. The increase in $W$ reduces both the even- and odd-mode capacitances and effective dielectric constants of the structure. The reduction in these parameters is large for the even mode, since the fields are concentrated across the slots of width $W$, as shown in Figure 7.10(a). Therefore $Z_{0,e}$ increases significantly as $(d + 2S)/(d + 2S + 2W)$ decreases. In the case of a odd mode, the reduction in the above parameters is small because the fields are concentrated mainly across the separation $d$ as shown in Figure 7.10(b). Therefore $Z_{0,o}$ increases by a very small amount as $(d + 2S)/(d + 2S + 2W)$ decreases.

The voltage coupling coefficient $K$ is defined as [9]

$$K = \frac{Z_{0,e} - Z_{0,o}}{Z_{0,e} + Z_{0,o}}. \quad (7.84)$$

The computed $K$ [9] is shown in Figure 7.14. In this figure $[(d/2) + S]/h = 0$ corresponds to the case of a substrate with infinite thickness. Further, for small $[(d/2) + S]/h$ ratios such as 0.01 and 0.1, the curves are indistinguishable. In general, for a given substrate and for a fixed $W$ and $d + 2S$, the coupling decreases as $d$ increases.

7.4 CONDUCTOR-BACKED EDGE COUPLED COPLANAR WAVEGUIDE

In this section expressions for computing the even- and odd-mode effective dielectric constant and characteristic impedance of a conductance-backed edge coupled coplanar waveguide obtained using the quasi-static conformal mapping technique [10] will be presented. The structure is shown in Figure 7.15. As in Section 7.3, a magnetic wall and an electric wall is placed along the plane of symmetry for the even and odd mode of excitation, respectively, and one-half of the structure is isolated. Through a sequence of conformal mapping steps, the total capacitance per unit length is obtained. From the capacitance the effective dielectric constant and characteristic impedance are obtained. Expressions for these quantities are given in the following sections.
FIGURE 7.14 Computed coupling coefficient as a function of $d/(d + 2S)$ with $(d + 2S)/(d + 2S + 2W) = 0.342$ and $\varepsilon_r = 9.9$. (From Reference [9], © Ann. Telecommun. 1984.)

FIGURE 7.15 Conductor-backed edge coupled coplanar waveguides.
7.4.1 **Even Mode**

The even mode effective dielectric constant $\varepsilon_{\text{eff}, e}$ is given by \[10\]

$$
\varepsilon_{\text{eff}, e} = \frac{2 \varepsilon_r}{K'(k_e)} + \frac{K(\delta k_1)}{K'(\delta k_1)},
$$

and the characteristic impedance $Z_{0,e}$ is given by \[10\]

$$
Z_{0,e} = \frac{120\pi}{\sqrt{\varepsilon_{\text{eff}, e}} \left[ 2 \frac{K(k_e)}{K'(k_e)} + \frac{K(\delta k_1)}{K'(\delta k_1)} \right]},
$$

where $\delta$ and $k_1$ are given by Eqs. (7.56) and (7.58), respectively. Further $K(k_e)$ and $K'(k_e)$ are the complete elliptic integrals of the first kind with modulus $k_e$. The modulus $k_e$ is given by

$$
k_e = \phi_1 - \frac{(\phi_1^2 - \phi_2^2)^{1/2} + (\phi_1^2 - \phi_3^2)^{1/2}}{\phi_3(\phi_1^2 - \phi_2^2)^{1/2} + \phi_2(\phi_1^2 - \phi_3^2)^{1/2}},
$$

where

$$
\phi_1 = \frac{1}{2} \cosh^2 \left[ \frac{\pi}{2h} \left( \frac{d}{2} + S + W \right) \right],
$$

$$
\phi_2 = \sinh^2 \left[ \frac{\pi}{2h} \left( \frac{d}{2} + S \right) \right] - \phi_1 + 1,
$$

$$
\phi_3 = \sinh^2 \left( \frac{\pi d}{4h} \right) - \phi_1 + 1.
$$

7.4.2 **Odd Mode**

The odd mode effective dielectric constant $\varepsilon_{\text{eff}, o}$ is given by \[10\]

$$
\varepsilon_{\text{eff}, o} = \frac{2\varepsilon_r}{K'(k_o)} + \frac{K(\delta)}{K'(\delta)},
$$

$$
\frac{2 \varepsilon_r}{K'(k_o)} + \frac{K(\delta)}{K'(\delta)}],
$$

where $k_o$ and $\delta$ are given by Eqs. (7.56) and (7.58), respectively. Further $K(k_o)$ and $K'(k_o)$ are the complete elliptic integrals of the first kind with modulus $k_o$.
and the characteristic impedance \( Z_{0,o} \) is given by [10]

\[
Z_{0,o} = \frac{120\pi}{\sqrt{\varepsilon_{\text{eff},o}} \left[ \frac{2}{K(k_o)} + \frac{K(\delta)}{K'(k_o)} \right]}, \tag{7.92}
\]

where \( \delta \) is given by Eq. (7.56). Further \( K(k_o) \) and \( K'(k_o) \) are the complete elliptic integrals of the first kind with modulus \( k_o \). The modulus \( k_o \) is given by

\[
k_o = \phi_4 \frac{-(\phi_4^2 - \phi_5^2)^{1/2} + (\phi_4^2 - \phi_6^2)^{1/2}}{\phi_6(\phi_4^2 - \phi_5^2)^{1/2} + \phi_5(\phi_4^2 - \phi_6^2)^{1/2}}, \tag{7.93}
\]

where

\[
\begin{align*}
\phi_4 &= \frac{1}{2} \sinh^2 \left[ \frac{\pi}{2h} \left( \frac{d}{2} + S + W \right) \right], \tag{7.94} \\
\phi_5 &= \sinh^2 \left[ \frac{\pi}{2h} \left( \frac{d}{2} + S \right) \right] - \phi_4, \tag{7.95} \\
\phi_6 &= \sinh^2 \left( \frac{\pi d}{4h} \right) - \phi_4. \tag{7.96}
\end{align*}
\]

The voltage coupling coefficient \( K \) is defined as in Eq. (7.84), and the computed values can be found in [10]. The compound even- and odd-mode \( \varepsilon_{\text{eff}} \) and \( Z_0 \) for a conductor-backed edge coupled coplanar waveguide placed inside a metal enclosure are given in [11]. These characteristics are obtained by solving the propagation parameters using the method of lines.

### 7.4.3 Even- and Odd-Mode Characteristics with Elevated Strip Conductors

A coplanar waveguide with an elevated center strip conductor is shown in Figure 2.20. In [12] the characteristics of a conductor-backed coplanar waveguide with two elevated and coupled strip conductors are presented. The two strip conductors are elevated by inserting a thin dielectric layer between the conducting strips and the substrate. For the purpose of analysis, the structure is placed inside a shielding metal enclosure and the propagation characteristics are obtained by numerically solving Laplace’s equations along a cross sectional plane.

### 7.5 BROADSIDE COUPLED COPLANAR WAVEGUIDE

This section presents the coupling characteristics between two coplanar waveguides that are stacked one on top of another. The two coplanar waveguides
are separated from each other by a thin dielectric sheet. A pair of ground planes that acts as a shield is placed symmetrically above and below the coupled coplanar waveguides, respectively, as shown in Figure 7.16. This structure is analyzed in a manner similar to the edge coupled coplanar waveguide by considering the even and odd modes of excitation. For each of these modes analytical expressions are presented to determine the effective dielectric constant and characteristic impedance based on quasi-static conformal mapping techniques. The assumption made to simplify the analysis is similar to those described in Section 2.2.1.

7.5.1 Even Mode

For the even excitation a magnetic wall is placed along the plane of symmetry in Figure 7.17(a) It then suffices to restrict the analysis of the upper half of the structure. The total even-mode capacitance per unit length $C_e$ is derived as explained in Section 2.2.1. This total capacitance is expressed as the sum of two capacitances $C_{e1}$ and $C_{e2}$, where $C_{e1}$ and $C_{e2}$ are the capacitances per unit length contributed by half the substrate region of height $h_1$ and the superstrate region of height $h_2$, respectively. That is, [13]

$$C_e = C_{e1} + C_{e2},$$

(7.97)
FIGURE 7.17 Excitation of broadside coupled coplanar waveguides: (a) Even mode; (b) odd mode.
where

\[ C_{e1} = 2\varepsilon_0 \varepsilon_{r1} \frac{K(k_{e1})}{K(k'_{e1})}, \quad (7.98) \]

\[ k_{e1} = \frac{\sinh(\pi S/4h_t)}{\sinh(\pi(S + 2W)/4h_t)}, \quad (7.99) \]

\[ k'_{e1} = \sqrt{1 - k^2_{e1}}, \quad (7.100) \]

\[ C_{e2} = 2\varepsilon_0 \varepsilon_{r2} \frac{K(k_{e2})}{K(k'_{e2})}, \quad (7.101) \]

\[ k_{e2} = \frac{\tanh(\pi S/4h_2)}{\tanh(\pi(S + 2W)/4h_2)}, \quad (7.102) \]

\[ k'_{e2} = \sqrt{1 - k^2_{e2}}, \quad (7.103) \]

and \(K(k_{ei})\) and \(K(k'_{ei})\), \((i = 1, 2)\) are the complete elliptic integral of the first kind and its complement. Substituting Eqs. (7.98) and (7.101) into Eq. (7.97), the total even-mode capacitance per unit length is

\[ C_e = 2\varepsilon_0 \left\{ \varepsilon_{r1} \frac{K(k_{e1})}{K(k'_{e1})} + \varepsilon_{r2} \frac{K(k_{e2})}{K(k'_{e2})} \right\}, \quad (7.104) \]

The even-mode effective dielectric constant \(\varepsilon_{eff,e}\) is defined as [13]

\[ \varepsilon_{eff,e} = \frac{C_e}{C_{e(\text{air})}}, \quad (7.105) \]

where \(C_{e(\text{air})}\) is the even-mode capacitance per unit length with the dielectric replaced by air, that is,

\[ C_{e(\text{air})} = 2\varepsilon_0 \left\{ \frac{K(k_{e1})}{K(k'_{e1})} + \frac{K(k_{e2})}{K(k'_{e2})} \right\}. \quad (7.106) \]

Substituting Eqs. (7.104) and (7.106) into Eq. (7.105), we have

\[ \varepsilon_{eff,e} = \varepsilon_{r2} + q_e (\varepsilon_{r1} + \varepsilon_{r2}), \quad (7.107) \]

where

\[ q_e = \frac{K(k_{e1})}{K(k'_{e1})} \frac{K(k_{e2})}{K(k'_{e2})} + \frac{K(k_{e1})}{K(k'_{e1})} \frac{K(k_{e2})}{K(k'_{e2})}, \quad (7.108) \]
The even-mode characteristic impedance $Z_{0,e}$ is defined as \[13\]
\[
Z_{0,e} = \frac{1}{c' \sqrt{\varepsilon_e C_{o(\text{air})}}},
\]
(7.109)
where $c'$ is the velocity of light in free space. Substituting Eqs. (7.104) and (7.106) into Eq. (7.109), we have
\[
Z_{0,e} = \frac{60\pi}{\sqrt{\varepsilon_{\text{eff},e}}}, \frac{1}{K(k'_{e1}) + K(k'_{e2})}. \quad (7.110)
\]

### 7.5.2 Odd Mode

For the odd excitation an electric wall is placed along the plane of symmetry in Figure 7.17(b). The analysis is then restricted to the upper half of the structure. The total odd-mode capacitance per unit length $C_0$ is derived as explained in Section 3.2.3. The total capacitance is expressed as the sum of two capacitances $C_{o1}$ and $C_{o2}$, where $C_{o1}$ and $C_{o2}$ are the capacitances per unit length contributed by half the substrate region of height $h_1$ and the superstrate region of height $h_2$, respectively. That is \[13\],
\[
C_0 = C_{o1} + C_{o2}, \quad (7.111)
\]
where
\[
C_{o1} = 2\varepsilon_0\varepsilon_{ri} \frac{K(k_{oi})}{K(k'_{oi})} \quad (i = 1, 2), \quad (7.112)
\]
and
\[
k_{oi} = \frac{\text{tanh}(\pi S/4h_i)}{\text{tanh}(\pi(S + 2W)/4h_i)} \quad (i = 1, 2), \quad (7.113)
\]
and $K(k_{oi})$ and $K(k'_{oi})$, $i = 1, 2$, are the complete elliptic integral of the first kind and its complement. Substituting Eq. (7.112) into Eq. (7.111) yields the total odd-mode capacitance per unit length
\[
C_0 = 2\varepsilon_0 \left[ \varepsilon_{r1} \frac{K(k_{01})}{K(k'_{01})} + \varepsilon_{r2} \frac{K(k_{02})}{K(k'_{02})} \right]. \quad (7.114)
\]
The odd-mode effective dielectric constant $\varepsilon_{\text{eff},0}$ is defined as \[13\]
\[
\varepsilon_{\text{eff},0} = \frac{C_0}{C_{o(\text{air})}}, \quad (7.115)
\]
where $C_{o(air)}$ is the odd-mode capacitance per unit length with the dielectric replaced by air, that is,

$$C_{o(air)} = 2\varepsilon_0 \left[ \frac{K(k_{o1})}{K(k_{o1}')} + \frac{K(k_{o2})}{K(k_{o2}')} \right]. \quad (7.116)$$

Substituting Eqs. (7.114) and (7.116) into Eq. (7.115) obtains

$$\varepsilon_{eff,o} = \varepsilon_{r2} + q_o(\varepsilon_{r1} - \varepsilon_{r2}), \quad (7.117)$$

where

$$q_o = \frac{K(k_{o1})}{K(k_{o1}')} \cdot \frac{K(k_{o1})}{K(k_{o1}) + K(k_{o2})}, \quad (7.118)$$

The odd-mode characteristic impedance $Z_{0,o}$ is defined as [13]

$$Z_{0,o} = \frac{1}{\varepsilon' \sqrt{\varepsilon C_{o(air)}}}, \quad (7.119)$$

where $\varepsilon'$ is the velocity of light in free space. Substituting Eqs. (7.114) and (7.116) into Eq. (7.119) obtains

$$Z_{0,o} = \frac{60\pi}{\sqrt{\varepsilon_{eff,o}}} \cdot \frac{1}{\left[ \frac{K(k_{o1})}{K(k_{o1}')} + \frac{K(k_{o2})}{K(k_{o2}')} \right]} \cdot (7.120)$$

### 7.5.3 Computed Even- and Odd-Mode Effective Dielectric Constant, Characteristic Impedance, Coupling Coefficient, and Mode Velocity Ratio

The computed even- and odd-mode effective dielectric constant [13] for the broadside coupled coplanar waveguide as a function of the strip conductor width is shown in Figure 7.18(a). For a fixed substrate thickness and slot width, the $\varepsilon_{eff,o}$ increases while $\varepsilon_{eff,e}$ decreases as the strip conductor width $S$ increases. The computed even- and odd-mode characteristic impedance [13] as a function of the strip conductor width $S$ is shown in Figure 7.18(b). For a fixed substrate thickness and slot width, the $Z_{0,e}$ and $Z_{0,o}$ decreases as $S$ increases. The broadside coupled coplanar waveguides have also been analyzed using the spectral domain method [14]. The numerical results show that the effective dielectric constants are almost insensitive to change in frequency, thus confirming that the quasi-static results given above are adequate for circuit design [14].
FIGURE 7.18 Computed even- and odd-mode (a) effective dielectric constant and (b) characteristic impedance, $\varepsilon_{r_1} = 12.9$, $\varepsilon_{r_2} = 1.0$, $W = 20 \mu m$, $h_2 = 1 \text{ mm}$. (From Reference [13], © IEEE 1989.)
FIGURE 7.19  Computed voltage coupling coefficient as a function of the strip conductor width, \( \varepsilon_{r1} = 12.9, \varepsilon_{r2} = 1.0, 2h_1 = 50 \mu m, h_2 = 5.0 \text{ mm} \). (From Reference [13], © IEEE 1989.)

The voltage coupling coefficient \( K \) is defined as [13]

\[
K = \frac{Z_{0,e} - Z_{0,o}}{Z_{0,e} + Z_{0,o}}.
\]  
(7.121)

The computed voltage coupling coefficients [13] as a function of the strip conductor width \( S \) is shown in Figure 7.19. For a fixed substrate thickness and slot width, the coupling increases as \( S \) increases.

The even- and odd-mode velocity ratio is defined as [13]

\[
\frac{v_e}{v_o} = \sqrt{\frac{\varepsilon_{eff,o}}{\varepsilon_{eff,e}}}
\]  
(7.122)

The compared velocity ratio [13] as a function of the strip conductor width is shown in Figure 7.20. For a fixed substrate thickness and slot width, the velocity ratio increases as \( S \) increases. From Figures 7.19 and 7.20 it is observed that as \( S \) increases both \( K \) as well as \( v_e/v_o \) increases. The computed characteristics for open broadside coupled coplanar waveguides with a dielectric overlay can be found in [15].
FIGURE 7.20 Computed even- and odd-mode velocity ratio, $\varepsilon_{r1} = 12.9$, $\varepsilon_{r2} = 1.0$, $2h_1 = 50 \mu m$, $h_2 = 5.0 \text{ mm}$. (From Reference [13], © IEEE 1989.)

REFERENCES


CHAPTER 8

Attenuation Characteristics of Conventional, Micromachined, and Superconducting Coplanar Waveguides

8.1 INTRODUCTION

In this chapter the attenuation characteristics of conventional, micromachined, and superconducting coplanar waveguides are presented. Section 8.2 presents closed form equations based on the conformal mapping technique, the mode-matching method, and the modified matched asymptotic expansion technique in order to compute the attenuation constant of a coplanar waveguide. In Section 8.3 the influence of the coplanar waveguide geometry on the attenuation characteristics is discussed. Recently silicon (Si) and silicon-germanium (SiGe) based integrated circuits have emerged for RF/microwave applications. Hence Section 8.4 discusses the attenuation characteristics of coplanar waveguides on CMOS grade low-resistivity as well as high-resistivity silicon wafers. Further, microelectromechanical systems (MEMS) based switches and actuators are being explored for potential phased-array antenna applications. Therefore the attenuation characteristics of coplanar waveguides on micromachined silicon wafers are presented in Section 8.5. Filter circuits based on superconducting coplanar waveguides have demonstrated potential for application in wireless and satellite communications systems. Hence the attenuation characteristics of high-temperature superconducting coplanar waveguides are discussed in Section 8.6
8.2 CLOSED FORM EQUATIONS FOR CONVENTIONAL CPW ATTENUATION CONSTANT

Coplanar waveguide (CPW) circuits fabricated using standard photolithography process on copper-clad soft plastic-like sheets have a conductor thickness $t$ several times the skin depth $\delta$. Typically this thickness $t$ is on the order of 17 $\mu$m, which is the result of rolling a half ounce of copper over an area of one square feet [1]. Hence, for deriving an expression for the CPW attenuation constant, the conductors are considered to be electrically very thick and with conductivity the same as that of bulk copper. For the case of thick conductors a simple closed form expression for CPW attenuation constant is derived in [2] using conformal mapping technique.

In monolithic microwave integrated circuits the conductor patterns are formed by evaporating or by sputtering precious metal such as gold on the surface of a dielectric substrate. These deposition processes yield conducting films with thickness on the order of a micron. The thickness is then built up to about 2.5 $\mu$m by an electroplating process. The conductor thickness $t$ in this case is said to be thin and in some cases may be less than or equal to the skin depth $\delta$ at the operating frequency. When $t \leq \delta$, the fields penetrate into the conductors and the conductivity inside the conductors can be accounted for by introducing a complex dielectric constant. The CPW attenuation constant for this case is determined using accurate full wave analysis, such as the mode-matching method [3]. The disadvantage of the mode-matching method is that it requires significant amount of computer resources to carry out the computations. However, closed form expressions that approximate the results of the mode-matching method are also available [4].

Besides thickness the cross section of the CPW conductors in MMICs may deviate from the ideal rectangular shape. The shape is strongly dependent on the fabrication process involved. In most cases the shape would be a trapezoid with 60° or 70° angles. The CPW attenuation constant for this case is derived by the modified matched asymptotic expansion technique [5], [6]. In this technique an approximate current density in first assumed on the CPW conductors and an equation for the CPW attenuation constant is derived. This equation involves a contour integral. Instead of evaluating this integral out to the edge of the conductors where the fields are singular, the limits of the integral are taken at some distance just before the edge. This short length before the edge is defined as the stopping distance $\Delta$ [6]. Once $\Delta$ is determined for a given edge shape as a function of $t/\delta$, a closed form expression is derived for the CPW conductor loss in [6]. In the subsections that follow closed form equations based on the foregoing numerical methods as well as measurement-based design equations are presented, and the corresponding computed attenuation constant is compared with measured data.
8.2.1 Conformal Mapping Method

Consider the CPW structure shown in Figure 8.1 with g tending to infinity. In the conformal mapping method [2] the total CPW attenuation is expressed as the sum of the attenuation due to dielectric losses in the substrate and the attenuation due to the conductor losses in the strip and the ground planes. The attenuation constant due to the dielectric loss is expressed as

\[ x_d = \frac{\pi}{\lambda_0} \frac{\varepsilon_r}{\sqrt{\varepsilon_{\text{eff}}}} q \tan \delta_e \text{ Nepers/meter,} \tag{8.1} \]

where \( \lambda_0 \) is the free space wavelength in meters, \( \varepsilon_r \) is the relative permittivity of the substrate, \( \tan \delta_e \) is the dielectric loss tangent, \( \varepsilon_{\text{eff}} \) is the effective dielectric constant defined in Eq. (2.37) and is expressed as

\[ \varepsilon_{\text{eff}} = 1 + q(\varepsilon_r - 1), \tag{8.2} \]

and \( q \) is the filling factor and is given by

\[ q = \frac{1}{2} \frac{K(k_1)}{K(k'_0)} \frac{K(k'_1)}{K(k_0)}. \tag{8.3} \]

The terms \( K(k_1) \) and \( K(k_0) \) are the complete elliptic integrals of the first kind with moduli \( k_1 \) and \( k_0 \) which are given by Eqs. (2.3) and (2.35), respectively,

\[ k_1 = \frac{\sinh(\pi S/4h_1)}{\sinh[\pi(S + 2W)/4h_1]}, \tag{8.4} \]

\[ k_0 = \frac{S}{S + 2W}. \tag{8.5} \]
The terms \( k_1' \) and \( k_0' \) are the complementary moduli given by

\[
k_1' = \sqrt{1 - k_1^2}, \quad (8.6)
\]

\[
k_0' = \sqrt{1 - k_0^2}. \quad (8.7)
\]

An expression for the attenuation constant \( \alpha_c \) due to conductor loss in the center strip conductor and the ground planes of the CPW is given below. The assumption made in deriving this expression is that the thickness \( t \) of the CPW conductors is far greater than the skin depth \( \delta \) in the metal. Typically \( t \) would be greater than 5\( \delta \). The attenuation constant \( \alpha_c \) is given by [2]

\[
\alpha_c = \frac{R_c + R_g}{2Z_0} \text{ Nepers/meter} \quad (8.8)
\]

where \( R_c \) is the series resistance in ohms per unit length of the center strip conductor and is given by

\[
R_c = \frac{R_s}{4S(1 - k_0^2)K_2(k_0)} \left[ \pi + \ln \left( \frac{4\pi S}{t} \right) - k_0 \ln \left( \frac{1 + k_0}{1 - k_0} \right) \right], \quad (8.9)
\]

\( R_g \) is the distributed series resistance in ohms per unit length of the ground planes and is given by

\[
R_g = \frac{k_0R_s}{4S(1 - k_0^2)K_2(k_0)} \left[ \pi + \ln \left( \frac{4\pi(S + 2W)}{t} \right) - \frac{1}{k_0} \ln \left( \frac{1 + k_0}{1 - k_0} \right) \right], \quad (8.10)
\]

and \( Z_0 \) is the coplanar waveguide characteristic impedance given by Eq. (2.38). The term \( R_s \) is the skin effect surface resistance given by

\[
R_s = \frac{1}{\delta \sigma} \text{ ohms}, \quad (8.11)
\]

where \( \sigma \) is the conductivity of the conductor in Siemens/meter, \( \delta \) is the skin depth given by

\[
\delta = \frac{2}{\sqrt{\omega \mu \sigma}} \text{ meters}, \quad (8.12)
\]

with

\[
\omega = 2\pi f \text{ as the angular frequency in radians,}
\]

\[
\mu = \mu_0 \mu_r \text{, as the permeability of the conductor,}
\]

\[
\mu_0 = 4\pi \times 10^{-7} \text{ Henry/meter.}
\]
The total attenuation $\alpha$ is

$$\alpha = (\alpha_c + \alpha_d) \text{ Nepers/meters.} \quad (8.13)$$

### 8.2.2 Mode-Matching Method and Quasi-TEM Model

Consider the CPW structure shown in Figure 8.1 with $g$ tending to infinity. In the mode-matching method [3] the fields in the substrate and in the air regions on top and bottom are initially represented as a sum of all the longitudinal-section modes $LSE_{xm}$ and $LSH_{xm}$ with unknown amplitudes. Next, the propagation constants $k_x$ and $k_z$ are obtained by a two-step procedure. In the first step, $k_{xm}$ in the plane of the metallization is determined for each $LSE_{xm}$ and $LSH_{xm}$ mode by satisfying the field continuity at the vertical boundaries and by solving the transverse resonance condition. In the second step, the field continuity at the horizontal planes is used and leads to a system of homogeneous equations. The eigenvalue of this system of equations is the complex propagation constant $k_z$ of the CPW. From the propagation constant the phase constant $\beta$ and the attenuation constant $\alpha$ can be obtained. Although the mode-matching method is very accurate, it is not suitable for computer-aided design (CAD) software because it requires considerable amount of computer resources. Hence closed form equations that approximate the mode-matching results are obtained in [4].

In deriving the closed form equations, the CPW is represented by a distributed equivalent circuit model consisting of a resistance $R$ and an inductance $L$ in series with a shunt capacitance $C$ and a conductance $G$. Such a model assumes a quasi-TEM mode of propagation on the CPW. This is a valid assumption and holds good even at millimeter-wave frequencies as discussed in Section 2.2.6 and shown in Table 2.3. The advantage of the model above is that it fits well into common network analysis software and takes into consideration both the finite thickness as well as the non-ideal conductivity of the CPW conductors. Since the closed form expressions are very lengthy, they are not reproduced here, but interested readers can refer to [4].

### 8.2.3 Matched Asymptotic Technique and Closed Form Expressions

This method takes into consideration both the finite thickness as well as the non-ideal conductivity of the CPW conductors. In addition the shape of the conductor cross section needs not be rectangular, but instead can be trapezoidal. Thus the sides of the conductor which are normally assumed to be vertical can now be considered to be inclined at an angle $\theta$ as shown in Figure 8.2. In this figure the average center strip width and the ground plane separation are indicated as $2a$ and $2b$, respectively.
FIGURE 8.2  Coplanar waveguide conductor geometry showing the stopping distance $\Delta$ and edge profile $\theta$.

The attenuation constant $\alpha_c$ due to conductor loss is given by [6]

$$\alpha_c = \frac{R_{sm}b^2}{16Z_0[K^2(k)(b^2 - a^2)]} \left\{ \frac{1}{a} \ln \left( \frac{2a(b-a)}{\Delta(b+a)} \right) + \frac{1}{b} \ln \left( \frac{2b(b-a)}{\Delta(b+a)} \right) \right\} \text{Nepers/meter,} \quad (8.14)$$

where

$$Z_0 = \frac{30\pi}{\sqrt{\varepsilon_{eff} K(k)}} \text{ohms,} \quad (8.15)$$

$$k = \frac{a}{b}, \quad (8.16)$$

$$k' = \sqrt{1 - k^2}, \quad (8.17)$$

$K(k) =$ complete elliptic integral of the first kind,

$$\varepsilon_{eff} = \varepsilon_r + \frac{1}{2}, \quad (8.19)$$

$\varepsilon_r =$ relative permittivity of the substrate,

$$R_{sm} = \omega \mu_c t \text{ Imaginary } \left( \frac{\cot(k_c t) + \csc(k_c t)}{k_c t} \right), \quad (8.21)$$

$$\omega = 2\pi f, \quad (8.22)$$

$$\mu_c = \mu_0 \mu_{rc} \quad (8.23a)$$

$$= \mu_0 (\mu_{rc} \approx 1 \text{ for copper or gold}), \quad (8.23b)$$

$$\varepsilon_c = \varepsilon'_c - j \frac{\sigma_c}{\omega}, \quad (8.24a)$$
The stopping distance $\Delta$ for a given conductor thickness $t$, skin depth $\delta$ and edge profile $\theta$, is given in Table 8.1.

In Figure 8.3, the computed attenuation constant $\alpha_c$ due to conductor loss [6] using Eq. (8.14) is compared with the experimentally measured values of Williams and Marks [7] over the frequency range of 0.2 to 20.0 GHz. The measured and the modeled results are in very good agreement at frequencies above 0.5 GHz. The reason for the discrepancy below 0.5 GHz is because Eq. (8.15) for the characteristics impedance $Z_0$ of a CPW is not valid. In deriving Eq. (8.15), the assumption made is that the conductors are perfectly conducting and infinitely thin. As a consequence the field penetration inside the conductors is negligibly small. This assumption is not valid when $t \leq \delta$ and the fields penetrate inside the conductors. The characteristic impedance $Z_c$ taking field penetration into account is given by [8]

$$Z_c = Z_0 \left( 1 + \frac{Q}{j k_0 \sqrt{\varepsilon_{eff} Z_0}} \right) \left( 1 + \frac{2}{\sqrt{1 + \frac{4Q}{j k_0 \sqrt{\varepsilon_{eff} Z_0}}}} \right) \text{ohms}, \quad (8.30)$$
TABLE 8.1 Computed \(t/\Delta\) as a Function of \(t/2\delta\) for edge Profile \(0=45^\circ\) and \(90^\circ\)

<table>
<thead>
<tr>
<th>(t/2\delta)</th>
<th>(90^\circ)</th>
<th>(45^\circ)</th>
<th>(t/2\delta)</th>
<th>(90^\circ)</th>
<th>(45^\circ)</th>
</tr>
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<td>266.73</td>
<td>306.15</td>
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<td>265.33</td>
</tr>
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<tr>
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<td>3.00</td>
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<td>3.55</td>
<td>170.73</td>
<td>317.89</td>
</tr>
<tr>
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</tr>
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</tr>
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<td>326.77</td>
<td>16.00</td>
<td>217.25</td>
<td>862.14</td>
</tr>
</tbody>
</table>

Source: From Reference [6], © IEEE 1995.

where

\[
Q = \left( \frac{Z_s + Z_m}{16K^2(k)(b^2 - a^2)} \right) \left\{ \frac{1}{a} \ln \left( \frac{2a (b - a)}{\Delta (b + a)} \right) + \frac{1}{b} \ln \left( \frac{2b (b - a)}{\Delta (b + a)} \right) \right\}, \quad (8.31)
\]

\[
Z_s = -j \sqrt{\frac{\mu_o}{\epsilon'_c - j \frac{\sigma_s}{\omega}}} \cos(k_c t) \quad (8.32a)
\]

\[
= -j \sqrt{\frac{\mu_o}{\epsilon'_0 - j \frac{\sigma_s}{\omega}}} \cot(k_c t) \quad (8.32b)
\]
FIGURE 8.3 Comparison of computed and measured attenuation constant due to conductor loss as a function of the frequency for a CPW with $t = 1.61 \mu m$, $a = 35.6 \mu m$, $b = 84.6 \mu m$, $\varepsilon_r = 12.9$, $g \to \infty$, and $\sigma_a = 3.602 \times 10^7$ S/meter (the circles are measured attenuation). (Reference [6], © IEEE 1995.)

As a caution, it should be mentioned that analogous to Eq. (8.15) for $Z_o$, Eq. (8.30) for $Z_e$ also has a low-frequency limit below which the equation is not valid. This frequency limit is typically on the order of few MHz [8].

The effect of conductor thickness $t$ on the computed attenuation constant $\alpha_a$ for a CPW [6] at a fixed frequency of 20 GHz is shown in Figure 8.4. As expected, the attenuation increases very rapidly once the conductor thickness $t$ becomes less than about two to three times the skin depth $\delta$. 

\[
\eta = \sqrt{\frac{\mu_0}{\varepsilon_0}}, \quad (8.33)
\]

\[
Z_m = -j \sqrt{\frac{\mu_0}{\varepsilon_r'}} \csc(k_c t), \quad (8.34a)
\]

\[
= -j \frac{\eta}{\sqrt{1 - j \frac{\sigma_a}{\omega \varepsilon_0}}} \cot(k_c t). \quad (8.34b)
\]
FIGURE 8.4 Computed attenuation constant due to conductor loss as a function of the conductor thickness $t$ for a CPW with $a = 35.6 \mu m$, $b = 84.6 \mu m$, $\varepsilon_r = 12.9$, $\sigma_c = 3.602 \times 10^7$ S/meter, $g \rightarrow \infty$, frequency = 20.0 GHz, and $\delta = 0.593 \mu m$. (Reference [6], © IEEE 1995.)

Figures 8.5 and 8.6 present the computed attenuation constant $\alpha_c$ for two CPWs [6] with $t$ equal to 3 and 1.61 $\mu m$, respectively. As a worst-case scenario the two CPWs are assumed to have an edge profile $\theta$ equal to 45°. These figures show that the attenuation constant $\alpha_c$ for $\theta$ equal to 45° is not significantly greater than the attenuation constant $\alpha_c$ for $\theta$ equal to 90° when $t$ is equal to 1.61 $\mu m$. However, when $t$ is equal to 3 $\mu m$, there is about 7 percent increase in the attenuation at 40 GHz. Therefore for CPWs with thick conductors the additional attenuation due to edge profile is significant.

The stopping distance $\Delta$ given in Table 8.1 is derived for an isolated strip edge. Hence, if the CPW center strip conductor becomes very narrow or if the slot width becomes very small, the stopping distance $\Delta$ may be in error. To discover the range of validity, the results of this method ($\alpha_c$) are compared in [6] with the data ($\alpha$) obtained using the rigorous spectral-domain/perturbation method [9]. This comparison is graphically illustrated in Figure 8.7. It is observed that when $t/a$ and $t/(b-a)$ approach 0.3 and 0.1, respectively, the error is in the range of 5 to 10 percent [6] between the two sets of results.

8.2.4 Measurement-Based Design Equations

In [10] the measured attenuation characteristics of CPWs fabricated on GaAs ($\varepsilon_r = 12.85$), InP($\varepsilon_r = 12.4$) and high-resistivity silicon ($\rho \geq 2500 \Omega\cdot cm$ and $\varepsilon_r = 11.9$) wafers are used to derive a closed form equation to predict the
FIGURE 8.5  Computed attenuation constant due to conductor loss as a function of frequency for a CPW with 90° and 45° edges and \( t = 3 \, \mu m, \ a = 5 \, \mu m, \ b = 25 \, \mu m, \ \varepsilon_r = 12.9, \ g \to \infty, \) and \( \sigma_c = 3.0 \times 10^7 \, S/meter. \) (Reference [6], © IEEE 1995.)

FIGURE 8.6  Computed attenuation constant due to conductor loss as a function of frequency for a CPW with 90° and 45° edges and \( t = 1.61 \, \mu m, \ a = 35.6 \, \mu m, \ b = 84.6 \, \mu m, \ \varepsilon_r = 12.9, \ g \to \infty, \) and \( \sigma_c = 3.602 \times 10^7 \, S/meter. \) (Reference [6], © IEEE 1995.)
FIGURE 8.7  Computed attenuation constant due to conductor loss as a function of center strip conductor width $S$ for a CPW with $t = 3.0 \mu m$, $b = 150.0 \mu m$, $\varepsilon_r = 12.8$, $g \to \infty$, and $\sigma_c = 5.882 \times 10^7$ S/meter. (Reference [6], © IEEE 1995.)

The equation for attenuation constant is as follows:

$$\alpha = pf^q \quad \text{dB/cm},$$

where

$$p = \sqrt{\frac{\varepsilon_r + 1}{2}} \left[ \frac{45.152}{(SW)^{0.41}e^{2.127i}} \right],$$

$$q = 0.183(t + 0.464) - 0.095k_t^{2.484}(t - 2.595),$$

$S =$ strip width in $\mu$m,                     (8.38a)

$W =$ slot width in $\mu$m,                     (8.38b)

$t =$ conductor thickness in $\mu$m,           (8.38c)

$f =$ frequency in GHz,                       (8.38d)

$$k_t = \frac{S + \Delta t}{S + 2W - \Delta t},$$

$$\Delta t = \frac{1.25t}{\pi} \left[ 1 + \ln \frac{4\pi S}{t} \right].$$
The ranges of validity of the equations above are

\[ 0.5 < t < 3 \mu m, \quad (8.41a) \]

\[ 0.2 < \frac{S}{S + 2W} < 0.7, \quad (8.41b) \]

\[ 10 < S < 80 \mu m, \quad (8.41c) \]

\[ 1 < f < 40 \text{GHz}. \quad (8.41d) \]

In the experimental CPWs the propagation parameters are made independent of the ground plane width \( g \) and the substrate height \( h \) by choosing \( g \) to be \( 4S \) and \( h \) greater than \( 3(S+2W) \). In [10] it is shown that the \( \alpha \) predicted by Eq. (8.35) is in good agreement with the measured \( \alpha \) in [11] for CPW lines on a GaAs wafer and on an InP wafer \( (t = 0.5 \mu m) \).

### 8.2.5 Accuracy of Closed Form Equations

In [10] an estimate of the accuracy of each of the four closed form equations described in Sections 8.2.1 through 8.2.4 is demonstrated by comparing them with a single set of measured data. The measurements in [10] are performed using a HP8510C automatic network analyzer and a microwave probe station. The HP8510C is calibrated using on-wafer coplanar waveguide (CPW) through-reflect-line (TRL) standards and four delay lines to cover the frequency range of 1 to 40 GHz. During calibration the HP8510C is computer controlled through the National Institute of Standards and Technology (NIST) software [12], and it acquires the scattering parameters \( (S\text{-parameters}) \) pertaining to each of the CPW standards and delay lines. The software de-embeds the CPW attenuation constant \( (\alpha_{\text{meas}}) \) from the measured \( S \)-parameters as explained in [13]. This experiment is repeated three times, and the average \( \bar{\alpha}_{\text{meas}} \) is calculated. This process is then extended to all 17 combinations of \( S \) and \( W \) included in the study. These combinations are representative of those encountered in typical MMIC design.

An estimate of the accuracy is obtained by calculating the normalized difference \( (\Delta \alpha) \) between the average measured attenuation constant \( (\bar{\alpha}_{\text{meas}}) \) and the calculated attenuation constant \( (\alpha_{\text{calc}}) \), that is,

\[ \Delta \alpha = \frac{\bar{\alpha}_{\text{meas}} - \alpha_{\text{calc}}}{\bar{\alpha}_{\text{meas}}}. \quad (8.42) \]
TABLE 8.2 Average Root-Mean-Square Error between Measured and Calculated Attenuation across the Frequency Band of 1–40 GHz for CPW Lines Fabricated on GaAs with Metal Thickness of 1.58 μm (σ = 4.1 × 10⁷ S/m Used to Calculate Attenuation)

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>10</td>
<td>4.5</td>
<td>0.177</td>
<td>0.248</td>
<td>0.154</td>
<td>0.018</td>
</tr>
<tr>
<td>20</td>
<td>6</td>
<td>0.124</td>
<td>0.177</td>
<td>0.088</td>
<td>0.018</td>
</tr>
<tr>
<td>30</td>
<td>8</td>
<td>0.111</td>
<td>0.150</td>
<td>0.076</td>
<td>0.034</td>
</tr>
<tr>
<td>40</td>
<td>10</td>
<td>0.080</td>
<td>0.111</td>
<td>0.046</td>
<td>0.028</td>
</tr>
<tr>
<td>50</td>
<td>11</td>
<td>0.074</td>
<td>0.093</td>
<td>0.042</td>
<td>0.031</td>
</tr>
<tr>
<td>10</td>
<td>9</td>
<td>0.085</td>
<td>0.143</td>
<td>0.087</td>
<td>0.022</td>
</tr>
<tr>
<td>20</td>
<td>16</td>
<td>0.083</td>
<td>0.062</td>
<td>0.040</td>
<td>0.037</td>
</tr>
<tr>
<td>30</td>
<td>22</td>
<td>0.111</td>
<td>0.035</td>
<td>0.070</td>
<td>0.055</td>
</tr>
<tr>
<td>40</td>
<td>28</td>
<td>0.141</td>
<td>0.057</td>
<td>0.106</td>
<td>0.069</td>
</tr>
<tr>
<td>50</td>
<td>35</td>
<td>0.119</td>
<td>0.050</td>
<td>0.082</td>
<td>0.031</td>
</tr>
<tr>
<td>60</td>
<td>40</td>
<td>0.184</td>
<td>0.105</td>
<td>0.165</td>
<td>0.070</td>
</tr>
<tr>
<td>70</td>
<td>46</td>
<td>0.215</td>
<td>0.143</td>
<td>0.209</td>
<td>0.082</td>
</tr>
<tr>
<td>80</td>
<td>51</td>
<td>0.224</td>
<td>0.153</td>
<td>0.222</td>
<td>0.069</td>
</tr>
<tr>
<td>10</td>
<td>20</td>
<td>0.088</td>
<td>0.076</td>
<td>0.054</td>
<td>0.043</td>
</tr>
<tr>
<td>20</td>
<td>35</td>
<td>0.123</td>
<td>0.044</td>
<td>0.068</td>
<td>0.045</td>
</tr>
<tr>
<td>30</td>
<td>50</td>
<td>0.163</td>
<td>0.081</td>
<td>0.123</td>
<td>0.058</td>
</tr>
<tr>
<td>40</td>
<td>65</td>
<td>0.216</td>
<td>0.142</td>
<td>0.200</td>
<td>0.082</td>
</tr>
<tr>
<td>average error</td>
<td>0.136</td>
<td>0.110</td>
<td>0.108</td>
<td>0.047</td>
<td></td>
</tr>
</tbody>
</table>


The $\Delta z$ is determined at 201 points across the frequency interval of 1 to 40 GHz and the average-root-mean-square error ($\Delta z_{\text{rms}}$) is calculated, that is,

$$
\Delta z_{\text{rms}} = \sqrt{\frac{(\Delta z_1)^2 + (\Delta z_2)^2 + \cdots + (\Delta z_{201})^2}{201}}.
$$

(8.43)

The $\Delta z_{\text{rms}}$ for all 17 combinations and the average error for each of the four closed form equations [10] are presented in Table 8.2.

According to [10], the attenuation constant predicted by Collin’s method [2] underestimates the valves at low frequencies. This is attributed to the thick metal assumption, that is, $t \gg d$. The average error for this method is on the order of 13.6 percent. On the other hand, Heinrich’s method [4] and Holloway’s and Kuester’s technique [5] do not assume the metal to be thick. Hence the difference between the measured and calculated attenuation constant is nearly independent of frequency. The average error for these two methods are on the order of 10.8 percent and 11.0 percent, respectively. The Ponchak et al.
equations [10] result in an average error on the order of 4.7 percent. Thus among the above four closed-form equations, the method described in [10] has the least average error.

8.3 INFLUENCE OF GEOMETRY ON COPLANAR WAVEGUIDE ATTENUATION

8.3.1 Attenuation Constant Independent of the Substrate Thickness and Dielectric Constant

In [14] the attenuation constant \( \alpha \) of two coplanar waveguides fabricated on a thin quartz substrate (165 µm) and on a thick semi-insulating GaAs wafer (525 µm) is measured. These coplanar waveguides have identical center strip conductor, slot, and ground plane width. The measurements show that the attenuation in dB/wavelength is about the same for both coplanar waveguides, even though the substrate thickness and dielectric constant are different. This suggests that \( \alpha \) is independent of substrate thickness and dielectric constant.

8.3.2 Attenuation Constant Dependent on the Aspect Ratio

In [9] the attenuation constant \( \alpha \) is computed as a function of the characteristic impedance \( Z_0 \) with the ground plane separation \( (S+2W) \) as a parameter. The results from [9] are shown in Figure 8.8. The figure shows that for a fixed

![Figure 8.8](image_url)
ground plane separation, the attenuation constant initially decreases and later increases as the characteristic impedance increases or the aspect ratio $S/(S+2W)$ decreases. It is interesting to note that minimum attenuation occurs for characteristic impedance close to $50\Omega$.

8.3.3 Attenuation Constant Varying with the Elevation of the Center Strip Conductor

The attenuation characteristics when the center strip conductor is elevated above the plane of the substrate are discussed in Section 2.7.

8.4 ATTENUATION CHARACTERISTICS OF COPLANAR WAVEGUIDE ON SILICON WAFER

8.4.1 High-Resistivity Silicon Wafer

Attenuation Constant as a Function of Wafer Resistivity

The measured attenuation constant $\alpha$ of coplanar waveguide on silicon wafer as a function of frequency with the silicon wafer resistivity as a parameter is reported in [15]. The resistivity of the wafers are in the range of 400 to 30,000 $\Omega$-cm and the conductors of the coplanar waveguide are separated from the silicon wafer by a thin layer of silicon dioxide of thickness $t_1$, for reasons explained later. In the slot regions the silicon dioxide is etched away as shown in Figure 8.9. The measured attenuation constant is summarized in Table 8.3, where it is observed that there is no significant improvement in the attenuation constant beyond 2500 $\Omega$-cm wafer resistivity. In [16] it is shown that the measured attenuation constant of a coplanar waveguide on a silicon wafer of resistivity 2500 $\Omega$-cm is about the same as that of a coplanar waveguide on a semi-insulating GaAs wafer. Since it has been proved that semi-insulating GaAs wafers are excellent materials for monolithic microwave integrated circuits (MMICs), these data

FIGURE 8.9 Coplanar waveguide on a silicon wafer with a thin interfacial layer of silicon dioxide.
indicate that silicon wafers with resistivity greater than 2500 Ω-cm are also viable substrates for MMIC applications.

Conductors in direct Contact with the Silicon Wafer  When the coplanar waveguide conductors are in direct contact with the high-resistivity silicon (HR-Si) wafer, the signal suffers the least attenuation [17]. However, a dc leakage current can flow between the CPW center strip conductor and the ground planes, since the HR-Si is not a perfect insulator [17]. The leakage current is not a concern in the case of passive devices such as couplers and filters. But leakage can be a serious problem when active devices are integrated. The measured attenuation constant $\alpha$ [16] for typical coplanar waveguide geometries used in MMIC design when the conductors are in direct contact with the silicon wafer are summarized in Table 8.4.

**TABLE 8.3** Measured Attenuation of CPW on High-Resistivity Silicon Wafers

<table>
<thead>
<tr>
<th>Resistivity Ω-cm</th>
<th>Attenuation (dB/cm)</th>
</tr>
</thead>
<tbody>
<tr>
<td>400–720</td>
<td>1.08</td>
</tr>
<tr>
<td>2500–3300</td>
<td>0.62</td>
</tr>
<tr>
<td>5000</td>
<td>0.58</td>
</tr>
<tr>
<td>5000–10,000</td>
<td>0.50</td>
</tr>
<tr>
<td>&gt; 30,000</td>
<td>0.45</td>
</tr>
</tbody>
</table>

Note: $S = 100 \mu m$, $W = 50 \mu m$, $t = 2.5 \mu m$ (gold), $t_1 = 1000 \AA$ (SiO$_2$), $Z_0 \approx 50 \Omega$.

**TABLE 8.4** Measured Attenuation of CPW on 2500 Ω-cm Silicon Wafer

<table>
<thead>
<tr>
<th>Frequency (GHz)</th>
<th>Attenuation (dB/cm)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>$S = 10 \mu m$, $W = 9 \mu m$</td>
</tr>
<tr>
<td>5</td>
<td>2.59</td>
</tr>
<tr>
<td>10</td>
<td>3.18</td>
</tr>
<tr>
<td>20</td>
<td>3.88</td>
</tr>
<tr>
<td>30</td>
<td>4.59</td>
</tr>
<tr>
<td>40</td>
<td>5.29</td>
</tr>
</tbody>
</table>

Note: $h = 410 \mu m$, $t = 0.02/1.45 \mu m$ (Ti/Au), $Z_0 = 50 \Omega$. 
### TABLE 8.5 Measured Attenuation of CPW on HR-Si Wafer with a Thick Interface Oxide Layer

<table>
<thead>
<tr>
<th>Frequency (GHz)</th>
<th>Attenuation (dB/cm)</th>
</tr>
</thead>
<tbody>
<tr>
<td>2.5</td>
<td>1.6</td>
</tr>
<tr>
<td>5.0</td>
<td>2.0</td>
</tr>
<tr>
<td>10.0</td>
<td>2.7</td>
</tr>
<tr>
<td>15.0</td>
<td>3.6</td>
</tr>
<tr>
<td>20.0</td>
<td>4.3</td>
</tr>
</tbody>
</table>

Note: $S = 8 \, \mu m$, $W = 5 \, \mu m$, $g = 40 \, \mu m$, $t = 2.4 \, \mu m$ (Cu), $t_1 = 6.6 \, \mu m$ (SiO$_2$), $\rho > 1000 \, \Omega \cdot \text{cm}$, $Z_0 = 60 \, \Omega$.

**Conductors Separated from the Silicon Wafer by a Thin Insulating Layer** A simple solution to block the leakage current is to deposit a thin insulator, such as silicon dioxide (SiO$_2$, $\varepsilon_r = 3.9$) or silicon nitride (Si$_3$N$_4$, $\varepsilon_r = 7.5$), between the silicon wafer and the metal conductors. In such a structure because of defects in the oxide layer, fixed positive charges are present at a distance of few tens of angstroms from the semiconductor-insulator interface [18]. These fixed positive charges set up an electron populated inversion layer in a p-type silicon or an accumulation layer in a n-type silicon at the interface [17], and [19]. This charge layer provides a low-resistance path for the RF fields in the coplanar waveguide slots. Consequently the coplanar waveguide attenuation increases substantially [17], [19] to [21] when an oxide or a nitride layer is present. In addition the interface can be charged or discharged depending upon the surface potential, hence the attenuation varies as a function of the dc bias voltage [19]. The charge layer can be interrupted by etching away the SiO$_2$ or Si$_3$N$_4$ layer from the slot regions as shown in Figure 8.9 [17] and [19]. After this etch step, the coplanar waveguide attenuation is almost independent of the dc bias and is about the same as when the metal is in direct contact with the high-resistivity silicon [17].

**Conductors Separated from the Silicon Wafer by a Very Thick Insulating Layer** In the coplanar waveguide structures considered in the previous sections the thickness of the oxide or nitride layer is few thousand angstroms while the slot width is several microns wide. This proximity causes significant interaction to take place between the RF fields in the slot and the interface charge sheet. However, when the oxide or nitride layer is very thick on the order of several microns and the slot width is less than the oxide thickness ($W < t_1$), the interaction of the RF fields with the interface charge sheet is small due to the large distance of separation. This is evident from the attenuation measurements reported in [22]. The results from [22] are summarized in Table 8.5. It is interesting to note that the attenuation constant given in Table 8.5 for
a coplanar waveguide with very thick oxide layer is about the same as when the coplanar waveguide conductors are in direct contact with the high-resistivity silicon wafer (see the second column of Table 8.4).

### 8.4.2 Low-Resistivity Silicon Wafer

In the previous sections it was shown that for low attenuation the resistivity of the silicon wafer should be greater than $2500 \Omega \cdot \text{cm}$. However, these high-resistivity silicon wafers are more expensive than the standard CMOS grade silicon wafers. Further there is also the possibility of them not being fully compatible with the standard silicon IC process. The standard process uses CMOS grade wafers with resistivity typically on the order of $0.5$ to $20.0 \Omega \cdot \text{cm}$ and aluminium for interconnects. Hence in this section a technique to lower the attenuation of coplanar waveguide on standard CMOS grade silicon wafers is discussed. A simple solution to isolate the RF fields in the coplanar waveguide slots from the low-resistivity wafer is to use a thick insulating layer of SiO$_2$ or polyimide. To lower further the surface resistance of the coplanar waveguide conductors, a metal with conductivity higher than that of aluminium is chosen. The measured attenuation constants for coplanar waveguide with different insulating material thickness is summarized in Table 8.6. Two observations can be made from this table. First, as the polyimide thickness increases, the attenuation constant decreases [23]. Second, when the slot width is less than the SiO$_2$ layer thickness, the attenuation constant is insensitive to the substrate resistivity [22]. This is evident by comparing the attenuation constant of a coplanar waveguide on a low-resistivity silicon wafer (the last row of Table 8.6) with the attenuation constant of an identical coplanar waveguide on a high-resistivity silicon wafer (see Table 8.5).

### 8.5 ATTENUATION CHARACTERISTICS OF COPLANAR WAVEGUIDE ON MICROMACHINED SILICON WAFER

#### 8.5.1 Microshield Line

A microshield line [26] to [28] is shown in Figure 7.1(b). In the microshield line the center strip conductor and the upper ground planes are supported by a dielectric membrane. The dielectric membrane is formed by depositing a tri-layer of SiO$_2$/Si$_3$N$_4$/SiO$_2$ on a silicon wafer. The shielding cavity below the membrane is formed by micromachining the silicon wafer and coating the surface with a metal, such as gold. The bottom wall of the cavity is formed by the metallized surface of a second silicon wafer that is placed below. The thickness of the strip conductor, the ground planes and the metal coating is about two to three times the skin depth at the operating frequency. A transition between a microshield line and a grounded coplanar waveguide is essential for on-wafer characterization of microshield lines. A typical transition is discussed
<table>
<thead>
<tr>
<th>Substrate Resistivity, Ω-cm</th>
<th>Insulating Material Thickness, μm</th>
<th>Metal for CPW Conductor and thickness, μm</th>
<th>CPW Strip Width, μm</th>
<th>CPW Slot Width, μm</th>
<th>Z₀, Ω GHz</th>
<th>4.0 GHz</th>
<th>10.0 GHz</th>
<th>20.0 GHz</th>
<th>40.0 GHz</th>
<th>Reference</th>
</tr>
</thead>
<tbody>
<tr>
<td>n-type Si 0.5–2.5</td>
<td>Polyimide 8.83</td>
<td>Au 10</td>
<td>4.5</td>
<td>50</td>
<td>—</td>
<td>0.3</td>
<td>—</td>
<td>0.75</td>
<td></td>
<td>[23]</td>
</tr>
<tr>
<td>n-type Si 0.5–2.5</td>
<td>Polyimide 14.59</td>
<td>Au 20</td>
<td>6</td>
<td>50</td>
<td>—</td>
<td>0.22</td>
<td>—</td>
<td>0.62</td>
<td></td>
<td>[23]</td>
</tr>
<tr>
<td>n-type Si 0.5–2.5</td>
<td>Polyimide 20.15</td>
<td>Au 30</td>
<td>8</td>
<td>50</td>
<td>0.11</td>
<td>0.17</td>
<td>0.285</td>
<td>0.55</td>
<td></td>
<td>[23]</td>
</tr>
<tr>
<td>p-type Si 20</td>
<td>Polyimide 10</td>
<td>Al 12</td>
<td>18</td>
<td>—</td>
<td>0.2</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>[24]</td>
</tr>
<tr>
<td>Si 5–20</td>
<td>Polyimide 10</td>
<td>Ti/Au 34</td>
<td>8</td>
<td>50</td>
<td>0.4</td>
<td>—</td>
<td>—</td>
<td>1.2</td>
<td></td>
<td>[19]</td>
</tr>
<tr>
<td>p-type Si 8 porous silicon 20</td>
<td>Oxidized SiO₂ 10</td>
<td>Au 100</td>
<td>30</td>
<td>50</td>
<td>0.1</td>
<td>0.3</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>[25]</td>
</tr>
<tr>
<td>Si 10</td>
<td>Cu 6.3</td>
<td></td>
<td>5</td>
<td>53</td>
<td>0.22</td>
<td>0.325</td>
<td>0.5</td>
<td>—</td>
<td></td>
<td>[22]</td>
</tr>
</tbody>
</table>
later in Section 10.4.1. Using two such transitions, a set of RF probes and the NIST software \[12\] the effective dielectric constant and attenuation constant can be determined. In Table 8.7 the geometry and the measured attenuation constant \[28\] of typical microshield lines are summarized. The table shows that the attenuation constant is as low as 0.03 dB/mm at 40.0 GHz.

### 8.5.2 Coplanar Waveguide with V-Shaped Grooves

A coplanar waveguide with V-shaped micromachined grooves and with finite width ground planes \[29\], \[30\] is shown in Figure 8.10. In this line the silicon material below the two slots is removed by a wet chemical etchant such as ethylenediamine pyrocatechol (EDP). As a result a V-shaped groove is formed below the slots with side walls dictated by the 54.74° angle of the \(\{111\}\) silicon crystal planes \[31\]. The groove size \(G\) is defined as the slot width \(W\) plus the lateral undercut \(U\) on either side. The depth of the center of the V-shaped groove depends on the dimension \(G\) and the angle of 54.74°. A SiO\(_2\)/Si\(_3\)N\(_4\)/SiO\(_2\) protective layer of thickness \(t\) is present between the conductors and the silicon wafer. In Table 8.8 the geometry and the measured attenuation constant \[29\] of typical coplanar waveguides with V-shaped grooves are summarized. In addition for the purpose of comparison, the measured attenuation constant of conventional coplanar waveguides with identical strip and slot width is presented. This table shows that the effective dielectric constant and the attenuation constant decreases as material below the slots is etched away. Furthermore a lower effective dielectric constant results in a lower line capacitance that increases the characteristic impedance \(Z_0\).

### 8.5.3 Coplanar Waveguide Suspended by a Silicon Dioxide Membrane over a Micromachined Wafer

In this section, first, a technique to lower the attenuation of a coplanar waveguide on a standard CMOS grade silicon wafer through the use of micromachining techniques is explained. Second, the measured attenuation constant of the coplanar waveguide before and after micromachining the wafer is presented.

A coplanar waveguide suspended by a silicon dioxide membrane over a micromachined silicon wafer \[32\], \[33\] is shown in Figures 8.11(a) and (b). The line is fabricated in a commercial 2 \(\mu\)m CMOS n-well process on a 460 \(\mu\)m thick \(\{100\}\) silicon wafer. The three steps involved in the fabrication process are briefly explained below. First, the silicon dioxide layer for the membrane and the aluminum conductor strips for the coplanar waveguide are formed over the silicon wafer. Second, through the openings in silicon dioxide layer small cavities are created in the silicon wafer adjacent to the conductors by reactive ion etching process. This is an isotropic etch, and hence the grooves propagate outward radially beneath the coplanar waveguide conductors and connect the cavities on either sides of the coplanar waveguide. This is followed by the third
### TABLE 8.7 Measured Effective Dielectric Constant and Attenuation of Microshield Line

<table>
<thead>
<tr>
<th>Strip Width $S$, μm</th>
<th>Slot Width $W$, μm</th>
<th>Height $H$, μm</th>
<th>Metallization Thickness $t$, μm</th>
<th>Characteristic Impedance $Z_0$, Ω</th>
<th>Effective Dielectric Constant $\varepsilon_{\text{eff}}$</th>
<th>Attenuation in dB/mm</th>
</tr>
</thead>
<tbody>
<tr>
<td>250</td>
<td>25</td>
<td>355</td>
<td>1.2</td>
<td>75</td>
<td>1.15</td>
<td>0.045</td>
</tr>
<tr>
<td>190</td>
<td>55</td>
<td>355</td>
<td>1.2</td>
<td>100</td>
<td>1.08</td>
<td>0.02</td>
</tr>
</tbody>
</table>

Note: Width of lower shielding cavity is 1800 μm. Membrane is SiO$_2$ (7000 Å)/Si$_3$N$_4$ (3000 Å)/SiO$_2$ (4000 Å).
and last step in which the wafer is immersed in a chemical etchant. This is an anisotropic etch and follows the crystalline structure of the \langle100\rangle wafer forming a V-shaped groove. The walls of the groove slope at an angle of 54.74° from the surface plane and are aligned to the \langle111\rangle crystallographic plane of the silicon wafer.

The measured attenuation constant before and after micromachining the wafer [32] is presented in Table 8.9. Clearly, there is a very significant improvement in the attenuation constant after the micromachining process. However, the improvement is limited by the relatively high series resistance of the strip conductors because of the very small thickness of the metal layers. In a commercial CMOS process, the thickness of the metal layer is fixed and is not a design parameter. Hence further improvement in attenuation constant can be obtained by increasing the strip conductor widths.

8.6 ATTENUATION CONSTANT FOR SUPERCONDUCTING COPLANAR WAVEGUIDES

In this section the closed form expressions presented for computing the attenuation constant $\alpha_c$ of superconducting coplanar waveguide [34] include conductor losses. These expressions are valid for arbitrary conductor thickness and are derived in a manner analogous to that for normal metal as in Section 8.2.3.

8.6.1 Stopping Distance

The first step is to determine the stopping distance $\Delta$. The value of the stopping distance is determined numerically and is a function only of the edge profile $\theta$, the strip thickness $t$, and the material properties of the conductors. The edge profile $\theta$ is assumed to be 90°; however, $\theta$ can take any arbitrary value between
Table 8.8: Measured Attenuation of Si-Micromachined Coplanar Waveguide at W-Band (94 GHz)

<table>
<thead>
<tr>
<th>Strip Width, μm</th>
<th>Slot Width, μm</th>
<th>Parameter</th>
<th>Conventional Coplanar Waveguide</th>
<th>Micromachined Coplanar Waveguide Undercut</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td>2 μm</td>
<td>4 μm</td>
</tr>
<tr>
<td>20</td>
<td>45</td>
<td>$e_{\text{eff}}$</td>
<td>4.938</td>
<td>4.165</td>
</tr>
<tr>
<td></td>
<td></td>
<td>$\alpha$ (dB/cm)</td>
<td>3.65</td>
<td>3.2</td>
</tr>
<tr>
<td></td>
<td></td>
<td>$Z_0$ (Ω)</td>
<td>71.3</td>
<td>77.31</td>
</tr>
<tr>
<td>40</td>
<td>80</td>
<td>$e_{\text{eff}}$</td>
<td>5.57</td>
<td>4.625</td>
</tr>
<tr>
<td></td>
<td></td>
<td>$\alpha$ (dB/cm)</td>
<td>1.95</td>
<td>1.8</td>
</tr>
<tr>
<td></td>
<td></td>
<td>$Z_0$ (Ω)</td>
<td>64.2</td>
<td>70.2</td>
</tr>
<tr>
<td>50</td>
<td>45</td>
<td>$e_{\text{eff}}$</td>
<td>5.408</td>
<td>4.83</td>
</tr>
<tr>
<td></td>
<td></td>
<td>$\alpha$ (dB/cm)</td>
<td>2.2</td>
<td>1.6</td>
</tr>
<tr>
<td></td>
<td></td>
<td>$Z_0$ (Ω)</td>
<td>57.0</td>
<td>60.31</td>
</tr>
</tbody>
</table>

Note: Silicon substrate thickness and resistivity are 500 μm and >2000 Ω-cm. SiO₂/Si₃N₄/SiO₂ protective layer is 1.5 μm thick. Metallization is 1.7 to 2.0 μm thick.
ATTENUATION CONSTANT FOR SUPERCONDUCTING COPLANAR WAVEGUIDES

FIGURE 8.11  Coplanar waveguide suspended by a silicon dioxide membrane over a micromachined substrate: (a) Top view; (b) cross section.
<table>
<thead>
<tr>
<th>Strip Width, $2a$ (μm)</th>
<th>Slot Width, $b - a$ (μm)</th>
<th>Ground plane Width, $c - b$ (μm)</th>
<th>Conductor Thickness $t$ (μm)</th>
<th>$e_{\text{eff}}$</th>
<th>$Z_0$ (Ω)</th>
<th>Attenuation (dB/cm)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>Before Micromachining</td>
</tr>
<tr>
<td>24</td>
<td>3</td>
<td>50</td>
<td>0.6</td>
<td>2.18</td>
<td>50</td>
<td>17.0 25.5 31.75 38.0</td>
</tr>
</tbody>
</table>
45° and 90°, as described in Section 8.2.3 for normal metals. The thickness \( t \) is also arbitrary and typically can range from 0.05 to 0.5 \( \mu \text{m} \). The material properties of the conductors are taken into account through the complex conductivity \( \tilde{\sigma} \) which is defined as [34]

\[
\tilde{\sigma} = \sigma_1 - j\sigma_2 \quad \text{S/meter},
\]

where \( \sigma_1 \) and \( \sigma_2 \) are the real and imaginary part respectively of the conductivity. The real and imaginary part represent the normal and super fluid, respectively, in a two-fluid model for a superconductor. The real part of the conductivity can be included in the expression for the normal fluid skin depth \( \delta_{nf} \) defined as [34]

\[
\delta_{nf} = \sqrt{\frac{2}{\mu_0 \omega \sigma_1}} \quad \text{meters},
\]

where

\[
\mu_0 = 4\pi \times 10^{-7} \quad \text{Henry/meter}
\]

\[
\omega = 2\pi f
\]

\( f = \) frequency of operation in c/s.

Likewise the imaginary part of the conductivity can be included in the expression for the superconducting magnetic penetration depth \( \lambda_p \) which is defined as [34]

\[
\lambda_p = \sqrt{\frac{1}{\mu_0 \omega \sigma_2}} \quad \text{meters}.
\]

The \( \lambda_p \) is also referred to as the London penetration depth. Typically for a good superconductor \( \lambda_p \ll \delta_{nf} \) and the ratio \( t/2\delta_{nf} \) is \( \lesssim 0.1 \). This is evident from Table 8.10, which presents the measured material characteristics of superconducting \( \text{YBa}_2\text{Cu}_3\text{O}_{7-\delta} \) thin films [34]. This material represents a general class of high-\( T_c \) superconductors.

In Figure 8.12 universal curves [34] for the numerically determined stopping distance \( \Delta \) are presented as a function of the normalized thickness \( t/2\lambda_p \) and the ratio \( t/2\delta_{nf} \) as a parameter for a superconducting strip with an edge profile \( \theta = 90 \). Notice that the stopping distance \( \Delta \) is sensitive to the ratio \( t/2\lambda_p \) but insensitive to small values of the parameter \( t/2\delta_{nf} \), typically in the range of \( 0 < t/2\delta_{nf} \lesssim 0.2 \). The parameter \( t/2\delta_{nf} \) for a good superconductor is \( \lesssim 0.1 \), from Table 8.10. Hence we can set the ratio \( t/2\delta_{nf} \approx 0 \) and use just one of the curves shown in Figure 8.12 for the stopping distance \( \Delta \) of a strip fabricated from a good superconductor. The data in Figure 8.12 are tabulated in Table 8.11 [37] to facilitate computation of the attenuation constant as explained in the next section.
TABLE 8.10 Material Characteristics of YBa$_2$Cu$_3$O$_{7-\delta}$ Thin Film Grown by Pulsed-Laser Deposition on LaAlO$_3$ ($T_c \approx 91$ K)

<table>
<thead>
<tr>
<th>$t$ (µm)</th>
<th>$\lambda_p$ (µm)</th>
<th>$t/2 \lambda_p$</th>
<th>$\sigma_1$ (S/m)</th>
<th>Frequency (GHz)</th>
<th>$\delta_{nf}$ (µm)</th>
<th>$t/2\delta_{nf}$</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Temperature = 76 K</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0.05</td>
<td>0.316</td>
<td>0.0791</td>
<td>$1.72 \times 10^6$</td>
<td>3</td>
<td>7.00</td>
<td>0.0036</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>10</td>
<td>3.84</td>
<td>0.0065</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>20</td>
<td>2.71</td>
<td>0.0092</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>30</td>
<td>2.22</td>
<td>0.0113</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>40</td>
<td>1.92</td>
<td>0.0130</td>
</tr>
<tr>
<td>Temperature = 30 K</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0.05</td>
<td>0.205</td>
<td>0.122</td>
<td>$2.13 \times 10^6$</td>
<td>3</td>
<td>6.30</td>
<td>0.0040</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>10</td>
<td>3.45</td>
<td>0.0072</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>25</td>
<td>2.18</td>
<td>0.0115</td>
</tr>
<tr>
<td>0.32</td>
<td>0.7805</td>
<td>2.63 $\times 10^6$</td>
<td>3</td>
<td>5.66</td>
<td>0.0282</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>10</td>
<td>3.10</td>
<td>0.0516</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>25</td>
<td>1.96</td>
<td>0.0815</td>
</tr>
<tr>
<td>0.5</td>
<td>1.2195</td>
<td>3.13 $\times 10^6$</td>
<td>3</td>
<td>5.19</td>
<td>0.0481</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>10</td>
<td>2.84</td>
<td>0.0879</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>25</td>
<td>1.80</td>
<td>0.1390</td>
</tr>
</tbody>
</table>

8.6.2 Closed Form Equations

After the stopping distance $\Delta$ has been determined, the attenuation constant of a superconducting coplanar waveguide can be computed using [34]

$$\alpha_c \approx \frac{R_{sm} b^2}{16Z_0[K^2(a/b)][(b^2 - a^2)]} \left\{ \frac{1}{a} \ln \left( \frac{2a(b - a)}{\Delta(b + a)} \right) + \frac{1}{b} \ln \left( \frac{2b(b - a)}{\Delta(b + a)} \right) \right\}, \quad (8.47)$$

where

$2a =$ coplanar waveguide center strip conductor width $S$

$2b =$ coplanar waveguide ground plane separation equal to $(S + 2W)$

$K(a/b) =$ complete elliptic integral of the first kind

$Z_0 =$ coplanar waveguide characteristic impedance given by Eq. (8.15):

$$R_{sm} = \mu_0 \omega t \text{ Imaginary} \left( \frac{\cot(k_c t) + \csc(k_c t)}{k_c t} \right)$$

which is a modified surface impedance for a superconductor strip of thickness $t$. 
FIGURE 8.12  Computed stopping distance as a function of \( t/2\lambda_p \) for various values of \( t/2\delta_{nf} \). (Reference [34], © IEEE 1999.)

The complex wavenumber \( k_c \) in the superconductor at a frequency \( \omega \) is given by [34]

\[
k_c^2 = \left( \frac{1}{\lambda_p} \right)^2 + 2j \left( \frac{1}{\delta_{nf}} \right)^2.
\]  \( (8.49) \)

The losses occurring both in the center strip conductor as well as the two ground planes of the coplanar waveguide are included in the expression for the attenuation constant given in Eq. (8.47).

The quality factor (\( Q \)) of a superconducting coplanar waveguide resonator is given by [34]

\[
Q = \frac{\beta}{2\alpha},
\]  \( (8.50) \)

where \( \beta \) is the phase constant and is expressed as

\[
\beta \approx \left( \frac{\omega}{c} \right) \sqrt{\varepsilon_{eff}} \text{ rad/m},
\]  \( (8.51) \)

where \( c \) is the velocity of light in vacuum and \( \varepsilon_{eff} \) is the effective dielectric
TABLE 8.11 Stopping Distance t/ as a Function of t/2p for Various Values of t/2nf
t/
t/2

0.0000
0.10000
0.20000
0.30000
0.40000
0.50000
0.60000
0.70000
0.80000
0.90000
1.0000
1.1000
1.2000
1.3000
1.4000
1.5000
1.6000
1.7000
1.8000
1.9000
2.0000
2.1000
2.2000
2.3000
2.4000
2.5000
2.6000
2.7000
2.8000
2.9000
3.0000
3.1000
3.2000
3.3000
3.4000
3.5000
3.6000
3.7000
3.8000
3.9000
4.0000
4.1000
4.2000
4.3000
4.4000
4.5000
4.6000
4.7000
4.8000
4.9000
5.0000

t/2 :1.0

200.50
198.70
193.49
185.47
175.50
164.54
153.54
143.33
134.49
127.43
122.33
119.23
118.06
118.64
120.79
124.26
128.80
134.15
140.06
146.27
152.57
158.75
164.66
170.16
175.16
179.62
183.50
186.81
189.57
191.82
193.58
194.93
195.90
196.54
196.91
197.05
196.99
196.77
196.43
195.98
195.46
194.89
194.28
193.64
192.99
192.34
191.70
191.06
190.45
189.85
189.28

Source: From Reference [37].

232

t/2 :0.5

33.968
33.266
31.465
29.289
27.493
26.594
26.840
28.300
30.965
34.814
39.823
45.967
53.202
61.455
70.608
80.500
90.928
101.66
112.45
123.05
133.24
142.83
151.68
159.69
166.80
173.01
178.32
182.80
186.49
189.47
191.82
193.62
194.94
195.86
196.44
196.73
196.79
196.66
196.38
195.98
195.49
194.94
194.34
193.72
193.07
192.42
191.78
191.14
190.52
189.92
189.35

t/2 :0.2

10.336
10.267
10.275
10.706
11.742
13.447
15.865
19.052
23.072
27.992
33.865
40.726
48.576
57.370
67.013
77.354
88.198
99.312
110.45
121.37
131.84
141.68
150.75
158.94
166.21
172.54
177.96
182.51
186.27
189.30
191.70
193.53
194.88
195.81
196.40
196.70
196.77
196.65
196.37
195.98
195.49
194.94
194.35
193.72
193.08
192.43
191.78
191.15
190.53
189.93
189.35

t/2 :0.1

9.2570
9.2685
9.4667
10.095
11.285
13.096
15.585
18.822
22.877
27.823
33.719
40.601
48.454
57.278
66.925
77.279
88.131
99.261
110.39
121.32
131.82
141.63
150.70
158.94
166.23
172.55
177.99
182.50
186.27
189.29
191.69
193.53
194.87
195.81
196.39
196.70
196.77
196.66
196.36
195.99
195.50
194.94
194.38
193.69
193.05
192.46
191.75
191.17
190.56
189.94
189.40

t/2 :0.01

9.1794
9.1974
9.4088
10.054
11.254
13.072
15.565
18.805
22.864
27.812
33.708
40.588
48.454
57.262
66.918
77.271
88.125
99.251
110.40
121.33
131.80
141.66
150.73
158.92
166.19
172.52
177.95
182.50
186.26
189.30
191.70
193.53
194.88
195.81
196.40
196.70
196.77
196.65
196.37
195.98
195.49
194.94
194.35
193.72
193.08
192.43
191.78
191.15
190.53
189.93
189.35


TABLE 8.12 Measured Attenuation Constant of YBa$_2$Cu$_3$O$_{7-a}$ Superconductive 50 Ω Coplanar Waveguides on LaAlO$_3$ Substrate ($T_c ≈ 91$ K)

<table>
<thead>
<tr>
<th>$t$ (μm)</th>
<th>$T$ (K)</th>
<th>Measured $\lambda_p$ (μm)</th>
<th>Measured $\sigma_i$ (S/m)</th>
<th>Strip Width (μm)</th>
<th>Slot Width (μm)</th>
<th>Measured Attenuation (dB/cm)</th>
</tr>
</thead>
<tbody>
<tr>
<td>0.05</td>
<td>76</td>
<td>0.316</td>
<td>$1.72 \times 10^6$</td>
<td>21</td>
<td>40</td>
<td>0.1</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>53</td>
<td>101</td>
<td>0.05</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td>105</td>
<td>200</td>
<td>—</td>
</tr>
</tbody>
</table>

constant approximated as

$$\varepsilon_{\text{eff}} \approx \frac{\varepsilon_r + 1}{2}$$  \hspace{1cm} (8.52)

and $\varepsilon_r$ is the dielectric constant of the substrate material.

8.6.3 Comparison with Numerical Calculations and Measured Results

The attenuation constant computed for a high-temperature superconducting coplanar waveguide using the closed form Eq. (8.47) and using the mode-matching method [3], [35] are shown to be in excellent agreement in [34]. In addition the measured attenuation constant and the computed attenuation constant using the closed form Eq. (8.47) for three high-temperature superconducting coplanar waveguide structures are shown to be in good agreement in [34]. These measured attenuation constants are representative of a general class of high-temperature superconducting materials, and they are summarized in Table 8.12. Additional characteristics and applications of high-temperature superconducting coplanar waveguides can be found in Section 12.4 and [36], respectively.

REFERENCES


[7] D. Williams and R. Marks, NIST, Boulder, CO., personal communication with authors of [6].


REFERENCES


[37] C. L. Holloway, personal communication.
CHAPTER 9

Coplanar Waveguide Discontinuities and Circuit Elements

9.1 INTRODUCTION

This chapter presents the characteristics of coplanar waveguide (CPW) discontinuities and circuits. These are typical discontinuities and are an integral part of practical CPW circuits. Therefore a good understanding of their circuit behavior is essential for design success. The CPW discontinuities in Sections 9.2 through 9.7 include open end, short end, series gap in the center strip conductor, step change in the width of the center strip conductor, and right angle bend.

Air-bridges are frequently employed in CPW circuits to suppress the propagation of the parasitic coupled slot line mode. Hence, different types of air-bridges and their characteristics are presented in Section 9.8. To realize CPW components such as stub filters, power dividers, and hybrid couplers, we require T-junctions. Hence Section 9.9 is devoted to two types of T-junctions and their characteristics. Sections 9.10 through 9.13 present the characteristics of CPW spiral inductors, interdigital and metal-insulator-metal (MIM) capacitors, series and shunt stubs, and shunt inductors, respectively.

9.2 COPLANAR WAVEGUIDE OPEN CIRCUIT

A coplanar waveguide (CPW) open circuit [1] is formed by ending the center strip conductor of width $S$ a short distance before the slot ends, thereby creating a gap $g_1$ as shown in Figure 9.1. An electric field exists at the open circuit between the terminated center conductor and the surrounding ground.
FIGURE 9.1 Coplanar waveguide open circuit.

conductor and hence gives rise to a capacitive reactance. This reactance is seen at the plane $P-P'$ coincident with the open end of the center conductor. Thus the apparent position of the open circuit is beyond the physical end of the center conductor. This length extension is denoted as $l_{oc}$. The open circuit capacitance $C_{oc}$ is a parallel combination of the capacitance due to the fringing fields across the gap $g_1$ and those across the slot $W$. The gap-dependent capacitance varies proportionately as $1/g_1$. The slot-dependent capacitance is constant. The capacitance $C_{oc}$ is related to $l_{oc}$ by

$$C_{oc} = \frac{\tan(\beta l_{oc})}{\omega Z_0}, \quad (9.1)$$

where $\beta$ is the phase constant and is given by

$$\beta = \frac{2\pi f}{c} \sqrt{\varepsilon_{\text{eff}}}, \quad (9.2)$$

and where

- $\varepsilon_{\text{eff}} = $ CPW effective dielectric constant
- $f = $ frequency in Hz
- $c = $ velocity of light in free space in meters/second
- $Z_0 = $ CPW characteristic impedance and

$$\omega = 2\pi f. \quad (9.3)$$
When \( l_{\text{oc}} \) is small compared to a wavelength, the term \( \tan(\beta l_{\text{oc}}) \) is approximately equal to \( \beta l_{\text{oc}} \) and hence Eq. (9.1) can be rewritten as

\[
C_{\text{oc}} = \left( \frac{\beta}{\omega Z_0} \right) l_{\text{oc}}. \tag{9.4}
\]

The capacitance \( C \) per unit length in F/meter for an ideal lossless CPW is given by

\[
C = \frac{\beta}{\omega Z_0}. \tag{9.5}
\]

Hence, Eq. (9.4) can be written as

\[
\frac{C_{\text{oc}}}{C} = l_{\text{oc}}. \tag{9.6}
\]

### 9.2.1 Approximate Formula for Length Extension When the Gap Is Large

The \( l_{\text{oc}} \) has been determined as a function of the gap \( g_1 \) using finite difference method (FDM) in the frequency domain in [2], [3]. These studies show that when the dimensions of the CPW are very small compared to the guide wavelength, the dispersion is negligible and \( l_{\text{oc}} \) remains nearly constant and independent of the frequency. In general, \( l_{\text{oc}} \) is a function of the strip conductor width \( S \), slot width \( W \) and the open end gap width \( g_1 \). However, for a fixed \( S \) and \( W \), as \( g_1 \) increases, \( l_{\text{oc}} \) monotonically decreases and eventually saturates. This limit is reached when \( g_1 \geq S + 2W \). Hence, for a minimum parasitic \( C_{\text{oc}} \) or \( l_{\text{oc}} \), it is sufficient to choose \( g_1 = (S + 2W) \). A simple design rule that provides this minimum \( l_{\text{oc}} \) when \( g_1 \geq S + 2W \) and \( 0.2 \leq S/(S + 2W) \leq 0.8 \) is [2]

\[
l_{\text{oc}} = \frac{S + 2W}{4}. \tag{9.7}
\]

This equation holds good for most semiconductor substrates including GaAs. In addition it has less than 1 percent error for a line with \( Z_0 = 50 \Omega \) and for all other line geometries a deviation up to 20 percent is observed [2].

### 9.2.2 Closed Form Equation for Open End Capacitance When the Gap Is Narrow

An analytical formula for \( C_{\text{oc}} \) under the narrow gap assumption, that is, when \( g_1 \leq 0.1(S + 2W) \), has been derived in [4]. The derivation in [4] is based on variational technique and makes use of analytical Green’s function and exact
TABLE 9.1 CPW Open Circuit Capacitance

<table>
<thead>
<tr>
<th>$h$, $\mu$m</th>
<th>$\varepsilon_r$</th>
<th>Strip Width, $\mu$m</th>
<th>Slot Width, $\mu$m</th>
<th>$e_{\text{eff}}$</th>
<th>$g_1$, $\mu$m</th>
<th>$C_{\text{oc}}$(fF)$^a$</th>
<th>$C_{\text{oc}}$(fF)$^b$</th>
</tr>
</thead>
<tbody>
<tr>
<td>200</td>
<td>12.9</td>
<td>20</td>
<td>20</td>
<td>4.8088</td>
<td>20</td>
<td>2.1</td>
<td>1.31</td>
</tr>
<tr>
<td>160</td>
<td></td>
<td>20</td>
<td>16</td>
<td>5.3205</td>
<td>20</td>
<td>16</td>
<td>13.3</td>
</tr>
<tr>
<td>20</td>
<td></td>
<td>160</td>
<td>2.9</td>
<td>6.0636</td>
<td>160</td>
<td>2.9</td>
<td>5.4</td>
</tr>
</tbody>
</table>

$^a$From Bromme and Jansen [5].
$^b$Using Eq. (9.9).

The computed results in [4] show that the ratio of the open end capacitance with and without a dielectric substrate ($C_{\text{oc}}/C_{\text{oc(air)}}$) is within 5 percent of the CPW $e_{\text{eff}}$ when $S/(S + 2W) \geq 0.25$ and $h/(S + 2W) \geq 1.0$. Hence in [4] $C_{\text{oc}}$ is approximated as

$$C_{\text{oc}} = C_{\text{oc(air)}} e_{\text{eff}}, \quad (9.8)$$

where

$$C_{\text{oc(air)}} = \frac{2\varepsilon_0}{\pi} \left\{ (S + W) \left[ \frac{\ln(\eta + \sqrt{1 + \eta^2})}{\eta} + \ln \left( \frac{\sqrt{1 + \eta^2} + 1}{\eta} \right) \right] - \frac{1}{3} \left( \frac{1}{\eta + \sqrt{1 + \eta^2}} + \frac{1}{\eta + \sqrt{1 + \eta^2}} \right) \right\}, \quad (9.9)$$

$$\eta = \frac{g_1}{S + W}. \quad (9.10)$$

The $C_{\text{oc}}$ values determined using Eq. (9.9) are compared with the values from [5] in Table 9.1. It is observed that for $g_1 \leq 0.1(S + 2W)$, the two sets of values are in fair agreement.

9.2.3 Radiation Loss

The radiation loss from a CPW open circuit has been numerically studied using the space domain integral equation method in [6], [7]. The computed results show that the radiation loss increases as the gap width $g_1$ and the center strip conductor width $S$ increases. As an example, for a CPW with $S = 0.5$ mm, $W = 0.25$ mm, on a substrate with $h = 0.635$ mm and $\varepsilon_r = 2.1$, the radiation loss factor which is given by $10 \log(1 - |\Gamma|^2)$, where $|\Gamma|$ is the magnitude of the reflection coefficient, increases from 2.8 to 3.0 percent as $g_1/S + 2W$ increases from 0.25 to 1.25 [6].
9.2.4 Effect of Conductor Thickness and Edge Profile Angle

The length extension $l_{oc}$ has been determined as a function of the conductor thickness $t$ with the edge profile angle $\alpha$ as a parameter using the hybrid finite-element method in [8]. The edge profile angle $\alpha$ is indicated in the inset in Figure 9.1. The computed $l_{oc}$ is for a fixed $\alpha = 90^\circ$, and when $t$ increases from 0 to 5 $\mu$m, it is observed to increase by only 1 percent [2]. Therefore $l_{oc}$ is considered to be independent of $t$. Furthermore, when $\alpha = 45^\circ$ or $135^\circ$, the computed $l_{oc}$ when $t$ increases from 0 to 5 $\mu$m is observed to decrease or increase, respectively, by only a few percent. Hence $l_{oc}$ is insensitive to both conductor thickness and edge profile.

9.3 COPLANAR WAVEGUIDE SHORT CIRCUIT

A coplanar waveguide (CPW) short circuit [1] is formed by abruptly ending the slots as shown in Figure 9.2. In which case a RF current flows around the end of the slots, and therefore magnetic energy is stored behind the termination. This magnetic energy gives rise to an inductive reactance that is modeled as $L_{sc}$ and located at the plane $P-P'$. Thus the apparent position of the short circuit is beyond the physical end of the slots. This length extension is denoted as $l_{sc}$.

9.3.1 Approximate Formula for Length Extension

The $l_{sc}$ has been determined as a function of the slot width $W$ using finite difference method (FDM) in the frequency domain in [2], [3]. Analogous to the CPW open circuit termination, the $l_{sc}$ is independent of the frequency when
TABLE 9.2 CPW Short-Circuit Length Extension and Inductance

<table>
<thead>
<tr>
<th>$h$, $\mu$m</th>
<th>$\varepsilon_r$</th>
<th>Strip Width, $\mu$m</th>
<th>Slot Width, $\varepsilon_{\text{eff}}$, $\mu$m</th>
<th>$Z_0$, $\Omega$</th>
<th>$l_{sc}/h^a$</th>
<th>$l_{sc}/h^b$</th>
<th>$L(\text{pH})^c$</th>
<th>$L(\text{pH})^d$</th>
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</thead>
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<tr>
<td>635</td>
<td>9.7</td>
<td>127</td>
<td>—</td>
<td>0.1</td>
<td>0.075</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td>254</td>
<td>—</td>
<td>—</td>
<td>0.15</td>
<td>0.125</td>
<td>—</td>
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<td>—</td>
<td>0.21</td>
<td>0.175</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td>508</td>
<td>—</td>
<td>—</td>
<td>0.25</td>
<td>0.225</td>
<td>—</td>
<td>—</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td>635</td>
<td>—</td>
<td>—</td>
<td>0.29</td>
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<td>—</td>
</tr>
<tr>
<td>635</td>
<td>9.7</td>
<td>635</td>
<td>127</td>
<td>—</td>
<td>0.22</td>
<td>0.175</td>
<td>—</td>
<td>—</td>
</tr>
<tr>
<td>254</td>
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<td>381</td>
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<td>0.275</td>
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<td>—</td>
<td>0.49</td>
<td>0.375</td>
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</tr>
<tr>
<td>200</td>
<td>12.9</td>
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<td>40</td>
<td>5.6</td>
<td>45.8</td>
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<td>5.2</td>
</tr>
<tr>
<td>40</td>
<td>160</td>
<td>6.1</td>
<td>75.6</td>
<td>—</td>
<td>—</td>
<td>50</td>
<td>36.2</td>
<td></td>
</tr>
<tr>
<td>160</td>
<td>40</td>
<td>5.7</td>
<td>31.2</td>
<td>—</td>
<td>—</td>
<td>19</td>
<td>6.2</td>
<td></td>
</tr>
</tbody>
</table>

*From Jansen [9].

*Using Eq. (9.11).

*From Bromme and Jansen [5].

*Using Eq. (9.12).

The dispersion is small. A simple design rule that provides $l_{sc}$ is given by [2]

$$l_{sc} \approx \frac{S + 2W}{8}.$$  (9.11)

Since $l_{sc}$ is sensitive to the conductor thickness $t$ as explained in the next section, Eq. (9.11) holds good only when $t < W/3$. In general, the values for $l_{sc}$ are about one-half of those obtained for an identical CPW with an open circuit termination [2]. Hence the parasitic effects associated with a short circuit are smaller than those for an open circuit termination. The $l_{sc}$ values determined using Eq. (9.11) are compared with the values from the graph in [9] for $h/\lambda_0 = 0.002$, where $\lambda_0$ is the free space wavelength, and presented in Table 9.2. It is observed that for small $S$ typically $S/h \leq 0.2$, the two sets of values are fairly close.

9.3.2 Closed Form Equations for Short-Circuit Inductance

A closed form equation for $L_{sc}$ based on magnetostatic analysis of a finite-length two-wire transmission line is derived in [10] and is given below:

$$L_{sc} = \left(\frac{2}{\pi}\right)\varepsilon_0\varepsilon_{\text{eff}}(a + b)Z_0^2\left\{1 - \frac{1}{[\cosh(60\pi^2/Z_0\sqrt{\varepsilon_{\text{eff}}})]}\right\},$$  (9.12)
where

\[ \varepsilon_{\text{eff}} = \text{CPW effective dielectric constant} \]

\[ Z_0 = \text{CPW characteristic impedance} \]

\[ 2a = S \]

\[ 2b = S + 2W \]

In a manner analogous to an open circuit termination discussed in Section 9.2, the length extension is given by

\[ l_{sc} = \frac{L_{sc}}{L}, \quad (9.13) \]

where \( L \) is the inductance per unit length in Henry/meter for an ideal lossless CPW and is given by

\[ L = \frac{\beta Z_0}{\omega}, \quad (9.14) \]

where \( \beta \) and \( \omega \) are defined in Eq. (9.2) and (9.3), respectively. The \( L_{sc} \) values determined using Eq. (9.12) are compared with the values from [5] in Table 9.2. It is observed that Eq. (9.12) greatly underestimates the inductance.

9.3.3 Effect of Conductor Thickness and Edge Profile Angle

The length extension \( l_{sc} \) has been determined as a function of the conductor thickness \( t \) with the edge profile angle \( \alpha \) as the parameter using the hybrid finite-element method in [8]. The edge profile angle is indicated in the inset in Figure 9.1. For \( \alpha = 90 \), the computed \( l_{sc} \), when \( t \) increases from 0 to 5 \( \mu \text{m} \) is observed to monotonically decrease by as much as 24 percent [8]. Furthermore, for \( \alpha \) either equal to 45° or 135°, the computed \( l_{sc} \), when \( t \) increases from 0 to 5 \( \mu \text{m} \) is also observed to decrease. However, the decrease is as much as 36 percent [8]. Hence \( l_{sc} \) is very sensitive to both the conductor thickness as well as edge profile angle.

9.4 COPLANAR WAVEGUIDE MIM SHORT CIRCUIT

In the CPW short circuit described in Section 9.3, the center strip conductor and the ground planes are in direct contact, and hence they are at the same potential. This poses a problem in designing circuits with active devices such as MESFETs that require different voltages on the gate and drain terminals. This difficulty can be overcome by including a metal-insulator-metal (MIM)
FIGURE 9.3 Coplanar waveguide MIM short circuit.

capacitor as an integral part of the short circuit as shown in Figure 9.3. The capacitor acts as a dc block for the bias voltage and as an ideal short circuit for signals at microwave frequencies. The length extension \( l_{sc(MIM)} \) is given by [2]

\[
l_{sc(MIM)} = \frac{L_{sc}}{L} - \frac{1}{\omega^2 L C_{MIM}},
\]

(9.15)

where \( L_{sc}/L \) is approximated by Eq. (9.11), \( L \) is given by Eq. (9.14), \( C_{MIM} \) can be determined from the well-known parallel-plate capacitance formula

\[
C_{MIM} = (\varepsilon_r)_{MIM} \frac{p_1 p_2}{t_{MIM}}.
\]

(9.16)

The quantities \( p_1, p_2, t_{MIM}, \) and \( (\varepsilon_r)_{MIM} \) in Eq. (9.16) are indicated in Figure 9.3. Typically in a MIM capacitor, the dielectric material is silicon nitride for which \( (\varepsilon_r)_{MIM} \) and \( t_{MIM} \) are about 6 and 0.2 \( \mu \)m, respectively. Circuit design considerations dictate that \( C_{MIM} \) should be as small as possible to keep the size small. However, for good short-circuit performance \( C_{MIM} \) should be sufficiently large. Hence \( C_{MIM} \) should satisfy the condition [2]

\[
\frac{1}{\omega C_{MIM}} \leq \frac{1}{50} Z_0,
\]

(9.17)

where \( Z_0 \) is the characteristic impedance of the CPW.
9.5 SERIES GAP IN THE CENTER STRIP CONDUCTOR OF A COPLANAR WAVEGUIDE

A series gap of length \( g \) in the center conductor of a CPW [1] is shown in Figure 9.4. In general, the widths \( S_1 \) and \( S_2 \) of the center strip conductor need not be equal. Hence the gap is modeled as a lumped \( \pi \)-network consisting of two unequal fringing capacitances \( C_1 \) and \( C_2 \) and a coupling capacitance \( C_3 \). This type of discontinuity has been theoretically investigated using, an unified strip/slot three dimensional full-wave electromagnetic simulator and three-dimensional finite difference method in [5] and [11], respectively. The computed values of \( C_1 \), \( C_2 \), and \( C_3 \) as a function of the gap \( g \) [11] are shown in Figures 9.4(b), (c), and (d). Furthermore closed form equations to calculate the fringing and coupling capacitances have been obtained in [12] by curve fitting the numerical results of [11]. The results above show that the coupling capacitance decreases proportionally as \( 1/g \). The fringing capacitances for \( S_1 = S_2 \) increase from the CPW line capacitance for \( g = 0 \), to the open circuit saturation capacitance for large \( g \). The effect of metallization thickness \( t \) on the coupling capacitance \( C_3 \) is shown in Figure 9.4(e). The figure shows that the coupling capacitances, in the case of very small gap, is sensitive to the conductor thickness.

9.6 STEP CHANGE IN THE WIDTH OF CENTER STRIP CONDUCTOR OF A COPLANAR WAVEGUIDE

A step change in width of the center strip conductor of a CPW [1] is shown in Figure 9.5. The step discontinuity perturbs the normal CPW electric and magnetic fields and gives rise to additional reactances. These additional reactances are assumed to be lumped and located at the plane of the strip discontinuity.

The step discontinuity has been analyzed using finite difference time domain (FDTD) technique in [13] and modeled as a shunt capacitor \( C_s \). The influence of this capacitance is to effectively lengthen the center strip conductor of the lower impedance CPW toward the higher-impedance CPW. Further, for two CPWs with identical aspect ratio \( S/(S + 2W) \) on the same substrate, \( C_s \) is larger for the CPW with the wider center strip conductor.

The step discontinuity has also been analyzed using hybrid finite element method [14], [15] and modeled as a \( T \)-network consisting of two series inductances \( L_{s1} \) and \( L_{s2} \) and a shunt capacitance \( C_s \). The computed series inductance and shunt capacitance as a function of the step change in the width of the center strip conductor, with the metallization thickness \( t \) as a parameter, are shown in Figure 9.6 (a) and (b), respectively. In Figure 9.6 (a) the series inductance \( L_s \) is the sum of \( L_{s1} \) and \( L_{s2} \). It is observed that for a fixed metallization thickness as the step ratio changes both \( L_s \) and \( C_s \) increase. Besides, at a fixed step ratio as the metallization thickness increases, \( L_s \)
FIGURE 9.4 Series gap in the center strip conductor of a coplanar waveguide: (a) circuit layout; (b) computed fringing capacitance $C_1$; (c) computed fringing capacitance $C_2$; (d) computed coupling capacitance $C_3$; (e) effect of metallization thickness $t$ on the coupling capacitance $C_3$. (Reference [11], ©IEEE 1990.)
Figures 9.4 Continued.

The percentage decrease in $L_s$ is greater than the percentage increase in $C_s$. However, the percentage decrease in $L_s$ is greater than the percentage increase in $C_s$.

### 9.7 COPLANAR WAVEGUIDE RIGHT ANGLE BEND

A coplanar waveguide right angle bend with chamfered corners [16], [17] is shown in Figure 9.7. Air-bridges are placed near the CPW bends in order to suppress the parasitic slot line mode. However, the air-bridges add parasitic capacitance to the bend and degrade its performance. In addition, the bend reactance is also responsible for performance degradation. Chamfering the corners provides a simple method to compensate for both parasitic capacitance as well as bend reactance. In Figure 9.7 the chamfer in the ground plane in defined by the ratio of the distances, $m/m_{\text{max}}$, and takes a value between 0 and 1. The strip corner is chamfered by a proportional amount given by $mS/(S + W)$. For a given $S/W$, the optimum chamfer $(m/m_{\text{max}})_{\text{opt}}$ for minimum
return loss is [17]

\[
\left( \frac{m}{m_{\text{max}}^{\text{opt}}} \right)_{\text{opt}} = \begin{cases} 
0.2102 \ln \left( \frac{S}{W} \right) + 0.7677 & \text{for } 0 \leq S/W \leq 2, \\
1 & \text{for } S/W > 2.5.
\end{cases}
\]  

(9.18)

In developing this equation, it is assumed that the substrate is GaAs \((\varepsilon_r = 12.9)\) and that the thickness \(h\) is 635 \(\mu\)m. In addition the length \(L_a\) and height \(h_a\) above the substrate, of the air-bridges, are assumed to be 40 \(\mu\)m and 3 \(\mu\)m, respectively.

Besides chamfering, compensation for the parasitic capacitance and bend reactance can also be provided by a step change in the width of the center strip conductor [18] or by a dielectric overlay [1]. These techniques are shown in Figures 9.8 (a) and (b). Not much information is available in the literature on the bend shown in Figure 9.8 (a). On the other hand, the CPW bend shown in Figure 9.8(b) is fabricated on a 3.175 mm thick RT-5880 Duroid substrate. The CPW strip and slot widths are 4.5212 and 0.254 mm, respectively, resulting in a characteristic impedance of 50 \(\Omega\). The dielectric overlay on top of the inner slot is formed by an alumina piece measuring 12.5 \(\times\) 12.5 \(\times\) 0.635 mm. Experimental results demonstrate that both techniques provide compensation over a broadband.
FIGURE 9.6 Computed equivalent circuit element values as a function of the step change in width of the center strip conductor with metallization thickness as a parameter, \( \varepsilon_r = 12.9, \ h = 350 \mu m, \ S_1 + 2W_1 = S_2 + 2W_2 = 150 \mu m, \ S_1/(S_1 + 2W_1) = 0.4 \): (a) Total series inductance \( L_s = L_{s1} + L_{s2} \); (b) shunt capacitance. (Reference [15], ©IEEE 1998; Reference [14], ©IEEE 1997.)

9.8 AIR-BRIDGES IN COPLANAR WAVEGUIDE

Air-bridges are used in coplanar waveguide (CPW) based circuits to suppress the parasitic coupled slot line mode and also to provide a dc bias to active devices. There are two types of air-bridges [19], [20] that are commonly used in CPW circuits, and their construction and characteristics are described below.
9.8.1 Type A Air-Bridge

In the air-bridge of Type A, the bridge is formed by an elevated metal strip that connects the ground planes on either side of the center strip conductor as shown in Figure 9.9(a). In this type of air-bridge, the thin metal film for the CPW center strip conductor is fabricated using evaporation, while the bridge is fabricated by electroplating. Typically the thickness \( t_m \) of the metal film and \( t_a \) of the bridge are about 0.4 and 3.0 \( \mu \text{m} \), respectively [19]. The cross section of the bridge is shown in the inset in Figure 9.9(a).

9.8.2 Type B Air-Bridge

The air-bridge of Type B consists of an elevated metal strip that bridges the center strip conductors of two back-to-back CPW open circuits as shown in Figure 9.9(b). The thin metal film for the ground plane below the bridge is fabricated using evaporation while the bridge is fabricated using electroplating. The thickness of the conductors are same as in Type A air-bridge [19]. The cross section of the bridge is shown in the inset in Figure 9.9(b).

9.8.3 Air-Bridge Characteristics

The Type A and Type B air-bridges have been studied using full wave frequency domain TLM method in [21]. The computed magnitude and phase
of the reflection coefficient $S_{11}$ for Type A and Type B air-bridges are shown as a function of the frequency in Figure 9.10(a) and (b). The height $h_a$ and length $L_a$ of both types of air-bridges are held fixed at 3 and 30 $\mu$m, respectively, while carrying out the computations and are typical dimensions of a practical air-bridge. The computed results show that the magnitude of $S_{11}$ is small and almost identical for both types of air-bridges. However, the phase of $S_{11}$ for Type A and Type B air-bridges are opposite, and this indicates that
FIGURE 9.9 Air-bridges for coplanar waveguide: (a) Type A; (b) Type B.

they behave as a capacitor and as a inductor, respectively. The excess capacitance in the case of Type A air-bridge is because of the parasitic parallel-plate capacitor formed by the air bridge and the center strip conductor [20]. In the case of Type B air-bridge, the current distributions is different on the CPW and the section of the line formed by the air-bridge. This change in current distribution gives rise to an inductance [20]. Figure 9.10(a) and (b) also
FIGURE 9.10  Computed reflection coefficient as a function of the frequency with the air-bridge thickness as a parameter, $W = 10 \, \mu m$, $S = 15 \, \mu m$, $h = 100 \, \mu m$, $v_r = 12.9$, $t = t_m = t_m$, $L_a = 30 \, \mu m$, $h_a = 3 \, \mu m$: (a) Type A; (b) Type B ($L_b = 45 \, \mu m$). (Reference [21], ©IEEE 1992.)
shows that the magnitude of $S_{11}$ for both type of air bridges are marginally higher, when the air bridge thickness $t_a$ is increased from 0 to 3 μm.

The computed magnitude and phase of $S_{11}$ as a function of the height $h_a$ and length $L_a$ of the air-bridges are shown in Figures 9.11 and 9.12, respectively. It is observed from Figure 9.11 that $S_{11}$ changes marginally for both type of air-bridges when the height $h_a$ is increased beyond 3 μm. Figure 9.12 shows that $S_{11}$ changes linearly for both type of air-bridges when the length $L_a$ increases beyond 30 μm.

### 9.8.4 Air-Bridge Discontinuity Characteristics

A CPW step discontinuity in close proximity of a Type A air bridge [22] is shown in Figure 9.13. The characteristic impedances $Z_{01}$ and $Z_{02}$ of the CPW on either side of the step are 50 and 45 Ω, respectively. The computed magnitude and phase of the reflection coefficient $S_{11}$ as a function of the distance of separation $d_1$ between the step and the air-bridge are shown in Figure 9.14. It is interesting to observe that the actual location of the air bridge with respect to the step has virtually no effect on $S_{11}$. The change in phase is due to the change in the length of the CPW between the step and the air bridge [21].

A step discontinuity in the air bridge of Type B [22] is shown in Figure 9.15. The characteristic impedances $Z_{01}$ and $Z_{02}$ of the CPW on either side of the air-bridge are 70 and 50 Ω, respectively. The computed magnitude and phase of the reflection coefficient $S_{11}$ and the transmission coefficient $S_{12}$ as a function of the distance $d_2$ from the end of the air-bridge are shown in Figure 9.16. It is observed that the location of the step has little effect on $S_{11}$ and $S_{12}$.

### 9.9. COPLANAR WAVEGUIDE T-JUNCTION

In the design of coplanar waveguide components such as, stub filters, power dividers and branch-line couplers, T-junctions are necessary. Since a T-junction includes several discontinuities, mode conversion takes place within the circuit. Thus power is converted from the desired CPW mode to the parasitic coupled slotline mode as will be shown later. A simple method to suppress the excitation of the coupled slotline mode is by maintaining electrical continuity between the ground planes of the circuit. Normally this is accomplished by bond wires or air-bridges. There are two types of CPW T-junctions that employ air-bridges [19], [23]. Their construction as well as their characteristics will be described in the following sections.

#### 9.9.1 Conventional T-Junction

A CPW conventional T-junction is shown in Figure 9.17. In this structure, the three CPW center strip conductors meet to form the junction while the
FIGURE 9.11 Computed reflection coefficient as a function of the air-bridge height, $W = 10 \mu m$, $S = 15 \mu m$, $h = 100 \mu m$, $\varepsilon_r = 12.9$, $t = t_m = t_s = 3 \mu m$, $L_a = 30 \mu m$, frequency = 40.0 GHz: (a) Type A; (b) Type B ($L_b = 45 \mu m$). (Reference [21], ©IEEE 1992.)
FIGURE 9.12  Computed reflection coefficient as a function of the air-bridge length, 
$W = 10 \, \mu m$, $S = 15 \, \mu m$, $h = 100 \, \mu m$, $\nu_e = 12.9$, $t = t_m = t_a = 3 \, \mu m$, $h_s = 3 \, \mu m$, frequency = 40.0 GHz): (a) Type A; (b) Type B ($L_b = L_a + 15.0 \, \mu m$). (Reference [21], ©IEEE 1992.)
FIGURE 9.13 A CPW step discontinuity in close proximity of a Type A air-bridge.

FIGURE 9.14 Computed reflection coefficient as a function of the distance of separation. $W_1 = 12 \, \mu m$, $S_1 = 12 \, \mu m$, $W_2 = 8 \, \mu m$, $S_2 = 20 \, \mu m$, $h = 100 \, \mu m$, $\varepsilon_r = 12.9$, $h_a = 3 \, \mu m$, $L_a = 30 \, \mu m$, $t = t_a = 3 \, \mu m$, frequency $= 40 \, \text{GHz}$, metallization $\sigma = 10,000 \, \text{S/mm}$. (Reference [22], ©IEEE 1993.)
FIGURE 9.15 A step discontinuity in the air-bridge of Type B.

FIGURE 9.16 Computed reflection and transmission coefficient as a function of the distance, $W_1 = 12.5 \, \mu m$, $S_1 = 10 \, \mu m$, $W_2 = 7 \, \mu m$, $S_2 = 21 \, \mu m$, $h = 100 \, \mu m$, $\varepsilon_r = 9.8$, $h_a = 3 \, \mu m$, $L_b = 45 \, \mu m$, $L_a = 30 \, \mu m$, $t = t_s = 3 \, \mu m$, frequency = 40 GHz, metallization $\sigma = 10,000 \, S/mm$. (Reference [22], ©IEEE 1993.)
continuity between ground planes at the junction is maintained either by bond wires or by air-bridges. Typically, the bond wires are 0.7 mil in diameter and the dimensions of the air bridges are as described in Section 9.8.

### 9.9.2 Air-Bridge T-Junction

In this circuit the CPW center strip conductors are elevated and meet to form a T-junction that resembles an air-bridge. The respective ground planes are extended to intersect and form a rectangular metal patch below the elevated strip conductors. The air-bridge T-junction is shown in Figure 9.18.
9.9.3 Mode Conversion in CPW T-Junctions

Mode conversion is a serious problem in CPW circuits with discontinuities and can result in excess insertion/return loss. A simple method to alleviate this problem is to insert air-bridges very close to the discontinuities as pointed out earlier. Here we will discuss the efficacy of this method when used in conjunction with CPW T-junctions shown in Figures 9.17 and 9.18. A good estimate of the effectiveness of this method is the amount of power converted from an incident coplanar waveguide mode at port 1 to a coupled slotline mode which emerges from port 2 eventually. This conversion can be expressed as a special transmission coefficient denoted as $S_{21(\text{CPW} \rightarrow \text{slotline})}$. Through the use of integral equation technique, the $S_{21(\text{CPW} \rightarrow \text{slotline})}$ has been computed for both types of CPW T-junctions in [24]. For the purpose of design two examples are considered for each type of T-junction in [24]. The two examples correspond to CPW with center strip conductor and slot width both of which are either wide or narrow, respectively. The computed $S_{21(\text{CPW} \rightarrow \text{slotline})}$ as a function of the frequency is shown in Figure 9.19. By comparing the $S_{21(\text{CPW} \rightarrow \text{slotline})}$ for both types of T-junction one clearly notices that the mode conversion is reduced to a greater extent in the case of an air-bridge T-junction. Further the reduction in mode conversion is up to a factor of five better for a junction formed with narrow strip and slot widths than with wide strip and slot widths.

![Figure 9.19](image_url)  
**FIGURE 9.19** Computed magnitude of transmission coefficient $S_{21(\text{CPW} \rightarrow \text{slotline})}$ as a function of frequency for both type CPW T-junctions on a substrate of thickness $h = 410 \, \mu\text{m}$ and $e_r = 12.9$, $t = 0 \, \mu\text{m}$, $t_s = 0 \, \mu\text{m}$; line geometry $S = 75 \, \mu\text{m}$, $W = 50 \, \mu\text{m}$, $Z_0 = 50 \, \Omega$, $h_s = 3 \, \mu\text{m}$ (solid line), $S = 15 \, \mu\text{m}$, $W = 10 \, \mu\text{m}$, $Z_0 = 50 \, \Omega$, $h_s = 3 \, \mu\text{m}$ (5 × $S_{21(\text{CPW} \rightarrow \text{slotline})}$) dash line). (Reference [24], ©IEEE 1993.)
9.9.4 CPW T-Junction Characteristics

The CPW T-junctions shown in Figures 9.17 and 9.18 have been modeled using integral equation technique and complex image technique in [24] and [25]. In addition a grounded CPW T-junction has been modeled using quasi-static spectral domain method in [26]. In an ideal nonsymmetric CPW T-junction if the characteristic impedance of the coplanar waveguide at port 1 and ports 2 and 3, are \( Z_{in} \) and \( Z_{out} \), respectively, then the magnitude of the reflection coefficient at port 1 ignoring junction effects is

\[
|S_{11}| = \left| \frac{Z_{out} - 2Z_{in}}{Z_{out} + 2Z_{in}} \right| \tag{9.19}
\]

and the magnitude of the transmission coefficient between ports 1 and 2 and between ports 1 and 3 is

\[
|S_{21}| = |S_{31}| = \sqrt{\frac{1 - |S_{11}|^2}{2}}. \tag{9.20}
\]

For a symmetric CPW T-junction, \( Z_{in} = Z_{out} \), and hence

\[
|S_{11}| = \frac{1}{3} \tag{9.21}
\]

and

\[
|S_{21}| = |S_{31}| = \frac{2}{3}. \tag{9.22}
\]

The numerically modeled, as well as measured, magnitude of \( S_{11} \) and \( S_{21} \) as a function of the frequency for a symmetric conventional T-junction and for an air-bridge T-junction [24] is shown in Figure 9.20(a) and (b). This figure shows that when the frequency is small, the magnitude of \( S_{11} \) and \( S_{21} \) approach the values given by Eqs. (9.21) and (9.22). However, when the frequency increases, the magnitude of \( S_{11} \) for both junctions increases due to the parasitic capacitive reactance of the bridge structures.

A lumped element equivalent circuit model for a conventional T-junction and an air-bridge T-junction are shown in Figure 9.21(a) and (b). In these models, the inductances \( L_1 \), \( L_2 \), and \( L_3 \) arise because of current flow interruptions. This effect is significant since most of the current flows along the slot edges of the CPW as shown by three-dimensional finite difference method (3D-FDM) in [27]. The capacitance \( C \) arises through additional charge accumulation due to field concentration at the corners as shown by 3D-FDM in [11]. The capacitance \( C_a \) in the case of conventional T-junction is the parasitic capacitance associated with the air-bridge. As examples, the element values determined numerically [26], [27] for both types of symmetric T-junctions are listed in Table 9.3. In the case of conventional T-junction, the
FIGURE 9.20  Computed magnitude of reflection and transmission coefficients for a symmetric structure as a function of the frequency, $S = 75 \, \mu m$, $W = 50 \, \mu m$, $Z_0 = 50 \, \Omega$, $h_a = 3 \, \mu m$, $h = 410 \, \mu m$, $\varepsilon_r = 12.9$, $t = 0 \, \mu m$, $t_a = 0 \, \mu m$: (a) Conventional T-junction; (b) air-bridge T-junction. (Reference [24], ©IEEE 1993.)

capacitance $C_a$ of the air-bridge is approximated by that of a parallel-plate capacitor.

9.10 COPLANAR WAVEGUIDE SPIRAL INDUCTOR

Lumped circuit elements such as spiral inductors have the potential to reduce the overall circuit size of MMIC balanced mixers [28] and frequency doublers
FIGURE 9.21 Lumped element equivalent circuit model: (a) Conventional T-junction; (b) air-bridge T-junction.

[29]. The size reduction in mixers and doublers is accomplished by replacing the distributed hybrid couplers and phase shifters by lumped element versions. As an example, a V-band (50.0 to 75.0 GHz) lumped 180° hybrid requires only 0.26 mm² of chip area, while a Lange coupler occupies about 3 mm² chip area that is larger by a factor of 10 [28].

A typical spiral inductor with two and a half turns in a CPW environment [29] is shown in Figure 9.22. This spiral inductor for the purpose of circuit simulation can be represented by a lumped equivalent circuit model [29] as shown in Figure 9.23. The inductance $L$ and the parasitic capacitances $C_{p1}$,

<table>
<thead>
<tr>
<th>TABLE 9.3 Computed Equivalent Circuit Element Values for Symmetric T-Junctions</th>
</tr>
</thead>
</table>

<table>
<thead>
<tr>
<th>$S$, $W$, $h$, $d$, $h_s$, $W_s$, $t_s$, $t$, $C$, $C_a$, $L_1$, $L_2$, $L_3$, $\mu$m, $\mu$m, $\mu$m, $\mu$m, $\mu$m, $\mu$m, fF, fF, pH, pH, pH</th>
</tr>
</thead>
</table>

<table>
<thead>
<tr>
<th>Air-bridge T-junction [27]</th>
</tr>
</thead>
<tbody>
<tr>
<td>75  50  400  12.9  50  2.5  —  0  0  141  —  13  74  74</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Conventional T-junction in a conductor back CPW [26]</th>
</tr>
</thead>
<tbody>
<tr>
<td>40  20  200  12.5  —  2.0  20  —  —  5.83  3.5  3.57  19.59  19.59</td>
</tr>
</tbody>
</table>
$C_p$, and $C_g$ in the model can be obtained using quasi-static finite difference method of analysis as described in [29] and [11], respectively. The resistance $R_t(f)$ in the equivalent circuit is given by [29]

$$R_t(f) = \begin{cases} 
R_{dc} + \left[ (R_t(1\text{ GHz}) \cdot f_g) - R_{dc} \right] \cdot \left( \frac{f}{f_g} \right) & \text{for } f < f_g, \\
R_t(1\text{ GHz}) \cdot \sqrt{f} & \text{for } f > f_g,
\end{cases}$$

(9.23)

where the resistance $R_t(f)$, $R_{dc}$, and $R_t(1\text{ GHz})$ are in ohms, and the frequency $f$ and $f_g$ are in GHz. The frequency $f_g$ is given by [29]

$$f_g = 39.131 \frac{(\rho/\rho_{Cu})}{t} \text{GHz},$$

(9.24)
TABLE 9.4 Geometrical Dimensions, Lumped Equivalent Circuit Model Element Values, and $\lambda/4$ Resonance Frequency of Three Rectangular Coplanar Spiral Inductors on a semi-insulating GaAs Substrate ($\varepsilon_r = 12.9$)

<table>
<thead>
<tr>
<th>Parameters</th>
<th>1</th>
<th>2</th>
<th>3</th>
</tr>
</thead>
<tbody>
<tr>
<td>Number of turns, $N$</td>
<td>2.5</td>
<td>3.5</td>
<td>4.5</td>
</tr>
<tr>
<td>Line width, $W_t$ ($\mu$m)</td>
<td>25</td>
<td>25</td>
<td>25</td>
</tr>
<tr>
<td>Gap width, $S_t$ ($\mu$m)</td>
<td>5</td>
<td>5</td>
<td>5</td>
</tr>
<tr>
<td>Inductor size, $l_x$, $l_z$ ($\mu$m)</td>
<td>185</td>
<td>240</td>
<td>300</td>
</tr>
<tr>
<td>Gap to ground, $S_m$ ($\mu$m)</td>
<td>50</td>
<td>50</td>
<td>50</td>
</tr>
<tr>
<td>Gap to ground, $S_g$ ($\mu$m)</td>
<td>50</td>
<td>50</td>
<td>50</td>
</tr>
<tr>
<td>Turn length $l_{\text{turn}}$ (mm)</td>
<td>1.245</td>
<td>2.055</td>
<td>3.155</td>
</tr>
</tbody>
</table>

Model parameters

| $L$ (nH) | 0.7013 | 1.455 | 2.813 |
| $C_{p1}$ (fF) | 41.97 | 60.72 | 81.34 |
| $C_{p2}$ (fF) | 19.03 | 23.36 | 29.65 |
| $C_e$ (fF) | 21.38 | 22.16 | 32.67 |
| $R_t$ (1 GHz) ($\Omega$) | 0.334 | 0.563 | 0.838 |
| $R_{dc}$ ($\Omega$) | 0.434 | 0.716 | 1.110 |
| $f(\lambda/4)$ (GHz) | 30    | 17    | 12    |

Source: From Reference [29], ©IEEE 1993.

where

$\rho = $ resistivity per unit length

$\rho_{\text{Cu}} = $ resistivity of copper

$t = $ metallization thickness in $\mu$m.

In Table 9.4 the physical parameters as well as the lumped equivalent circuit model element values for spiral inductors with different number of turns [29] are presented as examples. One notices from this table that as the number of turns increases, the inductance $L$ increases. In Figure 9.24 the measured and simulated transmission coefficient $S_{21}$ for the spiral inductors [29] in the above table are presented. It is observed first that at a fixed frequency, as the number of turns increases, the $S_{21}$ decreases. Second, there is good agreement between measured and simulated $S_{21}$. Measurements show that for an inductor on a GaAs substrate with $W_t = 3 \mu$m, $S_t = 5 \mu$m and $N = 7.5$, the $L$ is about 5.16 nH. When $N$ is increased to 14.5, the $L$ increases to 28 nH [43].

9.11 COPLANAR WAVEGUIDE CAPACITORS

Coplanar waveguide filter circuits, lumped hybrid couplers, dc blocking circuits, tuning elements in impedance matching network, and RF bypass circuits
FIGURE 9.24 Calculated and measured transmission coefficients of coplanar spiral inductors: (a) Magnitude; (b) phase. (Reference [29], ©IEEE 1993.)

are a few examples that require capacitors. These capacitors are of two types, interdigital and metal-insulator-metal (MIM). In this section the construction, the equivalent circuit models, and the numerically simulated results for both types of capacitors are presented.

9.11.1 Interdigital Capacitor

In Figure 9.25 the circuit layout for a typical interdigital capacitor [30] having five fingers is shown. The air-bridges at the two ends of the circuit are of Type B as explained in Section 9.8.2, and they are required for the suppression of the parasitic coupled slotline mode. The interdigital capacitor for the purpose of
circuit simulation can be represented by a $\pi$-equivalent circuit model shown in the inset in Figure 9.25. In this model, the series capacitance $C_s$ is the desired capacitance, while the shunt capacitances $C_{p1}$ and $C_{p2}$ are the parasitic capacitances between the interdigital structure and the CPW ground planes. The $C_s$, $C_{p1}$, and $C_{p2}$ can be calculated using three-dimensional finite difference method as explained in [11], [30]. The calculated as well as the measured $C_s$, $C_{p1}$, and $C_{p2}$ for several interdigital capacitors as a function of the number of fingers $n_f$, finger width $W_f$, finger separation $S_f$, finger length $L_f$, and substrate parameters are presented in Table 9.5. The experimental values in the table are

**TABLE 9.5 Measured and Modeled Coplanar Waveguide Interdigital Capacitor Values**

<table>
<thead>
<tr>
<th>$\varepsilon_r$</th>
<th>$h$, $\mu$m</th>
<th>$t$, $\mu$m</th>
<th>$n_f$</th>
<th>$W_f$, $\mu$m</th>
<th>$S_f$, $\mu$m</th>
<th>$L_f$, $\mu$m</th>
<th>$C_{p1}$ (fF)</th>
<th>Calculated</th>
<th>Measured</th>
<th>$C_{p2}$ (fF)</th>
<th>Calculated</th>
<th>Measured</th>
<th>$C_s$ (fF)</th>
<th>Calculated</th>
<th>Measured</th>
</tr>
</thead>
<tbody>
<tr>
<td>12.9</td>
<td>400</td>
<td>3</td>
<td>4</td>
<td>17</td>
<td>3</td>
<td>100</td>
<td>9.65</td>
<td>11</td>
<td></td>
<td>9.65</td>
<td>11</td>
<td></td>
<td>40.1</td>
<td>41</td>
<td></td>
</tr>
<tr>
<td>12.9</td>
<td>400</td>
<td>3</td>
<td>10</td>
<td>12</td>
<td>2</td>
<td>100</td>
<td>9.9</td>
<td>11</td>
<td></td>
<td>9.9</td>
<td>11</td>
<td></td>
<td>113.3</td>
<td>116</td>
<td></td>
</tr>
<tr>
<td>12.9</td>
<td>400</td>
<td>3</td>
<td>4</td>
<td>17</td>
<td>3</td>
<td>200</td>
<td>19.2</td>
<td>20</td>
<td></td>
<td>19.2</td>
<td>20</td>
<td></td>
<td>73</td>
<td>76</td>
<td></td>
</tr>
<tr>
<td>9.8</td>
<td>635</td>
<td>5</td>
<td>5</td>
<td>38</td>
<td>25</td>
<td>200</td>
<td>22.94</td>
<td>23</td>
<td></td>
<td>10.78</td>
<td>11</td>
<td></td>
<td>55</td>
<td>56</td>
<td></td>
</tr>
<tr>
<td>9.8</td>
<td>635</td>
<td>5</td>
<td>7</td>
<td>38</td>
<td>25</td>
<td>200</td>
<td>21.78</td>
<td>22</td>
<td></td>
<td>11.64</td>
<td>12</td>
<td></td>
<td>85</td>
<td>86</td>
<td></td>
</tr>
</tbody>
</table>

*Source: From Reference [11], ©IEEE 1990.*
FIGURE 9.26 Calculated and measured reflection and transmission coefficient of coplanar waveguide interdigital capacitors, ε_r = 12.9, h = 400 µm, L_f = 100 µm. Case 1: n_f = 4, W_f = 17 µm, S_f = 3 µm; case 2: n_f = 10, W_f = 12 µm, S_f = 2 µm. (a) Magnitude; (b) phase. (Reference [11], ©IEEE 1990.)

obtained from the measured scattering parameters. This step is carried out by a software routine which optimizing the π-equivalent circuit model element values till a good fit is established between the calculated and measured scattering parameters. Figure 9.26(a) and (b), presents examples of the calculated and measured magnitude and phase of the reflection and transmission coefficient for capacitors in Table 9.5 with the smallest and largest C_s values [11]. It is important to note that the capacitances C_{p1} and C_{p2} do not depend on the size and the number of fingers. This is due to the fact that the location of the CPW ground planes can be varied to minimize their effect. As a result it is possible to realize large values of C_s without increases C_{p1} and C_{p2}. In
practice, this is accomplished by increasing the number of fingers as well as the distance of separation between the interdigitated structure and the CPW ground planes.

9.11.2 Series Metal-Insulator-Metal Capacitor

The circuit layout of a series metal-insulator-metal (MIM) capacitor [30] is shown in Figure 9.27. The coplanar waveguide (CPW) center strip conductor and slot widths are indicated as $S$ and $W$, respectively. The capacitor is considered to be lumped and appears as a series element in the center strip conductor of the CPW. The inset in Figure 9.27 shows the cross section of the capacitor. In the cross section the thickness of the top and bottom electrodes are indicated as $t_{\text{top}}$ and $t_{\text{bot}}$, respectively. Further the electrodes are shown separated by a thin dielectric film of thickness $t_c$ and dielectric constant $\varepsilon_{\text{rc}}$. In most cases, the width $S_{\text{top}}$ and $S_{\text{bot}}$ are identical and same as $S$. Further for tight coupling, the electrodes overlap each other, and the overlap length $L_c$ can take a value anywhere from 0.5 $S$ to 4.0 $S$ [30].

The lumped element equivalent circuit model for the series MIM capacitor is shown in Figure 9.28. As a typical example consider a series MIM capacitor with the following parameters: $S = 100 \mu m$, $W = 75 \mu m$, $h = 450 \mu m$, $\varepsilon_r = 12.9$, $Z_{0(\text{CPW})} = 50 \Omega$, $t_c = 0.2 \mu m$, $t_{\text{top}} = 3.0 \mu m$, $t_{\text{bot}} = 0.48 \mu m$, $\varepsilon_{\text{rc}} = 7.45$, and $L_c = 300 \mu m$. For this example the series capacitance $C_s$ can be calculated using the well-known parallel-plate capacitor formula as follows:

$$C_s = \frac{\varepsilon_0 \varepsilon_{\text{rc}} SL_c}{t_c}.$$  (9.25)
By substituting the parameters, it is found that $C_s$ is about 9.9 pF. The capacitance $C_s$ is the parasitic capacitance between the open end of the top electrode and the center strip conductor below the dielectric film. This element is independent of the overlap length $L_c$ and is dependent on the electrode width and thickness as explained in Section 9.5. The $C_s$ computed for the example above has a value small compared to $C_s$ and is about 0.18 fF [30]. The parasitic resistance and inductance associated with the top and bottom electrodes are designated as $R_1, L_1$ and $R_2, L_2$, respectively, in the model. These are dependent on the electrode cross-sectional dimensions and length. The computed resistance and inductance are on the order of $R_1 = R_2 = 0.19 \Omega$, $L_1 = 62 \text{nH}$, and $L_2 = 61 \text{nH}$ [30]. The parasitic shunt capacitances at the two ends of the MIM capacitor are designated in the model as $C_{p1}$ and $C_{p2}$, respectively. The $C_{p1}$ and $C_{p2}$ computed for the example above have values small compared to $C_s$ and are on the order of 38 and 35 fF, respectively [30].

The numerically simulated and measured reflection and transmission coefficients [30] for the MIM capacitor in the example above are shown in Figure 9.29(a) and (b).

### 9.11.3 Parallel Metal-Insulator-Metal Capacitor

The circuit layout of the parallel MIM capacitor [30] is shown in Figure 9.30. The capacitor appears as a shunt element between the CPW center strip conductor and the ground planes. This element is very useful in circuits where a capacitor to ground is required. Moreover it results in small circuit size and consequently reduced parasitic effects. The lumped element equivalent circuit model for the capacitor is shown in Figure 9.31. As a typical example, consider a parallel MIM capacitor with the following parameters: $S = 100 \mu\text{m}$, $W = 75 \mu\text{m}$, $h = 450 \mu\text{m}$, $\varepsilon_r = 12.9$, $Z_{0(\text{CPW})} = 50 \Omega$, $t_c = 0.2 \mu\text{m}$, $t_{\text{top}} = 3.0 \mu\text{m}$, $t_{\text{bot}} = 0.48 \mu\text{m}$, $\varepsilon_{rc} = 7.45$, and $L_c = 300 \mu\text{m}$. The shunt capacitance $C_p$ in the model can be calculated using Eq. (9.25) and is about 9.9 pF [30]. The computed parasitic resistance and inductance are small and on the order of 0.1 $\Omega$ and 0.27 pH, respectively [30].
FIGURE 9.29 Calculated and measured reflection and transmission coefficient of coplanar waveguide series metal-insulation-metal capacitor, \( S = 100 \, \mu m \), \( W = 75 \, \mu m \), \( Z_{0(\text{CPW})} = 50 \, \Omega \), \( h = 450 \, \mu m \), \( \varepsilon_r = 12.9 \, \mu m \), \( L_c = 300 \, \mu m \), \( t_c = 0.2 \, \mu m \), \( \varepsilon_{rc} = 7.45 \, \mu m \), \( t_{\text{bot}} = 0.48 \, \mu m \), \( t_{\text{top}} = 3.0 \, \mu m \): (a) Reflection coefficient; (b) transmission coefficient. (Reference [30], ©Microwave Exhibitions and Publishers, 1994.)

9.11.4 Comparison between Coplanar Waveguide Interdigital and Metal-Insulator-Metal Capacitors

The capacitance range for CPW interdigital capacitors [30] and MIM capacitors [30] as a function of the geometry are given in Tables 9.6 and 9.7, respectively. These tables show that, the maximum attainable capacitance in the case of CPW interdigital and MIM capacitor is about 0.8 and 13.2 pF, respectively. Further, for a given capacitance value, the MIM capacitors are smaller in size. Last, the parasitic capacitances \( C_{p1} \) and \( C_{p2} \) are smaller in the case of MIM capacitors.
TABLE 9.6 CPW Interdigital Capacitor Geometry and Values on a GaAs Wafer

<table>
<thead>
<tr>
<th>( n_1 )</th>
<th>( W_1, \mu m )</th>
<th>( S_1, \mu m )</th>
<th>( L_1, \mu m )</th>
<th>( C_{p1}, \text{ (fF)} )</th>
<th>( C_{p2}, \text{ (fF)} )</th>
<th>( C_s, \text{ (fF)} )</th>
</tr>
</thead>
<tbody>
<tr>
<td>2</td>
<td>25</td>
<td>20</td>
<td>300</td>
<td>—</td>
<td>—</td>
<td>27</td>
</tr>
<tr>
<td>5</td>
<td>25</td>
<td>20</td>
<td>300</td>
<td>83</td>
<td>46</td>
<td>82</td>
</tr>
<tr>
<td>10</td>
<td>25</td>
<td>20</td>
<td>300</td>
<td>—</td>
<td>—</td>
<td>190</td>
</tr>
<tr>
<td>35</td>
<td>10</td>
<td>10</td>
<td>300</td>
<td>—</td>
<td>—</td>
<td>800</td>
</tr>
</tbody>
</table>

Note: \( h = 450 \mu m, \varepsilon_r = 12.9, \) Input/output CPW: \( S = 100 \mu m, W = 75 \mu m, G = 200 \mu m, Z_{(CPW)} = 50 \Omega, \) \( G = \) the ground plane width.

FIGURE 9.31 Lumped element equivalent circuit model for the parallel MIM capacitor.

9.12 COPLANAR WAVEGUIDE STUBS

Coplanar waveguide series as well as shunt stubs are essential for constructing filter circuits using capacitive and inductive elements [31]. The values of these capacitances and inductances are a function of the stub length and geometry. In this section several lumped element equivalent circuit models for CPW stubs are presented.
TABLE 9.7 CPW MIM Capacitor Geometry and Values on a GaAs Wafer

<table>
<thead>
<tr>
<th>S, μm</th>
<th>W, μm</th>
<th>Lc, μm</th>
<th>C_p1 (fF)</th>
<th>C_p2 (fF)</th>
<th>C_s (pF)</th>
</tr>
</thead>
<tbody>
<tr>
<td>100</td>
<td>75</td>
<td>300</td>
<td>38</td>
<td>35</td>
<td>9.9</td>
</tr>
<tr>
<td>100</td>
<td>75</td>
<td>50</td>
<td>—</td>
<td>—</td>
<td>1.65</td>
</tr>
<tr>
<td></td>
<td></td>
<td>400</td>
<td>—</td>
<td>—</td>
<td>13.2</td>
</tr>
<tr>
<td>50</td>
<td>37</td>
<td>25</td>
<td>—</td>
<td>—</td>
<td>0.82</td>
</tr>
<tr>
<td></td>
<td></td>
<td>200</td>
<td>—</td>
<td>—</td>
<td>6.6</td>
</tr>
<tr>
<td>25</td>
<td>20</td>
<td>12.5</td>
<td>—</td>
<td>—</td>
<td>0.41</td>
</tr>
<tr>
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<td>5</td>
<td>—</td>
<td>—</td>
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<tr>
<td>10</td>
<td>10</td>
<td>40</td>
<td>—</td>
<td>—</td>
<td>0.165</td>
</tr>
<tr>
<td>10</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>1.32</td>
</tr>
</tbody>
</table>

Note: h = 450 μm, e_r = 12.9, Z_0(CPW) = 50 Ω, e_εc = 7.45, t_c = 0.2 μm, t_bot = 0.48 μm, t_top = 3.0 μm.

9.12.1 Open-End Coplanar Waveguide Series Stub

An open circuited stub formed by an interdigital structure in the center strip conductor of a coplanar waveguide is shown in Figure 9.32, gives rise to a series capacitance with negligible parasitics when the dimensions of the circuit are very small [32]. Hence, for the purpose of circuit analysis, the stub can be accurately modeled as a series capacitance \( C_s \) as shown in the inset in Figure 9.32. Typically the length \( L \) in Figure 9.32 is less than \( 0.1λ_{g(CPW)} \) when the circuit is used as a capacitor. As a design aid the experimentally determined capacitance as a function of the length \( L \) [32] for open circuited stub on a conductor-backed GaAs wafer of thickness \( h \) is presented in Figure 9.33. The figure shows that \( C_s \) increases linearly with \( L \) but decreases as the interdigital finger width \( S \) increases. The capacitance values in this figure are obtained by computer optimization of the measured scattering parameters of the circuit across the frequency range of 1 to 26.5 GHz. Consequently the model above is valid over a wide frequency range.

The circuit in Figure 9.32 has been analyzed using space domain integral equation (SDIE) method in [33]. The computed as well as the measured reflection and transmission coefficients shows that when the transverse dimensions of the CPW as well as the finger length \( L_1 \) are very large, the simple capacitive series equivalent circuit model discussed above cannot accurately predict the circuit performance. In particular, the simple model cannot predict the bandpass resonance when the mean stub length approaches \( 0.25λ_{g(CPW)} \). Hence a new equivalent circuit model that is valid over the frequency range of 5 GHz to the first bandpass resonance is demonstrated in [33] and shown in Figure 9.34. In this model, as the finger length \( L_1 \) approaches zero, the inductances \( L_{s1}, L_{s2}, \) and \( L_{s3} \) reduce to zero and the capacitances \( C_{p1} \) becomes equal to \( C_{p2} \), resulting in a symmetric capacitive \( π \)-equivalent circuit model that is expected of a series gap as explained in Section 9.5.
FIGURE 9.32 Open end coplanar waveguide series stub. Inset shows a simple equivalent circuit model for the stub.

FIGURE 9.33 Series capacitance as a function of the length $L$ ($S = 66 \mu\text{m}$, $W = 40 \mu\text{m}$, $h = 100 \mu\text{m}$, $\varepsilon_r = 12.8$, $L_2 = 500 \mu\text{m}$, $g_1 = g_2 = W_1$). (Reference [32], ©IEEE, 1992.)
In [33] simple equations are given in terms of the finger length $L_1$ which predicts the equivalent circuit element values. These equations are strictly valid for a circuit with $S = 440 \, \mu\text{m}$, $W = 240 \, \mu\text{m}$, $S_1 = 140 \, \mu\text{m}$, $W_1 = 90 \, \mu\text{m}$, $g = 75 \, \mu\text{m}$, and finger length $L_1$ through $2500 \, \mu\text{m}$ fabricated on an alumina substrate of thickness and dielectric constant equal to $546 \, \mu\text{m}$ and $9.9$, respectively. In addition the equations take into account the presence of a supporting Duroid® substrate below of thickness and dielectric constant equal to $3175 \, \mu\text{m}$ and $2.2$, respectively. The equations are as follows [33]:

\begin{align}
C_s &= 1.01 \times 10^{-4}L_1 + 1.642 \times 10^{-2}, \\
C_{p1} &= 0.39 \times 10^{-4}L_1 + 1.765 \times 10^{-2}, \\
C_{p2} &= 0.883 \times 10^{-4}L_1 + 1.765 \times 10^{-2}, \\
L_{s1} &= 3.26 \times 10^{-4}L_1, \\
L_{s2} &= 1.22 \times 10^{-4}L_1, \\
L_{s3} &= 1.43 \times 10^{-4}L_1,
\end{align}

where the finger length $L_1$ is in $\mu\text{m}$, the inductances in nH, and the capacitances in pF.

The foregoing lumped element equivalent circuit model predicts the response up to the first resonant frequency with a 5 percent accuracy [33]. It is expected that similar linear relationships hold good for stubs with any dimensions. Thus it is enough to model two different stub lengths from which the characteristics of other lengths can be derived.

The open end series stub can also be implemented in the ground planes of a finite-width coplanar waveguide instead of the center strip conductor as demonstrated in [34]. The results indicate that the stubs in the ground planes can be modeled as two stubs in parallel to achieve twice the capacitance value than can be achieved for an identical length stub in the center strip conductor. However, the resonant frequencies in the two cases are identical.

### 9.12.2 Short-End Coplanar Waveguide Series Stub

Most of the discussion in the previous section pertaining to the open end coplanar waveguide series stub is also relevant to the short-end coplanar
waveguide series stub, and hence many details are omitted here to avoid repetition. A short-end coplanar waveguide series stub is shown in Figure 9.35. The short-end stub can be modeled as a series combination of a resistor $R_s$ and an inductor $L_s$ [32] as shown in the inset in Figure 9.35. This model is valid when the dimensions of the circuit, including the finger length $L$, are small, typically less than $0.1\lambda_{g\text{CPW}}$. The experimentally determined $R_s$ and $L_s$ [32] are shown in Figure 9.36(a) and (b), as a function of $L$. The circuit is fabricated on a conductor backed GaAs wafer of thickness $h$ and dielectric constant $\varepsilon_r$. The figures show that both $R_s$ and $L_s$ increase with $L$ but decrease as $S_1$ increases.

Analogous to the open end coplanar waveguide stub, the simple model discussed above cannot predict the band-stop resonance when the mean stub length approaches $0.25\lambda_{g\text{CPW}}$. Hence a new equivalent circuit model that is valid over the frequency range of 5 GHz to the first band-stop resonance is demonstrated in [33] and shown in Figure 9.37. In this model, as the finger length $L$ approaches $g$, $L_{s2}$ will approach $L_{s3}$ and $C_{p1}$ will approach $C_{p2}$, resulting in a symmetric model as expected for a simple notch in the center strip conductor of the CPW. In [33] simple equations are given in terms of the finger length $L$, which predicts the equivalent circuit element values. These equations are strictly valid for a circuit with parameters same as the open end.
FIGURE 9.36 Equivalent circuit element values as a function of the length $L$ ($S = 66 \, \mu m$, $W = 40 \, \mu m$, $h = 100 \, \mu m$, $\varepsilon_r = 12.8$, $L_2 = 500 \, \mu m$, $g = W_1$): (a) Series resistance; (b) series inductance. (Reference [32], ©IEEE, 1992.)

coplanar waveguide stub. The equations are as follows [33]:

$$C_s = 1.32 \times 10^{-4}L + 3.3515 \times 10^{-2}, \quad (9.32)$$

$$C_{p1} = 1.5959 \times 10^{-2}, \quad (9.33)$$

$$C_{p2} = 1.1249 \times 10^{-4}L + 7.522 \times 10^{-3}, \quad (9.34)$$

$$L_{s1} = 1.77 \times 10^{-4}L - 8.35 \times 10^{-4}, \quad (9.35)$$

$$L_{s2} = 2.6368 \times 10^{-4}L - 6.618 \times 10^{-3}, \quad (9.36)$$

$$L_{s3} = 1.8656 \times 10^{-4}L - 8.34 \times 10^{-4}, \quad (9.37)$$

where the finger length $L$ is in $\mu m$, the inductance in $nH$, and the capacitance in $pF$. 
As a concluding remark it may be mentioned that a short-end series stub can also be implemented in the ground planes of a finite width coplanar waveguide instead of the center strip conductor as demonstrated in [34]. The results indicate that the inductance and resistance is half the value of the same stub when located in the center strip conductor.

9.12.3 Combined Short and Open End Coplanar Waveguide Series Stubs

A combined short and open end series stubs in the center strip conductor of a coplanar waveguide is shown in Figure 9.38(a). When the stub lengths and parasitics are small, this circuit gives rise to a series combination of an inductance and a capacitance [35]. Consequently maximum power transfer takes place from the input to the output port at resonance. The stub layout shown in Figure 9.38(b) can, with some imagination, be easily recognized as a parallel combination of an inductance and a capacitance [35]. In this case the input and the output ports are isolated at resonance.

9.12.4 Coplanar Waveguide Shunt Stubs

An open end coplanar waveguide shunt stub printed in the CPW ground plane is shown in Figure 9.39, and the inset shows a similar shunt stub with a short end. When the length of these stubs are small, they give rise to a shunt capacitance and a shunt inductance, respectively. These circuits have been analyzed using the space domain integral equation (SDIE) method in [36] and [37]. The results show that the computed and measured scattering parameters are in good agreement over a wide frequency range. In addition in [36] it has been demonstrated that by bending the stubs as in the above figures, the loss of power due to radiation is significantly reduced. This is because the fields radiated by the two opposing stubs partially cancel. A lumped element equivalent circuit model for the cross junction in the shunt stubs can be found in [38]. Finally, the characteristics of shunt stubs printed within the center strip conductor of a CPW are presented in [39].

9.12.5 Coplanar Waveguide Radial Line Stub

Coplanar waveguide radial line single-stub [40] and double-stub [41] resonators are shown in Figures 9.40(a) and (b). These resonators have several
applications, which include bias line filters requiring a point of virtual RF ground, mixer, and frequency multiplier circuits that require a reactance to terminate the diodes and harmonics. In general, the advantages of a radial line stub over a straight 50Ω stub are smaller resonant length, wider bandwidth, and smaller discontinuity reactance at the junction with the main line. In this section, closed form equations to predict the resonant radius, for single-stub as well as double-stub resonators are given. These equations are obtained by curve-fitting the measured data.

FIGURE 9.38 Combined short- and open end coplanar waveguide series stubs: (a) Series combination of an inductance and a capacitance; (b) parallel combination of an inductance and a capacitance.
The resonant outer radius for a coplanar waveguide and a grounded coplanar waveguide radial line single stub are, respectively, given by two equations [40]:

\[
\log(R_2) = C_1 \log(\sqrt{\varepsilon_r} f_0) + C_2 \log(h) + C_3 \log(R_1) + C_4, \quad (9.38)
\]

\[
\log(R_2) = C_5 \log(\sqrt{\varepsilon_r} f_0) + C_6 [\log(h) + \log(R_1)], \quad (9.39)
\]

where \( f_0 \) is the resonant frequency in GHz, \( R_1 \) and \( R_2 \) are the inner and outer radius of the stub in meters, and \( h \) is the substrate thickness in meters. The coefficients are \( C_1 = -1.0496, C_2 = 0.098375, C_3 = -0.1401, C_4 = -1.297, C_5 = -0.82462, \) and \( C_6 = 0.21201. \) These equations are valid for the following range of parameters:

Coplanar waveguide,

\[
\begin{aligned}
6 & \leq \varepsilon_r \leq 11.7 \\
0.254 \text{ mm} & \leq h \leq 0.635 \text{ mm} \\
\theta & = 60^\circ \\
0.114 \text{ mm} & \leq W \leq 0.234 \text{ mm} \\
0.152 \text{ mm} & \leq S \leq 0.508 \text{ mm} \\
0.092 \text{ mm} & \leq R_1 \leq 0.3 \text{ mm}
\end{aligned}
\]
FIGURE 9.40 Coplanar waveguide radial line resonators: (a) Single stub; (b) double stub.
where $\varepsilon_r$ is the substrate dielectric constant, $\theta$ is the sector angle $W$ and $S$ are the coplanar waveguide slot and strip width, respectively.

Grounded coplanar waveguide,

$$
\varepsilon_r = 2.2, \ h = 0.254 \text{ mm}, \ \theta = 60^\circ, \ W = 0.127 \text{ mm}, \ S = 0.518 \text{ mm}, \ \text{and} \ R_1 = 0.3 \text{ mm}.
$$

The closed form Equations to predict the resonant outer radius for a coplanar waveguide and a grounded coplanar waveguide radial line symmetric double stub ($R_2 = R_4$ and $\theta_1 = \theta_4$) are, respectively, given by the following two equations [41]:

$$
\log(R_2) = C_1 \log[\sqrt{\varepsilon_r f_0}] + C_2[\log(h) + \log(R_1)], \ \ (9.41)
$$

$$
\log(R_2) = C_3 \log[\sqrt{\varepsilon_r f_0}] + C_4[\log(h) + \log(R_1)], \ \ (9.42)
$$

where $f_0$ is the resonant frequency in GHz, $R_1$ and $R_2$ are the inner and outer radius of the stub in meters, and $h$ is the substrate thickness in meters. The coefficients are $C_1 = -0.89203$, $C_2 = 0.16733$, $C_3 = -0.79377$, and $C_4 = 0.20831$. The equations above are valid for the following parameters:

Coplanar waveguide,

$$
\varepsilon_r = 10.5, \ h = 0.635 \text{ mm}, \ \theta = 60^\circ, \ W = 0.234 \text{ mm},
$$

$$
S = 0.33 \text{ mm}, \ \text{and} \ R_1 = 0.191 \text{ mm}.
$$

Grounded coplanar waveguide,

$$
\varepsilon_r = 2.2, \ h = 0.254 \text{ mm}, \ \theta = 60^\circ, \ W = 0.127 \text{ mm},
$$

$$
S = 0.518 \text{ mm}, \ \text{and} \ R_1 = 0.3 \text{ mm}.
$$

The equations above are for a fixed sector angle $\theta = 60^\circ$. If the sector angle changes, then the resonant frequency also changes. These changes can be understood by considering the characteristics of the CPW radial line single stub discussed earlier. For this stub the measured resonant frequency as a function of $\theta$ for a fixed $R_2$ [40] is shown in Figure 9.41. It is observed that, the resonant frequency decreases by 20 percent as $\theta$ increases from $30^\circ$ to $90^\circ$. Note that $R_1$ does not remain constant but increases with $\theta$.

### 9.13 COPLANAR WAVEGUIDE SHUNT INDUCTOR

Metal strips across the slots of a coplanar waveguide, as shown in Figure 9.42, effectively behave as shunt inductors. An approximate method to estimate the shunt inductance is to use the well-known formula for ribbon inductors, which
FIGURE 9.41 Measured resonant frequency of coplanar waveguide radial line single stub as a function of the sector angle $\theta$ ($S = 0.33$ mm, $W = 0.234$ mm, $h = 0.635$ mm, $\varepsilon_r = 10.5$, $R_2 = 5.08$ mm).

FIGURE 9.42 Coplanar waveguide shunt inductor.
is as follows \cite{42}:

\[ L = 2W \left\{ \ln \left( \frac{2\pi W}{d} \right) - 1 + \frac{d}{\pi W} \right\} \text{nH}, \quad (9.43) \]

where \( d \) and \( W \), measured in centimeters, are the width and length of the inductor, respectively. However, the accuracy of this formula is quite poor, with error on the order of 10 percent or greater for small inductances resulting from the use of ribbons with wide width \cite{42}.

An alternative approach to obtain the effective inductance of the structure shown in Figure 9.42 is to conduct a series of experiments to measure the loaded quality factor \( Q_L \) and the transmission coefficient \( S_{21} \) of a single section resonator having variable shunt inductance values \cite{42}. These resonators are made to resonate at roughly the same frequency \( f_r \). The data gathered are then used to calculate the effective inductance \( L \) from the following relationship \cite{42}:

\[ Q_L = \frac{\pi}{4} z S_{21} \left\{ \left( \frac{Z_s}{2\pi f_r L} \right)^2 + \left( \frac{z-1}{z} \right)^2 \right\}, \quad (9.44) \]

where

- \( z = Z_0/Z_s \)
- \( Z_s = \) source and load impedance
- \( Z_0 = \) coplanar waveguide characteristic impedance.
Figure 9.43 shows an example of the measured effective inductance as a function of the strip width $d$ for a coplanar waveguide shunt inductor fabricated on a 1.5748 mm thick RT-5880 Duroid substrate ($\varepsilon_r = 2.2$).

REFERENCES


REFERENCES

287


CHAPTER 10

Coplanar Waveguide Transitions

10.1 INTRODUCTION

This chapter presents transitions between coplanar waveguide (CPW) to other microwave transmission media, such as microstrip, slotline, coplanar stripline (CPS), balanced stripline, and rectangular waveguide. Each section is devoted to a particular transmission media. Wherever possible the geometry and the measured performance characteristics of a transition are summarized in a table.

Section 10.2 describes several CPW-to-microstrip transitions. These transitions are broadly divided into two types, electromagnetically coupled and directly coupled. Section 10.3 describes two types of transitions that are compatible with CPW microwave probes. These transitions, when incorporated at the input/output ports of monolithic microwave integrated circuits (MMICs), facilitate their characterization using wafer probes. Section 10.4 describes several CPW-to-CPW transitions. These CPW lines are either on opposite sides of a dielectric substrate or on two substrates that are orthogonal to each other. This section also includes a transition from a grounded CPW to a CPW supported on a dielectric membrane. Such a transition is fabricated by micromachining a silicon wafer.

Section 10.5 presents several transitions between a CPW and a rectangular waveguide. These transitions resort to any one of the following techniques to couple power in and out: a tapered metal ridge attached to the broadwall inside the waveguide, an aperture in the waveguide wall or a metal post, or a probe that enters the waveguide through an opening.

Sections 10.6 and 10.7 present several different transitions between a CPW and a balanced transmission line, such as a slotline or a coplanar stripline (CPS). These transitions are ideally suited for applications involving printed dipole type antennas. Sections 10.8 and 10.9 present several different transitions
between a CPS and a microstrip line or a slotline. This section also includes a transition between a micro-CPS and a microstrip line. The micro-CPS is a new variant of the CPS in which the two strip conductors are located at different heights and separated by a dielectric film. Last, Section 10.10 presents a transition between a CPW and a balanced stripline.

10.2 COPLANAR WAVEGUIDE-TO-MICROSTRIP TRANSITION

10.2.1 Coplanar Waveguide-to-Microstrip Transition Using Ribbon Bond

In this transition [1] the dielectric substrate with the microstrip line is adhesive bonded to the ground plane of the coplanar waveguide (CPW) as shown in Figure 10.1. This arrangement allows the two transmission lines to share a common ground plane. Electrical continuity between open ends of the CPW center strip conductor and the microstrip line is provided by a gold ribbon. The open end shunt capacitances of the two transmission lines, together with the series inductance of the gold ribbon, form a \( \pi \)-equivalent circuit. This type of circuit has a low-pass characteristic. Hence for broad bandwidth, the shunt capacitance as well as the series inductance must be kept small. In [1] the characteristics of an experimental transition on an alumina substrate are reported. Typical dimensions of the transition are given in the caption of Figure 10.1. The maximum VSWR of this transition is less than 1.4:1 over the frequency range of 2.0 to 18.0 GHz [1]. This includes the VSWR of the coaxial-to-microstrip and the CPW-to-coaxial transitions at the input and output ports.

FIGURE 10.1 Coplanar waveguide-to-microstrip transition via bond wire/ribbon: \( h = h_1 = 0.635 \text{ mm}, \varepsilon_r = \varepsilon_{r1} = 9.6, S + 2W = 2.2 \text{ mm.} \)
10.2.2 Coplanar Waveguide-to-Microstrip Surface-to-Surface Transition via Electromagnetic Coupling

In this section the construction and characteristics of two types of transition are discussed. In the first type of transition [2], the microstrip line on a separate substrate is placed on top of the coplanar waveguide (CPW) such that the two transmission lines share a common ground plane and the two strip conductors overlap as shown in Figure 10.2(a). Coupling between the strip conductors is achieved electromagnetically and no wire or ribbon bonds are necessary. In [2] the characteristics of an experimental transition designed for 7.5 GHz operation are reported. Typical dimensions and the measured characteristics are summarized in Table 10.1. The characteristics of this transition are modeled using full-wave analysis and are shown to be in good agreement with the measured results [2]. The full-wave analysis is then used to predict the dimensions for two 35.0 GHz transitions with alumina and quartz as substrates [2], respectively. The dimensions of the 35.0 GHz transitions are also summarized in Table 10.1.

### TABLE 10.1 Coplanar Waveguide-to-Microstrip Transition with Electromagnetic Coupling between Strip Conductors

<table>
<thead>
<tr>
<th>Dimensions and Characteristics</th>
<th>Design 1</th>
<th>Design 2</th>
<th>Design 3</th>
</tr>
</thead>
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<td></td>
<td></td>
</tr>
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<td><strong>SUBSTRATE MATERIAL</strong></td>
<td>DUROID 6010.2</td>
<td>ALUMINA</td>
<td>QUARTZ</td>
</tr>
<tr>
<td>$h$ (mm)</td>
<td>0.635</td>
<td>0.127</td>
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<tr>
<td>$S$ (mm)</td>
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<td>$W$ (mm)</td>
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<td>0.3</td>
</tr>
<tr>
<td>$g$ (mm)</td>
<td>1.0</td>
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<td>0.198</td>
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<td><strong>Microstrip</strong></td>
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<td></td>
</tr>
<tr>
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<td>GaAs</td>
</tr>
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<td>$h_1$ (mm)</td>
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<td>0.1</td>
<td>0.1</td>
</tr>
<tr>
<td>$W_o$ (mm)</td>
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<td>0.24</td>
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<tr>
<td>$L$ (mm)</td>
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<td><strong>Measured characteristics</strong></td>
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</tr>
<tr>
<td>Return loss (dB)$^a$</td>
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<td>—</td>
</tr>
<tr>
<td>Bandwidth (%)</td>
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</tr>
<tr>
<td>Insertion loss (dB)$^b$</td>
<td>1.7</td>
<td>—</td>
<td>—</td>
</tr>
</tbody>
</table>

$^a$De-embedded for two back-to-back transitions.

$^b$Includes two CPW to coaxial transitions at each end and 17.0 mm of 50 Ω microstrip in between.
In the second type of transition [1], [3], the microstrip line and the CPW are fabricated on a single substrate with a common continuous strip conductor as shown in Figure 10.2(b). In contrast to the previous design, the coupling between the respective ground planes is achieved electromagnetically. In addition the ground planes of the CPW are of finite width to suppress the excitation of the parasitic parallel plate mode.
This transition is modeled either as a bandpass filter whose center frequency is determined by the length of the coupled section [1] or as a six-port network formed by three coupled microstrip lines [3]. In this section the six-port network model will be briefly described. This model, as seen from Figure 10.2(b) has port 2 and port 5 as its input and output ports. Ports 4 and 6 are terminated in an open circuit. The length of the coupled section is one-quarter of the guide wavelength in the three coupled microstrip section [4] at the center frequency $f_0$ of operation. Therefore at $f_0$ the open circuits translate to a short circuit at ports 1 and 3. In order for this six-port network to behave as an efficient coupler, the insertion loss and the return loss have to be optimized. The three coupled microstrip lines that constitute the network support three modes of propagation, namely the odd mode, the even mode, and the odd and even mode. Therefore the insertion loss and the return loss are functions of the three characteristic impedances corresponding to the above modes [56].

There are two variants of this basic structure. In the first variant the lines 1–4 and 3–6 are replaced by wideband radial stubs to enhance the bandwidth [3]. The radial stubs are shown by dotted lines in Figure 10.2(b). In the second variant, the lines 1–4 and 3–6 are replaced by metal vias [5]. The vias are shown by dotted lines in Figure 10.2(b). The characteristics of the experimental transitions are reported in [1] and [3]. Typical dimensions as well as the measured characteristics of the transitions are summarized in Table 10.2.

### 10.2.3 Coplanar Waveguide-to-Microstrip Transition via a Phase-Shifting Network

This transition [6] is illustrated in Figure 10.3. At the input it consists of a 50 Ω microstrip line that branches into three orthogonal lines. The two outer line lengths are made longer than the inner line length such that the electric fields between points $a$ and $b$ and between $a$ and $c$ are equal in magnitude but 180° out of phase. Consequently at this plane a coplanar waveguide (CPW) mode is excited and then propagates along the three strip conductors. The longer path length is taken to be about $0.79\lambda_{gm}$, where $\lambda_{gm}$ is the guide wavelength in the microstrip at the center frequency $f_0$ to compensate for the right angle bend parasitics.

The experimental transition [6] is fabricated on RT/Duroid 6010.5 of 0.254 mm thickness and $\varepsilon_r$ of 10.5. The measured 3 dB insertion loss bandwidth is approximately 40 percent at $f_0$ of 9.2 GHz. The minimum insertion loss occurs at $f_0$ and is about 0.25 dB. The transition is numerically modeled using FDTD technique, and the measured and modeled characteristics are in good agreement [6].

### 10.2.4 Coplanar Waveguide-to-Microstrip Transition via a Metal Post

In this transition [7] power is coupled from a coplanar waveguide to a microstrip line located on the opposite sides of a common ground plane that
TABLE 10.2 Coplanar Waveguide-to-Microstrip Transition with Electromagnetic Coupling between Ground Conductors

<table>
<thead>
<tr>
<th>Dimensions and Characteristics</th>
<th>Houdart and Aury Design</th>
<th>Gauthier et al. Design</th>
<th>With Straight Stubs</th>
<th>With Radial Stubs</th>
</tr>
</thead>
<tbody>
<tr>
<td>Center frequency (GHz)</td>
<td>8.0</td>
<td>14.5</td>
<td>94.0</td>
<td>94.0</td>
</tr>
</tbody>
</table>

**Coplanar waveguide**

<table>
<thead>
<tr>
<th>Substrate Material</th>
<th>ALUMINA, $\varepsilon_r = 9.6$</th>
<th>HIGH-RESISTIVITY SILICON, $\varepsilon_r = 11.7$</th>
</tr>
</thead>
<tbody>
<tr>
<td>$h$ (µm)</td>
<td>635</td>
<td>120</td>
</tr>
<tr>
<td>$S_1$ (µm)</td>
<td>420</td>
<td>30</td>
</tr>
<tr>
<td>$W_1$ (µm)</td>
<td>310</td>
<td>55</td>
</tr>
<tr>
<td>$g_1$ (µm)</td>
<td>680</td>
<td>45</td>
</tr>
<tr>
<td>$S_2$ (µm)</td>
<td>—</td>
<td>50</td>
</tr>
<tr>
<td>$W_2$ (µm)</td>
<td>—</td>
<td>45</td>
</tr>
<tr>
<td>$g_2$ (µm)</td>
<td>—</td>
<td>145</td>
</tr>
</tbody>
</table>

**Microstrip**

| $W_m$ (µm)                     | —                               | 70                                            |
| $L$ (µm)                       | 3900                            | 280                                           |
| $\theta$ (deg)                | —                               | 60                                            |

**Measured characteristics**

| Return loss (dB)               | $b \leq -15.0$                  | $b \leq -15.0$ | $\leq -17.0$ | $\leq -17.0$ |
| Return loss bandwidth (%)      | 75                              | 41             | —            | —            |
| Insertion loss (dB)            | —                               | —              | $a0.4$       | $a0.4$       |
| 3-dB insertion loss bandwidth (%) | —                               | —              | 20           | 25           |

*a*For two back transitions with 860 µm long microstrip line in between.

*b*Includes two CPW to coaxial transitions.

has a circular aperture. The transition is formed by a metal post that enters the aperture and makes contact with the strip conductors of the coplanar waveguide and the microstrip line, respectively. The transition is shown in Figure 10.4. A pair of bond wires located adjacent to the post holds the elevated coplanar waveguide ground planes and the microstrip ground plane at a common potential. This arrangement of conductors results in a conductor-backed coplanar waveguide (CBCPW). In [7] the characteristics of an experimental transition are reported. Typical dimensions of the transition are given in the caption of Figure 10.4. The measured insertion loss of the transition is
FIGURE 10.3 Coplanar waveguide-to-microstrip transition via a phase shifting network: $W = 0.23$ mm, $W_1 = 0.47$ mm, $W_2 = 0.254$ mm, $W_3 = 0.102$ mm, $l_2 = 2.72$ mm, $S_1 = 2.97$ mm, $h_1 = 3.3$ mm, $\varepsilon_r = 10.5$, substrate thickness = 0.254 mm.

less than 1.0 dB over the frequency range of 0.045 to 6.5 GHz. The insertion loss includes the losses occurring in the junction, the attenuation of the short length of CBCPW and microstrip line on either side of the junction, and the attenuation of the coaxial connectors of the test fixture. The measured return loss is less than $-10.0$ dB across the above frequency band.

10.2.5 Coplanar Waveguide-to-Microstrip Transition Using a Via-Hole Interconnect

In this transition which is shown in Figure 10.5, the coplanar waveguide (CPW) and the microstrip line are fabricated on opposite sides of a semiconductor wafer, such as semi-insulating GaAs or InP. The two lines are then interconnected by an etched and metallized via [8]. The first step in the fabrication process is the definition of the coplanar environment on the first side of the wafer with standard photolithography. The wafer is then electro-
FIGURE 10.4  Coplanar waveguide-to-microstrip transition via a metal post: $S = 1.14 \, \text{mm}$, $W = 0.25 \, \text{mm}$, $W_m = 0.76 \, \text{mm}$, $D_1 = 1.02 \, \text{mm}$, $D_2 = 2.54 \, \text{mm}$, $T_1 = 3.18 \, \text{mm}$, $\varepsilon_{r_1} = 2.2$, $T_2 = 0.25 \, \text{mm}$, $\varepsilon_{r_2} = 2.2$.

Plated with gold to a thickness at least three times the skin depth at the operating frequency; typically this is about $1.5 \, \mu\text{m}$ at Ka-band frequencies. In this design the gold thickness is $4 \, \mu\text{m}$. At this point the wafer is thinned by lapping and polishing so that the final via interconnect has a small inductance. Typically for Ka-band and W-band applications, the wafers are thinned to

FIGURE 10.5  Coplanar waveguide-to-microstrip transition using a via-hole interconnect: $h = 100 \, \mu\text{m}$, $\varepsilon_r = 12.9$, $d_1 = 55 \, \mu\text{m}$, $d_2 = 140 \, \mu\text{m}$, $t = 4 \, \mu\text{m}$.
about 100 and 50 μm, respectively. Next the via hole is patterned and etched through the substrate with a reactive ion etch process. In the final step the microstrip line is defined on the backside and is then electroplated selectively. A single via interconnect between 50 Ω lines fabricated as above on a 100 μm thick semi-insulating GaAs wafer has a measured insertion loss of 0.15 dB at Ka-band frequencies [8].

10.2.6 Coplanar Waveguide-to-Microstrip Orthogonal Transition via Direct Connection

Two types of orthogonal transitions [9] are considered in this section. In these transitions a coplanar waveguide (CPW) on an orthogonal substrate makes a direct connection with a microstrip line on a horizontal substrate either from the bottom or from the top as shown in Figure 10.6(a) and (b). The transition with connection from the bottom will be described first. In this transition the ground plane of the microstrip line has a rectangular opening to avoid shorting the coplanar waveguide. The width \( W_1 \) of the opening is set equal to \( S + 2W \), where \( S \) and \( W \) are the center strip conductor and slot width, respectively, of the CPW. The length \( L_1 \) of the opening for a given geometry and substrate material is experimentally determined to minimize insertion loss and provide good impedance match. Typically \( L_1 \) is about \( 0.025λ_{gm} \), where \( λ_{gm} \) is the guide wavelength in the microstrip line at the center frequency. The microstrip width \( W_m \) is chosen such that the characteristic impedance \( Z_{0m} = 50 Ω \). The CPW center strip conductor width \( S \) is made equal to \( W_m \) and the slot width \( W \) is chosen such that the characteristic impedance \( Z_{0(CPW)} \) is equal to 50 Ω. The CPW center strip conductor extends beyond the CPW ground plane by a distance \( L \) equal to the total thickness of the microstrip substrate and ground plane.

Next the transition with connection from the top is described. In this transition, before the two strip conductors meet, both the CPW and the microstrip line are tapered over a short length so that the characteristic impedance increases from 50 to 60 Ω. The CPW and the microstrip taper lengths \( T \) and \( T_1 \) are typically 0.045\( λ_{g(CPW)} \) and 0.055\( λ_{gm} \), respectively, where \( λ_{g(CPW)} \) and \( λ_{gm} \) are the guide wavelength in the 50 Ω CPW and microstrip at the center frequency of operation. The width \( S_1 \) of the CPW center strip conductor is chosen to be equal to the strip width \( W_2 \) of the microstrip line. The slot width \( W_1 \) of the CPW is chosen so that the \( Z_{0(CPW)} \) is 60 Ω. The CPW is terminated in an open circuit with an open end length \( L \) equal to the total thickness of the microstrip substrate and ground plane.

The experimental transitions [9] are fabricated on RT/Duroid 6006 substrate. Typical dimensions of the transitions are given in the captions of Figure 10.6(a) and (b). The de-embedded insertion loss and return loss are 0.3 dB and less than −17.0 dB across the frequency band of 2.0 to 14.0 GHz for the transition in Figure 10.6(a). The de-embedded insertion loss and return loss are 0.2 dB and less than −15.0 dB across the same frequency band for the transition in Figure 10.6(b).
FIGURE 10.6 Coplanar waveguide-to-microstrip orthogonal transition via direct contact: (a) Connection is from the bottom, \( h = h_1 = 0.63 \text{ mm} \), \( \varepsilon_r = \varepsilon_{r1} = 6.0 \), \( S = 0.93 \text{ mm} \), \( W = 0.20 \text{ mm} \), \( L = 0.65 \text{ mm} \), \( W_1 = 1.33 \text{ mm} \), \( L_1 = 0.42 \text{ mm} \), \( W_m = 0.93 \text{ mm} \); (b) connection is from the top, \( h = h_1 = 0.63 \text{ mm} \), \( \varepsilon_r = \varepsilon_{r1} = 6.0 \), \( S = 0.93 \text{ mm} \), \( W = 0.20 \text{ mm} \), \( T = 0.99 \text{ mm} \), \( L = 0.65 \text{ mm} \), \( S_1 = 0.65 \text{ mm} \), \( W_1 = 0.3 \text{ mm} \), \( W_m = 0.93 \text{ mm} \), \( T_1 = 0.99 \text{ mm} \), \( W_2 = 0.65 \text{ mm} \).
10.3 TRANSITIONS FOR COPLANAR WAVEGUIDE WAFER PROBES

10.3.1 Coplanar Waveguide Wafer Probe-to-Microstrip Transition Using a Radial Stub

A coplanar waveguide wafer probe-to-microstrip transition [10] in which the
ground continuity is established through the use of an electromagnetically
coupled microstrip radial stub is shown in Figure 10.7. In this transition the
center signal contact and the outer ground contacts of the wafer probe
establish direct connection with the microstrip line and the microstrip radial
stub on the substrate, respectively. The microstrip radial stub provides a virtual
short circuit between the ground contacts of the wafer probe and the substrate
ground plane.

For any given frequency of operation, the optimum stub length neglecting
the fringing fields along the perimeter of the stub is derived in [11]. If the stub
angle \( \theta \) is large, and the stub inner radius \( r_1 \) is small compared to the
wavelength of operation, the optimum stub length \( L \) is given by [11]

\[
L \approx \frac{\lambda_0}{2\pi\sqrt{\varepsilon_r}},
\]

(10.1)

where \( \lambda_0 \) is the free space wavelength and \( \varepsilon_r \) is the substrate relative permit-
tivity. The stub length is optimum for the following two reasons: First, for this
length the stub impedance is the lowest hence the radial stub is close to being
a virtual short circuit. Second, the stub impedance is also insensitive to the
substrate thickness, which is a desirable feature when making measurements
on substrates of different thicknesses.

![Diagram of the coplanar probe-to-microstrip transition using a radial stub.](image)

**FIGURE 10.7** Coplanar probe-to-microstrip transition using a radial stub.
Quite often in practice measurements are made over a band of frequencies, in which case it is necessary to determine the maximum frequency of the stub operation. In general, as the frequency of operation increases, the stub electrical length increases and approaches approximately half a wavelength in the dielectric. At this frequency the radial stub and the substrate ground plane are decoupled, and the radial stub behaves as an open circuit with a large impedance. This condition therefore sets the upper limit of the operating frequency. The stub reactance becomes infinite when

$$L \approx \frac{3.832\lambda_0}{2\pi\sqrt{\varepsilon_r}}.$$  \hspace{1cm} (10.2)

For example, a coplanar waveguide wafer probe-to-microstrip transition for optimum operation at 10.6 GHz with a maximum operating frequency of 40.0 GHz has the following typical dimensions as determined from Eqs. (10.1) and (10.2): stub length $L = 1250 \mu$m, inner radius $r_1 = 125 \mu$m, outer radius $r_2 = 1375 \mu$m, and stub angle $\theta = 180^\circ$. The substrate is a semi-insulating GaAs of thickness $h = 92 \mu$m and $\varepsilon_r = 12.9$.

### 10.3.2 Coplanar Waveguide Wafer Probe-to-Microstrip Transition Using Metal Vias

This transition [12] is shown in Figure 10.8. In this transition the center signal contact and the outer ground contacts of the wafer probe establish direct connection with the microstrip line and pads on the substrate, respectively. The pads are connected by metal vias to the substrate ground plane. The disadvantage of this approach is that the fabrication is more complicated than the transition discussed in Section 10.3.1. Typical dimensions for a transition which is good through 26.5 GHz are included in the caption of Figure 10.8.

**FIGURE 10.8** Coplanar probe-to-microstrip transition using metal vias: $h = 100 \ \mu$m, $\varepsilon_r = 12.9$, $A = 250 \ \mu$m, $B = 200 \ \mu$m, $C = 200 \ \mu$m, $D = 100 \ \mu$m, $W = 75 \ \mu$m.
10.4 TRANSITIONS BETWEEN COPLANAR WAVEGUIDES

10.4.1 Grounded Coplanar Waveguide-to-Microshield Coplanar Line

In a microshield coplanar line the center strip conductor and the upper ground planes are supported by a very thin dielectric membrane. This results in a line that is very fragile and therefore cannot withstand repeated probe contact pressure during characterization. To alleviate this problem, the probe contact pads are designed as a grounded coplanar waveguide (GCPW).

Therefore a transition from GCPW-to-microshield coplanar line is necessary. One such transition design [13] is shown in Figure 10.9. The transition is fabricated on a high resistivity silicon wafer with resistivity greater than 2000 Ω-cm. The membrane is about 1.5 μm thick and is a tri-layer composite of SiO₂/Si₃N₄/SiO₂ with typical thickness of 7000 Å/3000Å/4000 Å, respectively.

The dielectric constant of the oxide is 3.9 and that of the nitride is 7.5. To minimize power leakage due to surface waves in the GCPW section of the transition, the length is kept small typically about λₐ/10 to λₐ/8, where λₐ is the guide wavelength. Further, to suppress leaky modes, metalized cavities are integrated in the back of the substrate and located on either side in close proximity to the probe contact pads. These metalized cavities short out the electric field setup between the top and bottom ground planes by the leaky

![Figure 10.9](image)

**FIGURE 10.9** Grounded coplanar waveguide-to-microshield line: h = 355 μm, t = 1.2 μm, εᵣ = 11.7. Grounded CPW: strip width = 50 μm, slot width = 125 μm, Z₀ = 73 Ω; microshield line: strip width = 250 μm, slot width = 25 μm, Z₀ = 75 Ω, cavity width = 1800 μm.
modes. Last to maintain CPW-like mode of propagation, the slot width to substrate thickness ratio is kept small. In [13] the characteristics of an experimental GCPW-to-microshield coplanar line transition are reported. Typical dimensions of the transition are summarized in the caption of Figure 10.9. The measured effective dielectric constant of the microshield line is 1.15. The measured return loss of two back-to-back transition over the frequency range of 10.0 to 40.0 GHz is less than $-18.0 \text{ dB}$.

The transition above is fabricated on a high-resistivity silicon wafer. It is also possible to fabricate similar transition on a GaAs wafer. In [14] the microwave performance of a coplanar waveguide (CPW) transition supported on a $\text{Si}_3\text{N}_4$ or a polyimide film ($\varepsilon_r = 2.9$) that extends across a cavity micromachined from a semi-insulating GaAs substrate is demonstrated.

### 10.4.2 Vertical Fed-through Interconnect between Coplanar Waveguides with Finite-Width Ground Planes

A schematic illustrating two back-to-back vertical interconnects [15] between coplanar waveguides with finite-width ground planes (FW-CPW) on opposite sides of a dielectric substrate is shown in Figure 10.10. In this circuit the width of the CPW ground planes are twice the center strip conductor width. The diameters of the metal-filled vias are about the same as the center strip conductor width which is 0.254 mm. These features result in a very compact circuit. The circuit is fabricated using a low-temperature co-firing ceramic (LTCC) tape for the dielectric substrate and a screen-printing technique for the

![Figure 10.10](image)

**FIGURE 10.10** Vertical fed through interconnect between coplanar waveguides with finite width ground planes (FW-CPW): $h = 0.286$ mm, $\varepsilon_r = 5.9$, $S = 0.31$ mm, $W = 0.1$ mm, $g = 0.61$ mm.
10.4.3 Orthogonal Transition between Coplanar Waveguides

An orthogonal transition [16] between two coplanar waveguides (CPWs) is shown in Figure 10.11. In this transition continuity between the two CPWs is established by three metal pins. In the horizontal CPW three holes are provided to receive the pins. In addition to facilitate solder connection a circular island is provided in the center strip conductor. Further, for good impedance matching, the CPW beyond the island is terminated in a short-circuited stub. The length $L_s$ of the short-circuited stub, the diameter $D$ of the pin, and radius $R_1$ and $R_2$ of the island and the surrounding slot region, respectively, are experimentally optimized to obtain the best insertion loss and return loss characteristics. In [16] the characteristics of an experimental

![Diagram of orthogonal transition between coplanar waveguides](image)

**FIGURE 10.11** Orthogonal transitions between coplanar waveguides: $h = 0.0508$ cm, $\varepsilon_r = 2.22$, $R_1 = 0.043\lambda_g$, $R_2 = 0.063\lambda_g$, $D = 0.024$ cm, $L_s = 0.2\lambda_g$, where $\lambda_g$ is the guide wavelength in the CPW at $f_0 = 18.0$ GHz.
transition are reported. The dimensions $L$, $D$, $R_1$, and $R_2$ are given in the caption of Figure 10.11.

The measured insertion loss and return loss of the transition is 1.7 and $-20.0 \text{ dB}$, respectively, at the center frequency $f_0$ of 18.0 GHz. The measured insertion loss includes the losses occurring at the interconnection, the losses in the 25.4 mm length of CPW on either side of the interconnect and the losses in the two coaxial connectors used at the measurement ports. The bandwidth over which the return loss is less than $-10.0 \text{ dB}$ is about 8 percent at $f_0 = 18.0 \text{ GHz}$. This transition has potential applications in the construction of linearly tapered slot antenna arrays [16].

10.4.4 Electromagnetically Coupled Transition between Stacked Coplanar Waveguides

In this transition coplanar waveguides on two separate substrates are stacked one on top of another and are proximity coupled [17]. In the arrangement shown in Figure 10.12, the feed line is located on the bottom side of the feed substrate and is terminated in a modified open circuit that also forms the coupling region. The line to which power is to be coupled is located on the top

\begin{figure}[h]
\centering
\includegraphics[width=\textwidth]{fig10_12.png}
\caption{Electromagnetically coupled transition between stacked co-planar waveguides.}
\end{figure}
side of the coupled substrate and has an identical coupled region at the open end.

To analyze this transition, the coupled region is considered as a symmetric broadside coupled coplanar waveguide as shown in the inset on the left-hand side of Figure 10.12. This structure is then analyzed by considering the even and odd modes of propagation [17], as discussed in Chapter 7. The even- and odd-mode propagation parameters, such as the effective dielectric constant ($\varepsilon_{\text{eff},e}$, $\varepsilon_{\text{eff},o}$) and characteristic impedances ($Z_{0,e}$, $Z_{0,o}$), are related to the substrate parameters and the geometry of the coupled lines. Next the coupled region is represented by a two-port network as shown in the inset on the right-hand side of Figure 10.12. This two-port network is completely described in terms of its $ABCD$-parameters [18]. These $ABCD$-parameters are in turn expressed in terms of the propagation parameters as follows [18]:

$$ A = \frac{Z_{0,e} \cot \theta_e + Z_{0,o} \cot \theta_o}{Z_{0,e} \csc \theta_e - Z_{0,o} \csc \theta_o} = D, \quad (10.3) $$

$$ B = \frac{j}{2} \frac{Z_{0,e}^2 + Z_{0,o}^2 - 2Z_{0,e}Z_{0,o}(\cot \theta_e \cot \theta_o + \csc \theta_e \csc \theta_o)}{Z_{0,e} \csc \theta_e - Z_{0,o} \csc \theta_o}, \quad (10.4) $$

$$ C = \frac{2j}{Z_{0,e} \csc \theta_e - Z_{0,o} \csc \theta_o}, \quad (10.5) $$

where

$$ \theta_e = \beta_e l = \frac{2\pi}{\lambda_0} \sqrt{\varepsilon_{\text{eff},e}}, \quad (10.6) $$

$$ \theta_o = \beta_o l = \frac{2\pi}{\lambda_0} \sqrt{\varepsilon_{\text{eff},o}}. \quad (10.7) $$

By converting the $ABCD$-parameters to $S$-parameters, the reflection coefficient and the transmission coefficient can be determined. To accurately predict the center frequency, the capacitance associated with the open end of the CPW should be compensated by reducing the length $L$ of the coupled region. In [17] the characteristics of an experimental transition are reported. Typical dimensions as well as the measured characteristics of two back-to-back transitions are summarized in Table 10.3. The insertion loss and return loss of the transitions in Table 10.3 are the de-embedded values.

### 10.4.5 Electromagnetically Coupled Transition between Orthogonal Coplanar Waveguides

This transition is formed when a coplanar waveguide on a separate substrate is placed perpendicular to a coplanar waveguide on a second substrate as shown in Figure 10.13. The preliminary experimental results are reported in [19].
TABLE 10.3  Stacked and Electromagnetically Coupled Coplanar Waveguides

<table>
<thead>
<tr>
<th>Dimensions and Characteristics</th>
</tr>
</thead>
<tbody>
<tr>
<td>Center frequency, GHz</td>
</tr>
</tbody>
</table>

*Feed substrate*

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Value (mm)</th>
</tr>
</thead>
<tbody>
<tr>
<td>$\varepsilon_r$</td>
<td>10.2</td>
</tr>
<tr>
<td>$h$</td>
<td>1.27</td>
</tr>
<tr>
<td>$S_1$</td>
<td>2.4</td>
</tr>
<tr>
<td>$W$</td>
<td>3.9</td>
</tr>
<tr>
<td>$S_2$</td>
<td>4.8</td>
</tr>
<tr>
<td>$L$</td>
<td>6.3</td>
</tr>
</tbody>
</table>

*Coupled substrate*

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Value (mm)</th>
</tr>
</thead>
<tbody>
<tr>
<td>$\varepsilon_{r1}$</td>
<td>10.2</td>
</tr>
<tr>
<td>$h_1$</td>
<td>0.635</td>
</tr>
</tbody>
</table>

*Measured characteristics for two back-to-back transitions*

<table>
<thead>
<tr>
<th>Characteristic</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Return loss (dB)*</td>
<td>$\leq -20.0$</td>
</tr>
<tr>
<td>Bandwidth (%)$^b$</td>
<td>25</td>
</tr>
<tr>
<td>Insertion loss (dB)</td>
<td>0.6</td>
</tr>
</tbody>
</table>

*With 13.0 mm of coplanar waveguide in between.*

$^b$Over which the return loss is $\leq -20.0$ dB.

FIGURE 10.13  Electromagnetically coupled transition between orthogonal coplanar waveguides.
10.5 COPLANAR WAVEGUIDE-TO-RECTANGULAR WAVEGUIDE TRANSITION

10.5.1 Coplanar Waveguide-to-Ridge Waveguide In-line Transition

A coplanar waveguide (CPW)-to-ridge waveguide in-line transition [20] is shown in Figure 10.14. In this transition the center strip conductor of the CPW terminates in an abrupt open circuit, while the two ground planes on either sides extend further and meet at a short distance away from the open circuit forming an isosceles triangular slot region inbetween. The width of the triangle at the base is $S + 2W$, where $S$ and $W$ are the CPW center strip conductor and slot width, respectively. The ground plane beyond the apex of the triangle forms the lower broadwall of the rectangular waveguide. Since the slot is formed in the center of the waveguide broadwall, it does not lose power through radiation. Over the slot region a cosine tapered ridge extends from the top broadwall of the waveguide. When the waveguide and the circuit board are clamped together the ridge makes contact with the CPW center strip conductor at the open circuit. The width of the ridge is the same as the width of the CPW center strip conductor $S$ to ensure small discontinuity reactance. The ridge acts as an impedance transformer between the standard rectangular waveguide and CPW. The characteristic impedance of the waveguide and the CPW are typically few hundreds of ohms and few tens of ohms, respectively.

The electric field distribution at cross sectional planes along the transition is shown in Figure 10.15. From this figure one can easily visualize that the ridge and the nonradiating slot gradually split the electromagnetic fields of the TE$_{10}$ waveguide mode and rotate them through 90° to match the fields of the CPW.

![Coplanar waveguide-to-ridge waveguide in-line transition](image)
In [20] the characteristics of an experimental transition at K-band frequencies are reported. The CPW is fabricated on a $h = 3.175$ mm thick RT/Duroid 5880 ($\varepsilon_r = 2.2$) with single-sided copper cladding. The waveguide is a standard K-band waveguide to which a ridge with a cosine taper is attached. The cosine taper is approximately $1.5\lambda_g$ at the center frequency, where $\lambda_g$ is the guide wavelength in the standard rectangular waveguide. The longitudinal edge formed by the substrate, and the waveguide is sealed by conductive silver epoxy. The strip conductor width $S$ and the slot width $W$ of the CPW are 0.813 and 0.203 mm, respectively, yielding a characteristic impedance of about 75 $\Omega$. Measurements made over the frequency range of 18.0 to 26.5 GHz show that for two back-to-back transitions with 20.32 mm length of CPW in between, the insertion loss is $1.75 \pm 0.25$ dB. The measured return loss is less than $-11.0$ dB. A scaled version of this transition at W-band on a GaAs substrate is reported in [21]. The insertion loss per transition is in the range of 1.0 to 3.0 dB and the return loss less than $-10.0$ dB across the frequency band of 75.0 to 110.0 GHz.
10.5.2 Coplanar Waveguide-to-Trough Waveguide Transition

The cross section of a transition [22] from a 50 Ω CPW to a ridge-trough waveguide is shown in Figure 10.16. The transition has five different waveguide sections. Each section has a characteristic impedance of 50 Ω and a length of quarter wavelength. The corresponding electric field distribution along the five cross sections are shown in Figure 10.17(a) to (e). The first cross section immediately behind the CPW resembles a ridge in a trough as shown in Figure 10.17(a). The electric fields in the left and the right half of the cross section are equal and opposite, and hence they match that of the CPW. At this cross section the waveguide has a width $a_1$ and a height $b_1$, the ridge has a width $a_2$ and a gap $b_2$, and last, the trough has a width $a_3$ and a depth $b_3$. The cutoff frequency $f_c$ of the ridge-trough waveguide is expressed in terms of the inductance $L$ and capacitance $C$ as follows [22]:

$$f_c = \frac{1}{2\pi \sqrt{(L/2) C}}, \quad (10.8)$$

where

$$L = \frac{\mu(a_1 - a_3)}{2} b_1. \quad (10.9)$$

In this expression $\mu$ is permeability of the medium and

$$C = C_1 + 2(C_2 + C_3 + C_4). \quad (10.10)$$

The terms $C_1$ and $C_2$ are the electrostatic, parallel-plate capacitances of the ridge-trough waveguide and are expressed as [22]

---

![Figure 10.16](image-url)  
**FIGURE 10.16** Coplanar waveguide-to-ridge-trough waveguide transition.
FIGURE 10.17  Five different waveguide cross sections of the transition: (a) Ridge in trough; (b) ridge even with trough; (c) ridge over trough; (d) ridge overlapping trough; (e) conventional ridge waveguide.

\[ C_1 = \varepsilon \frac{a_2}{b_2}, \quad (10.11) \]
\[ C_2 = \varepsilon \frac{2(b_3 - b_2)}{a_3 - a_2}, \quad (10.12) \]

and \( \varepsilon \) is the permittivity of the medium.

The terms \( C_3 \) and \( C_4 \) represent the fringing capacitances present at the bottom corners of the ridge and the upper corners of the trough respectively. The capacitance \( C_3 \) is expressed as [22]

\[ C_3 = C_d(x), \quad (10.13) \]

where

\[ C_d(x) = \frac{\varepsilon}{\pi} \left[ \frac{x^2 + 1}{x} \cosh^{-1} \left( \frac{1 + x^2}{1 - x^2} \right) - 2 \ln \left( \frac{4x}{1 - x^2} \right) \right], \quad (10.14) \]
The capacitance $C_4$ is also expressed in terms of $C_d(x)$ as

$$C_4 = C_d(x); \quad (10.16)$$

however, $x$ is now given by

$$x = \frac{(a_3 - a_2)}{(a_1 - a_2)}. \quad (10.17)$$

From the cutoff frequency, the cutoff wavelength of the ridge-trough waveguide can be determined as follows [22]

$$\lambda_c = \frac{c}{f_c}, \quad (10.18)$$

where $c$ is the velocity of light in free space.

The characteristic impedance $Z_{0i}$ at infinite frequency for the ridge-trough waveguide shown in Figure 10.17(a) is expressed as [22]

$$Z_{0i} = \frac{120\pi}{A_1 + A_2 + A_3}, \quad (10.19)$$

where

$$A_1 = \frac{\sin \theta_3}{b_2}, \quad (10.20)$$

$$A_2 = \frac{\cos \theta_3}{\sin(\theta_1 + \theta_2)} \left[ \left( \frac{2}{a_3 - a_2} - \frac{1}{b_1} \right) \cos \theta_1 - \frac{2 \cos(\theta_1 + \theta_2)}{a_3 - a_2} + \frac{1}{b_1} \right], \quad (10.21)$$

$$A_3 = \frac{2 \cos \theta_3}{\varepsilon} \left[ C_3 + C_4 \frac{\sin \theta_1}{\sin(\theta_1 + \theta_2)} \right], \quad (10.22)$$

$$\theta_1 = \frac{\pi(a_1 - a_2)}{\lambda_c}, \quad (10.23)$$

$$\theta_2 = \frac{2\pi(b_3 - b_2)}{\lambda_c}, \quad (10.24)$$

$$\theta_4 = \frac{\pi a_2}{\lambda_c}. \quad (10.25)$$
Once the $Z_{oi}$ at infinite frequency has been calculated, the characteristic impedance $Z_0$ at a finite frequency $f$, can be determined from the relation [22]

$$Z_0 = \frac{Z_{oi}}{\sqrt{1 - (f_c/f)^2}}. \quad (10.26)$$

In the second cross section shown in Figure 10.17(b), the ridge is even with the trough. The $Z_0$ at this cross section is also determined using Eqs. (10.19) to (10.26) with $(b_3 - b_2)$ set equal to zero. In the third cross section shown in Figure 10.17(c), the ridge is over the trough. For this case also Eqs. (10.9) and (10.10) hold good. However, the constituent capacitances $C_1$ to $C_4$ take on a different form as follows [22]:

$$C_1 = \varepsilon \frac{a_3}{b_2}, \quad (10.27)$$

$$C_2 = \varepsilon \frac{a_2 - a_3}{2(b_2 - b_3)}, \quad (10.28)$$

$$C_3 = C_d(x) \quad \text{with} \quad x = \frac{(b_2 - b_3)}{b_1}, \quad (10.29)$$

$$C_4 = C_d(x) \quad \text{with} \quad x = \frac{(b_2 - b_3)}{b_2}, \quad (10.30)$$

where $C_d$ is given by Eq. (10.14). The $f_c$ is next determined from Eq. (10.8) with the new value of capacitances given by Eqs. (10.27) to (10.30).

The $Z_{oi}$ at infinite frequency for the ridge-trough waveguide shown in Figure 10.17(c) is expressed as [22]

$$Z_{oi} = \frac{120\pi}{\lambda_c b_2 \pi \{B_1 + B_2\} + B_3}, \quad (10.31)$$

where

$$B_1 = \sin \phi_3, \quad (10.32)$$

$$B_2 = \frac{b_2 \cos \phi_3}{\sin(\phi_1 + \phi_2)} \left[ \cos \phi_1 \left( \frac{1}{b_2 - b_3} - \frac{1}{b_1} \right) - \frac{\cos(\phi_1 + \phi_2)}{b_2 - b_3} + \frac{1}{b_1} \right], \quad (10.33)$$

$$B_3 = 2 \cos \frac{\phi_3}{\varepsilon} \left( C_4 + \frac{C_3 \sin \phi_1}{\sin(\phi_1 + \phi_2)} \right), \quad (10.34)$$

$$\phi_1 = \frac{\pi(a_1 - a_2)}{\lambda_c}, \quad (10.35)$$
\[ \phi_2 = \frac{\pi(a_2 - a_3)}{\lambda_c} , \]  
\[ \phi_3 = \frac{\pi a_3}{\lambda_c} , \]  
(10.36)  
(10.37)

and \( \lambda_c \) is given by Eq. (10.18).

The equations above simplify when the ridge width \( a_2 \) is the same as the trough width \( a_3 \). In this case \( a_2 - a_3 \) is zero, and hence \( \phi_2 \) is zero. Last, the \( Z_0 \) is determined from Eq. (10.26). In the fourth cross section shown in Figure 10.17(d), the ridge over laps the tough. The \( Z_0 \) at this cross section is also determined using Eqs. (10.31) to (10.37) and (10.26). In the final cross section shown in Figure 10.17(e), there is no trough, and the cross section is that of a conventional ridge waveguide. The expression for \( L \) remains the same as in Eq. (10.9), but the capacitance \( C \) is expressed as [22]

\[ C = \frac{\varepsilon a_2}{b^2} + 2C_d(x) , \]  
(10.38)

where \( C_d(x) \) is given by Eq. (10.14) with \( x = b_2/b_1 \). The cutoff frequency is calculated from Eq. (10.8). The \( Z_{0i} \) at infinite frequency is given by [23]

\[ Z_{0i} = \frac{120\pi}{D_1 + D_2} , \]  
(10.39)

where

\[ D_1 = 2 \frac{C_d(x)}{\varepsilon} \cos \psi_2 , \]  
(10.40)

\[ D_2 = \frac{\lambda_c}{\pi b_2} \left( \sin \psi_2 + \frac{b_2}{b_1} \cos \psi_2 \tan \frac{\psi_1}{2} \right) , \]  
(10.41)

\[ \psi_1 = \frac{\pi(a_1 - a_2)}{\lambda_c} , \]  
(10.42)

\[ \psi_2 = \frac{\pi a_2}{\lambda_c} . \]  
(10.43)

The \( Z_0 \) at any finite frequency is calculated from Eq. (10.26).

The conventional ridge waveguide is then matched to a standard rectangular waveguide using a seven section binomial transformer. The design of the binomial transformers are given in [24]. The characteristics of a W-band (75.0 to 110.0 GHz) CPW probe with this transition is reported in [25]. The insertion loss is less than 0.7 dB from 75.0 to 106.5 GHz, increasing to 0.8 dB at 110.0 GHz. The return loss is less than \(-15.0\) dB over the entire W-band.
10.5.3 Coplanar Waveguide-to-Rectangular Waveguide Transition with a Tapered Ridge

The coplanar waveguide (CPW)-to-rectangular waveguide transition [26] with a tapered ridge is shown in Figure 10.18. The transition consists of a very thin metal ridge located longitudinally on the bottom broadwall of a rectangular waveguide. The shape of the ridge is approximately a cosine wave or a staircase. The ridge guides the RF power to a slot cut in the top broadwall. In the slot the RF power is split into two halves and guided in the two air regions on either side of the ridge. The magnitude and direction of the electric field lines in the two air regions are equal and opposite to each other as shown in the figure. Thus the ridge and the air regions form the center strip conductor and the slots respectively of a CPW with air as a dielectric substrate. In the figure the CPW center strip conductor and the slot widths are denoted as $S$ and $W$, respectively. The thickness of the conductor is denoted as $t$. The length of the transition, which is a uniform CPW, is denoted as $L$. Typical values for these dimensions are summarized in Table 10.4.

The electric field lines at any cross section of the CPW is shown in the inset in Figure 10.18. From this inset it is easy to visualize the presence of two equipotential planes $A–A$ and $B–B$ located midway in the two slot regions. In addition a virtual magnetic wall exists midway along the center strip conductor.

![Figure 10.18: Coplanar waveguide-to-rectangular waveguide transition with a tapered ridge.](image-url)
of the CPW. Therefore the structure between the magnetic wall and the equipotential plane is isolated and modeled as a microstrip of width \( t \) and thickness \( S/2 \) supported on an air-dielectric substrate of thickness \( W/2 \) [26]. This partial structure has a characteristic impedance \( Z_0 \). The characteristic impedance of each slot which consists of two partial sections in series in therefore \( 2Z_0 \). In a CPW the two slots are in parallel and therefore the characteristic impedance of the CPW in \( Z_0 \). In [26] the characteristics of several experimental back-to-back transitions at X-band, Ka-band, and W-band frequencies are reported. These characteristics are summarized in Table 10.4.

### 10.5.4 Coplanar Waveguide-to-Rectangular Waveguide End Launcher

A coplanar waveguide (CPW)-to-rectangular waveguide end launcher [27] is schematically illustrated in Figure 10.19. In the end launcher a dielectric substrate carrying the CPW enters the rectangular waveguide through an aperture in the center of the end wall. The CPW center strip conductor extends beyond the ground planes further into the waveguide and forms an L-shaped loop. The loop couples power from the quasi-TEM CPW mode to the \( \text{TE}_{10} \) waveguide mode. The center strip conductor width \( S \) and slot width \( W \) of the CPW for a given substrate thickness \( h \) are determined so as to provide a good impedance match to a 50 \( \Omega \) coaxial connector. The waveguide height and width are standard for a given frequency band. The length, height, and width of the probe extending into the waveguide are denoted as \( L, H, W_1, \) and \( W_2 \), respectively. The length \( L \) is approximately \( \lambda_{g(\text{waveguide})}/6 \) at the center frequency \( f_0 \) of 30.75 GHz. The height \( H \) is half the substrate height. The width \( W_1 \) and \( W_2 \) are 0.4 and 0.508 mm, respectively. The end launcher operates with a return loss of better than \( -10.0 \text{ dB} \) over approximately 20 percent bandwidth centered at \( f_0 \). The measured insertion loss of the end launcher is approximately \( 1.0 \text{ dB} \) and includes the losses in the coaxial connector and in the coax-to-waveguide adapter of the test setup used in the characterization.
10.5.5 Coplanar Waveguide-to-Rectangular Waveguide Launcher with a Post

A channelized coplanar waveguide (CCPW)-to-rectangular waveguide post launcher [28] and the CCPW substrate with the coupling probe in place are schematically illustrated in Figures 10.20 and 10.21, respectively. The channel width $C$, center strip conductor width $S$, and slot width $W$ of the CCPW for a given substrate thickness $h$ are determined as explained in Chapter 2. The waveguide height, width, and broadwall thickness are denoted as $a$, $b$, and $T$, respectively, and are standard for a given frequency band. The axis of the two transmission lines are parallel; however, they can be oriented at any arbitrary angle. A metal post of diameter $d_1$ enters the waveguide through an aperture of diameter $d_2$ to form an electric probe. The length of the probe extending into the waveguide is $L_p$. The opposite end of the post is attached through the dielectric substrate to the center strip conductor of the CCPW. The waveguide and the CCPW are terminated in a fixed short circuit placed at a distance $L_w$ and $L_s$ from the center of the post, respectively.

FIGURE 10.19 Coplanar waveguide-to-rectangular waveguide end launcher: $h = 0.254$ mm, $\varepsilon_r = 2.22$, $S = 0.554$ mm, $W = 0.254$ mm, $G = 1.25$ mm.
In the experimental launcher [28], \( L_w \) and \( L_s \) are approximately \( \lambda_{g(waveguide)}/6 \) and \( \lambda_{g(CPW)}/6 \), respectively, at the center frequency. The radii of curvature \( R_1 \) and \( R_2 \) of the circular inland in the CCPW center strip conductor and the ground plane at the location of the post are approximately \( 0.7d_1 \) and \( 0.7d_1 + W \), respectively. Further the normalized diameter \( d_1/b \) and length \( L_p/a \) are equal

**FIGURE 10.20** Cutaway drawing of channelized coplanar waveguide (CCPW)-to-rectangular waveguide post launcher: \( a = 7.8994 \) mm, \( b = 15.7988 \) mm, \( C = 5.08 \) mm, \( h = 3.175 \) mm, \( d_1 = 1.3208 \) mm, \( d_2 = 5.08 \) mm, \( L_p = 5.715 \) mm, \( T = 1.016 \), \( L_w = 4.191 \) mm, \( \epsilon_r = 2.2 \).

**FIGURE 10.21** CCPW circuit board with a probe: \( S = 1.143 \) mm, \( W = 0.254 \) mm, \( L_s = 2.54 \) mm, \( R_1 = 0.889 \) mm, \( R_2 = 1.143 \) mm.
to 0.084 and 0.723, respectively. The post launcher operates over the entire Ku-band extending from 12.4 to 18.0 GHz. The measured return loss at the CCPW port is less than $-10.0$ dB, and the insertion loss between the CCPW and the waveguide ports is 1.0 dB. The insertion loss includes the losses in the coaxial connector and in the coax-to-waveguide adapter of the test setup.

10.5.6 Channelized Coplanar Waveguide-to-Rectangular Waveguide Launcher with an Aperture

A channelized coplanar waveguide (CCPW)-to-rectangular waveguide aperture launcher [28] and the CCPW substrate with an aperture in the lower ground plane are schematically illustrated in Figures 10.22 and 10.23, respectively. The lower ground plane is flush with the inner surface of the waveguide narrow wall and consequently the aperture interrupts the transverse surface currents. Thus power from the $\text{TE}_{10}$ waveguide mode is coupled to the CCPW. The aperture width $W_a$ is chosen as 0.254 mm for ease of fabrication. The aperture length is equal to the channel width $C$. The waveguide and the CCPW are terminated in a short circuit placed at a distance $L_w$ and $L_s$ from the center.

FIGURE 10.22 Cutaway drawing of channelized coplanar waveguide (CCPW)-to-rectangular waveguide aperture launcher: $a = 7.8994$ mm, $b = 15.7988$ mm, $C = 5.08$ mm, $d = 0.7874$ mm, $L = 25.4$ mm, $L_w = 11.43$ mm, $\varepsilon_r = 2.2$. 
FIGURE 10.23  CCPW circuit board with an aperture: $S = 0.6858$ mm, $W = 0.3048$ mm, $S_1 = 1.397$ mm, $W_1 = 0.254$ mm, $L_1 = 1.143$ mm, $W_2 = 0.254$ mm, $L_8 = 11.0236$ mm.

of the aperture, respectively. The length of the impedance matching taper $L_a$ is equal to $\lambda_{g_{\text{CCPW}}}/2$.

In the experimental launcher [28], $L_W$ and $L_S$ are approximately $\lambda_{g_{\text{waveguide}}}/4$ and $\lambda_{g_{\text{CCPW}}}/2$, respectively, at the center frequency. The measured return loss at the CCPW port is less than $-10.0$ dB, and the insertion loss between the CCPW port and the waveguide port is about $1.5$ dB across the frequency band of $11.0$ to $12.0$ GHz.

10.5.7  Coplanar Waveguide-to-Rectangular Waveguide Transition with a Printed Probe

A coplanar waveguide (CPW) to rectangular waveguide transition that makes use of a printed probe is shown in Figure 10.24. In this transition, the printed probe is formed by extending the CPW center strip conductor beyond the ground planes into the waveguide. The circuit board carrying the printed probe enters the waveguide through an aperture cut in the center of the broadwall parallel to the longitudinal axis. A tunable backshort is provided to maximize the power coupled from the waveguide to the CPW. In [29] the characteristics of an experimental transition fabricated on a $0.127$ mm thick alumina substrate are reported. The measured insertion loss and return loss of two back-to-back transitions over the frequency range of $43.0$ to $50.0$ GHz is less than $2.0$ dB and about $-15.0$ dB, respectively.

A CPW-to-rectangular waveguide transition can also be designed with the probe entering the waveguide through an aperture cut in the broadwall perpendicular to the waveguide longitudinal axis. However, in this kind of transition a probe in the shape of a rectangular patch is found to be very effective [30]. As in the previous example a tunable backshort is also necessary to maximize the coupling. The characteristics of an experimental transition at
X-band are reported in [30]. The CPW and the patch are fabricated on a 0.794 mm thick substrate with $\epsilon_r = 2.35$. The CPW strip width $S$ and slot width $W$ are 3 mm and 0.1 mm, respectively. The CPW characteristic impedance $Z_{(\text{CPW})}$ is 50 $\Omega$. The patch has an area of $10 \times 6$ mm and, the distance of the backshort from the patch is 5.6 mm. The measured return loss is about $-15.0$ dB over the frequency range of 9.8 to 12.4 GHz. Further it has been observed that the bandwidth of the transition is larger when the patch faces the backshort than when the patch faces the waveguide [30].

### 10.6 COPLANAR WAVEGUIDE-TO-SLOTLINE TRANSITION

In this section the design and characteristics of transitions between an unbalanced coplanar waveguide (CPW) and a balanced slotline will be presented. Transitions of this type are commonly referred to as baluns.

#### 10.6.1 Coplanar Waveguide-to-Slotline Compensated Marchand Balun or Transition

The coplanar waveguide (CPW)-to-slotline transition and its lumped element equivalent circuit model first reported by Houdart [1] are shown in Figure 10.25(a) and (b). The advantage of this transition is its uniplanar construction. In an uniplanar circuit the conductors are all on the same side of the substrate, which simplifies fabrication. This transition for the purpose of design is
FIGURE 10.25 Coplanar waveguide-to-slotline compensated Marchand balun or transition: (a) Circuit layout; (b) lumped element equivalent circuit model.

considered as a planar version of the coaxial balun reported by Marchand \[31\] and Oltman \[32\]. According to \[31\], \[32\] the coaxial balun behaves as a bandpass network. In this section we will show that the CPW-to-slotline transition operates both as a balun and as an impedance transformer.

In Figure 10.25(a) the center strip conductor width, slot width, and characteristic impedance of the input CPW are denoted as $S$, $W$, and $Z_{0(\text{CPW})}$, respectively. The center strip conductor width, slot width, open end gap width, length, and characteristic impedance of the open circuited CPW stub are denoted as $S_b$, $W_b$, $G_b$, $L_{\text{CPW}}$, and $Z_{b}$, respectively. The slot width and characteristic impedance of the output slotline are denoted as $W_s$ and $Z_{0(\text{slot})}$, respectively. The slot width, length, and characteristic impedance of the short circuited slotline stub are denoted as $W_a$, $L_{\text{slot}}$, and $Z_{a}$, respectively. To keep the design simple, the stub end effects, air-bridge, or wire bond reactances and the junction reactances are neglected. The design of the transition proceeds as follows: If $f_1$ and $f_2$ are the frequencies corresponding to the lower and upper band edges, the center frequency $f_0 = (f_1 + f_2)/2$ is first calculated. The second step involves the determination of $Z_a$. In \[32\] it is shown that the bandwidth
of the balun is a maximum when $Z_a$ is maximum. In order to maximize $Z_a$, the slot width $W_a$ has to be large. However, $W_a$ cannot be made arbitrarily large. The largest $W_a$ has to be small compared to the guide wavelength in the slotline stub at $f_2$ to avoid multi-moding. Thus an appropriate $Z_a$ is chosen. The third step involves, the determination of optimum $Z_b$. For $Z_{0(CPW)} = 50 \Omega$ and for arbitrary $Z_{0(slot)}$, the optimum $Z_b$ is given by [32]

$$Z_{b(opt)} = \left[ \frac{Z_a \tan^2 \left( \frac{\pi f_n}{2 f_0} \right)}{1 + \left( \frac{Z_a}{Z_{0(slot)}} \right)^2 \tan^2 \left( \frac{\pi f_n}{2 f_0} \right)} \right]$$

(10.44)

where $f_n$ is either $f_1$ or $f_2$. The length $L_{slot}$ and $L_{CPW}$ are quarter guide wavelength at $f_0$. Clearly, the balun also operates as an impedance transformer.

In Figure 10.25(b) the series compensating capacitive reactance $X_c$ arises from the open circuited CPW stub and at any frequency $f$ is given by the well-known relation

$$X_c = -jZ_b \cot \left( \frac{\pi f}{2 f_0} \right).$$

(10.45)

Similarly the shunt compensating reactance $X_L$ arises from the short circuited slotline stub and is given by

$$X_L = jZ_a \tan \left( \frac{\pi f}{2 f_0} \right).$$

(10.46)

In [33], [34], [35], and [36] the characteristics of several experimental transitions are reported. Typical dimensions, circuit parameters and measured characteristics of these transitions are summarized in Table 10.5. This table shows that the compensated Marchand balun or transition has a wide bandwidth.

### 10.6.2 Coplanar Waveguide-to-Slotline Transition with Radial or Circular Stub Termination

A coplanar waveguide (CPW)-to-slotline uniplanar transition with radial stub termination [35], [36], and [37] is shown in Figure 10.26(a). In this transition the slotline radial open stub radius and angle are denoted as $R_s$ and $\theta_s$, respectively. The characteristic impedance of the slotline and the CPW are denoted as $Z_{0(slot)}$ and $Z_{0(CPW)}$, respectively. In [35], [36], and [37] the characteristics of several experimental transitions are reported. Typical dimensions, circuit parameters and the measured characteristics are summarized in
Table 10.5. Since the slotline radial open stub has a wide bandwidth, the transition also has a wide bandwidth. In [36] the slotline radial stub is modeled by tandem-connected segments of piecewise uniform slotlines. Typically 10 line segments of equal length are used, but different characteristic impedance is shown to be sufficient. Based on this model the computed insertion loss agrees very well with the measured results.

Circuits containing active devices require a dc bias. For dc biasing a narrow isolating slot is etched in the ground plane near one end of the radial arc [35] as shown in Figure 10.26(a). Measurements made with and without the isolating slot indicate that the insertion loss is essentially identical in both cases indicating that the perturbation by the slot is minimum [35].

An alternate design [38], [39] for the transition is presented in Figure 10.26(b). In this design the slotline radial opens stub is replaced by a circular open stub. The characteristics of an experimental transition of this type are reported in [38]. These characteristics are summarized and compared with

<table>
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<td>9.9, 0.635</td>
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Coplanar waveguide

<table>
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<td>S (mm)</td>
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<tr>
<td>W (mm)</td>
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<td>( Z_{0\text{CPW}} ) (( \Omega ))</td>
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<td>( G_b ) (mm)</td>
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<td>( L_{\text{CPW}} ) (mm)</td>
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Slotline

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<td>( W_s ) (mm)</td>
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<td>( Z_{0\text{SLT}} ) (( \Omega ))</td>
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Measured characteristics*

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<td>( S_{11} ) (dB)</td>
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<td>( S_{21} ) (dB)</td>
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*For two back-to-back transitions.
FIGURE 10.26 Coplanar waveguide-to-slotline transition: (a) Radial stub termination and dc isolation slot; (b) circular stub termination.

those of the previous design in Table 10.6. It is observed that this design also results in low insertion loss and wide bandwidth.

In [40] a transition with a straight stub inplace of a radial or circular stub is investigated. The transition is designed for operation over the frequency range of 0.24 to 60.0 GHz. The slotline stub length is chosen as $\frac{\lambda_{g(slot)}}{4}$ at the center frequency of 35.0 GHz. The characteristics of this transition are also summarized in Table 10.6 for comparison.

10.6.3 Coplanar Waveguide-to-Slotline Double-Y Balun or Transition

The double-Y uniplanar balun [35] is based on a radial six-port junction formed by placing alternatively three balanced and three unbalanced transmission lines. These lines have equal characteristic impedances. Further the length of adjacent pair of lines are made equal and terminated in a short circuit and an open circuit, respectively.
### TABLE 10.6 Coplanar Waveguide-to-Slotline Transition

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<td>εr AND THICKNESS (mm)</td>
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<td>SILICON, 11.9, 0.33</td>
<td>10.0, 1.27</td>
</tr>
</tbody>
</table>

#### Coplanar waveguide

| S (mm)                                  | 0.5                        | 0.025                | 0.127        | 0.03          |
| W (mm)                                  | 0.25                       | 0.025                | 0.051        | 0.025         |
| Z0(CPW) (Ω)                             | 50                         | 50                   | 50           | 50            |

#### Slotline

| Ws (mm)                                 | 0.1                        | 0.025                | 0.053        | 0.025         |
| Z0(SLOT) (Ω)                            | 50                         | —                    | 50           | 50            |
| Radial stub radius, Rs (mm)             | 6.0                        | 1.0                  | —            | —             |
| Radial stub angle, θs (deg)             | 60                         | 90                   | —            | —             |
| Circular stub radius, Rc (mm)           | —                          | —                    | 1.59         | —             |
| Straight stub length (mm)               | —                          | —                    | —            | 0.815         |

#### Measured characteristics

| Frequency range (GHz)                   | 1.1–5.7              | 20.0–40.0            | 2.9–12.2     | 28.5–44.0    |
| S21 (dB) for two back-to-back transitions | *≤ 1.0              | *≤ 3.5               | *≤ 1.0       | d≤ 2.0       |
| S21 (dB)                                | —                      | ≤ –10.0              | ≤ –10.0      | ≤ –10.0      |

*With 8.0 mm of slotline in between and coaxial launchers.
*With 6.0 mm of slotline in between.
*With 8.9 mm of slotline in between and coaxial launchers.
*With slotline in between.

This type of baluns differs from the Marchand baluns in the following manner: First, the double-Y is unable to perform impedance transformation since all the lines have the same characteristic impedance. Second, the upper cutoff frequency in general is set when the line length becomes an odd multiple of \( \lambda_g/8 \), where \( \lambda_g \) is the wavelength in the transmission lines. Third, it is an all-pass network.

A double-Y balun constructed with slotline and coplanar waveguide (CPW) as transmission lines is shown in Figure 10.27(a). The bond wires across the CPW at the junction suppress the propagation of coupled slotline even mode.
To understand the operation of this balun consider the equivalent circuit model shown in Figure 10.27(b). The circuit elements $Z_1$ to $Z_6$ refer to the input impedance of the stubs and the transmission lines as seen from the junction. As a simplification the parasitics associated with the junction are all neglected in the equivalent circuit model. Assuming $Z_2 = Z_5$ and $Z_3 = Z_6$ and that all impedances are normalized to $Z_4$, that is,

$$\frac{Z_n}{Z_4} = Z'_n, \quad n = 1, 2, \ldots, 6, \quad (10.47)$$

it can be shown that the normalized input impedance at port 1 of the junction is [35]

$$Z'_{in} = \frac{1}{1 + Z_2 + Z_3} \left[ Z_2Z'_3 \frac{(1 + Z'_2)(1 + Z'_3)(Z'_2 + Z'_3)}{2 + Z'_2 + Z'_3} \right]. \quad (10.48)$$

For perfect transmission between the input CPW and the output slotline ports,
TABLE 10.7  Coplanar Waveguide-to-Slotline Double-Y Balun or Transition

<table>
<thead>
<tr>
<th>Dimensions and Characteristics</th>
<th>Reference [35]</th>
<th>Reference [41]</th>
</tr>
</thead>
<tbody>
<tr>
<td>SUBSTRATE MATERIAL</td>
<td>HIGH-RESISTIVITY</td>
<td>—</td>
</tr>
<tr>
<td>$\varepsilon_r$ AND THICKNESS (mm)</td>
<td>SILICON, 11.9, 0.33</td>
<td>9.8, 0.635</td>
</tr>
<tr>
<td></td>
<td></td>
<td>9.8, 0.635</td>
</tr>
<tr>
<td><strong>Coplanar waveguide</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>$S$ (mm)</td>
<td>—</td>
<td>0.25</td>
</tr>
<tr>
<td>$W$ (mm)</td>
<td>—</td>
<td>0.10</td>
</tr>
<tr>
<td>$Z_{0\text{(CPW)}}$ (Ω)</td>
<td>50</td>
<td>50</td>
</tr>
<tr>
<td>Stub length (mm)</td>
<td>0.415</td>
<td>1.63</td>
</tr>
<tr>
<td></td>
<td></td>
<td>0.904</td>
</tr>
<tr>
<td><strong>Slotline</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>$W_s$ (mm)</td>
<td>—</td>
<td>0.1</td>
</tr>
<tr>
<td>Stub length (mm)</td>
<td>0.39</td>
<td>1.83</td>
</tr>
<tr>
<td>$Z_{0\text{(SLT)}}$ (Ω)</td>
<td>50</td>
<td>50</td>
</tr>
<tr>
<td>Open circuit diameter (mm)</td>
<td>0.85</td>
<td>6.0</td>
</tr>
<tr>
<td></td>
<td></td>
<td>3.0</td>
</tr>
<tr>
<td><strong>Measured characteristics</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Frequency range (GHz)</td>
<td>20.0–35.0</td>
<td>1.45–8.7</td>
</tr>
<tr>
<td>$S_{11}$ (dB)</td>
<td>$^a\leq -15.0$</td>
<td>$\leq -17.0$</td>
</tr>
<tr>
<td>$S_{21}$ (dB)</td>
<td>$^a3.0–4.0$</td>
<td>1.0</td>
</tr>
</tbody>
</table>

For two back-to-back transitions.

$Z_{in}$ must equal to 1. This condition is equivalent to [35]

$$Z_2'Z_3' = 1.$$  \hspace{1cm} (10.49)

The equation above can also be expressed in terms of the reflection coefficient as [35]

$$\Gamma_2 = -\Gamma_3,$$  \hspace{1cm} (10.50)

where $\Gamma_2$ and $\Gamma_3$ are the reflection coefficients at ports 2 and 3, respectively.

In [35] and [41] the characteristics of experimental transitions fabricated on high-resistivity silicon and Duroid substrates, respectively, are reported. These characteristics are summarized in Table 10.7. The measured characteristics do not demonstrate all-pass characteristics. The reason for this is because the circular open circuit represents a good open circuit only over two to three octave frequency range.
Circuits with active devices require dc bias for operation. A provision for dc bias can be made by etching a narrow slot in the ground plane surrounding the circular open. This slot, when located diametrically opposite to the point of entry of the slotline from the junction, causes minimum perturbation to the balun characteristics [35].

10.6.4 Electromagnetically Coupled Finite-Width Coplanar Waveguide-to-Slotline Transition with Notches in the Ground Plane

An orthogonal transition [42] between a coplanar waveguide with finite-width ground planes (FW-CPW) and a slotline that are on opposite sides of a substrate is shown in Figure 10.28. The FW-CPW and the slotline are orthogonal to each other and are electromagnetically coupled. To enhance the coupling between the lines, two notches of length $L_1$ and $L_2$ and width $W$ are located in the FW-CPW ground planes above the slotline.

The dimensions of the transition are experimentally optimized for the highest return loss bandwidth. The ratio of the lengths $L_1/L_2 \approx 0.33$, and $L_2 \approx 0.25\lambda_{g(slot)}$, where $\lambda_{g(slot)}$ is the guide wavelength in the slotline at the center frequency. The width $2G$ of the ground plane is about $0.65\lambda_{g(CPW)}$, where $\lambda_{g(CPW)}$ is the guide wavelength in the FW-CPW. The CPW is terminated in a short circuit at a distance of $L_c \approx 0.4\lambda_{g(CPW)}$ from the center of the notch. The slotline is terminated in a short circuit at a distance $L_s \approx 0.25\lambda_{g(slot)}$ from the notch. A pair of bond wires on either side of the notch suppresses the parasitic coupled slotline even mode on the FW-CPW.

![Figure 10.28](image)

**FIGURE 10.28** Electromagnetically coupled finite width coplanar waveguide-to-slotline transition with notches in the ground plane: (a) Top metallization, $S = 0.0762$ cm, $W = 0.0254$ cm; (b) bottom metallization.
In [42] the return loss characteristics of an experimental transition fabricated on a 0.508 mm thick RT/Duroid 5800 ($\varepsilon_r = 2.2$) substrate are reported. The return loss is measured at the FW-CPW port with the slotline port terminated in a wideband load, such as a tapered slot antenna. The transition has a return loss of less than $-10.0$ dB over 14 percent bandwidth centered at 21.0 GHz.

### 10.6.5 Electromagnetically Coupled Finite-Width Coplanar Waveguide-to-Slotline Transition with Extended Center Strip Conductor

An in-line transition [43] between a coplanar waveguide with finite-width ground planes (FW-CPW) and a slotline that are on opposite sides of a substrate is shown in Figure 10.29. The FW-CPW and the slot line are in line and are electromagnetically coupled. The in-line construction greatly reduces the overall circuit size.

![Electromagnetically coupled grounded finite width coplanar waveguide to slotline transition with extended center strip conductor](image)

**FIGURE 10.29** Electromagnetically coupled grounded finite width coplanar waveguide to slotline transition with extended center strip conductor. Top side circuit pattern: $S = S_1 = 0.1524$ mm, $W = 0.1067$ mm, $W_1 = 0.2515$ mm, $G = 2.54$ mm, $L_m = 4.6$ mm, $L_g = 3.98$ mm, $L_c = 5.08$ mm. Bottom side circuit pattern: $L = 18.7$ mm, $L_s = 6.83$ mm, $R = 4.35$ mm, $W_s = 0.157$ mm. Substrate parameters: $h = 0.381$ mm, $\varepsilon_r = 11.7$, $\rho = 5000–10,000$ $\Omega$ cm.
The design and construction of the transition is briefly described here. At the input port the characteristic impedance \( Z_{0(\text{FW-CPW})} \) of the FW-CPW is 50 \( \Omega \), and at the open end the \( Z_{0(\text{FW-CPW})} \) is 60 \( \Omega \). This change in impedance is realized by gradually flaring the FW-CPW slots. At the open end the top ground planes of the FW-CPW are terminated in two open circuited stubs of length \( L_g \). These stubs are modeled as microstrip lines of very low characteristic impedance, typically about 10 \( \Omega \) and length about \( \lambda_{g(\text{microstrip})}/4 \), where \( \lambda_g \) is the guide wavelength at the center frequency \( f_0 \). The stubs provide a virtual short circuit between the top ground planes of the FW-CPW and the slotline. The characteristic impedance of the slotline is 70 \( \Omega \). The center strip conductor of the FW-CPW, which extends beyond the terminated ground planes, forms the transition and is modeled as a microstrip line. The characteristic impedance of this microstrip line is 65 \( \Omega \). The distances \( L_g \) and \( L_m \) are approximately \( \lambda_{g(\text{slotline})}/4 \) and \( \lambda_{g(\text{microstrip})}/4 \), respectively, at \( f_0 \). The thickness \( t \) of the gold metallization is about three times the skin depth at \( f_0 \).

In [43] the characteristics of two back-to-back transitions fabricated on a high-resistivity silicon wafer for operation at \( f_0 = 6.0 \) GHz are reported. The measured insertion loss and return loss per transition are 1.5 dB and less than –10.0 dB, respectively, over 40 percent bandwidth centered at 4.55 GHz. This insertion loss includes, the insertion loss of a 5.08 mm long FW-CPW and half the length of the slotline between which is about 9.35 mm. The shift in the center frequency from 6.0 to 4.55 GHz is caused by discontinuity effects that are not adequately accounted for in the simplified design.

Figure 10.30 shows an alternate design [44] for constructing a transition of the above type. In this design the two microstrip stubs of length \( L_g \) are eliminated, and the top and bottom ground planes are directly connected by metal-filled vias. This technique works best on a soft substrate, such as RT/Duroid 5880. The advantage of this interconnect is its compactness; a feature much desired in an array antenna feed network. In [44] the return loss characteristics of an experimental transition is reported. The return loss is measured at the FW-CPW port with the slotline port terminated in a wideband load, such as a tapered slot antenna. The transition has a return loss of less than –10.0 dB over 90 percent bandwidth centered at 20.0 GHz.

10.6.6 Air-Bridge Coupled Coplanar Waveguide-to-Slotline Transition

A uniplanar transition [43] with air-bridge coupling between a coplanar waveguide (CPW) and a slotline is shown in Figure 10.31. The design and construction of the transition is briefly described here. At the input CPW port the characteristic impedance \( Z_{0(\text{CPW})} \) is 50 \( \Omega \). The CPW transforms to a 60 \( \Omega \) line that terminates in an open circuit. The characteristic impedance of the slotline is also 60 \( \Omega \). The circular bend at the feed end of the slotline provides a smooth transition. A 25 \( \mu \)m diameter bond wire between the open end of the CPW center strip conductor and the opposite edge of the slotline functions as an air bridge and couples RF energy. The length \( L_g \) is approximately \( \lambda_{g(\text{slotline})}/4 \),
FIGURE 10.30 Electromagnetically coupled transition with ground planes connected together by metal filled vias. Top side circuit pattern: $S = 0.762$ mm, $W = 0.254$ mm, $G = 5.08$ mm, $L_m = 2.951$ mm. Bottom side circuit pattern: $L_s = 3.43$ mm, $r_1 = 2.171$ mm, $r_2 = 2.425$ mm. Substrate parameters: $h = 0.0508$ cm, $\varepsilon_r = 2.2$, $t = 17$ $\mu$m.

FIGURE 10.31 Air-bridge coupled coplanar waveguide-to-slotline transition. Circuit pattern: $S = S_1 = 0.1524$ mm, $W = 0.0838$ mm, $W_1 = 0.1524$ mm, $L = 19.77$ mm, $L_s = 6.83$ mm, $L_c = 5.08$ mm, $R = 4.35$ mm, $W_2 = 0.157$ mm. Substrate parameters: $h = 0.381$ cms, $\varepsilon_r = 11.7$, $\rho = 5000–10,000$ $\Omega$ cm.
where \( \lambda_g \) is the guide wavelength at the center frequency \( f_0 \). The thickness \( t \) of the metalization is three times the skin depth at \( f_0 \).

In [43] the characteristics of two back-to-back transitions fabricated on a high resistivity silicon wafer for operation at \( f_0 = 6.0 \) GHz are reported. The measured insertion loss and return loss per transition are 1.5 dB and less than \(-10.0\) dB, respectively, over 30 percent bandwidth centered at 6.0 GHz. The above insertion loss includes, the insertion loss of a 5.08 mm long CPW, slotline stub of length \( L_s \) and half the length of the slotline in between which is about 9.9 mm.

Figure 10.32 shows an alternate design [45] for constructing a transition of the above type. In this design, the quarter wave short circuited stub of length \( L_s \) is eliminated and instead the slotline is terminated in abrupt open circuit. Further the CPW and the slotline are orthogonal to each other. In [45] the measured characteristics of an experimental transition are reported. The measured insertion loss and return loss for two back-to-back transitions are 1.6 dB and less than \(-12.5\) dB, respectively, over the frequency band of 21.5 to 26.5 GHz. These losses include the insertion loss of 650 \( \mu \)m long slotline in between and two 1000 \( \mu \)m long CPWs at the input and output, respectively.

### 10.7 COPLANAR WAVEGUIDE-TO-COPLANAR STRIPLINE TRANSITION

In microwave circuits a transition or a balun is required to connect a balanced transmission line, such as, a coplanar stripline (CPS) to an unbalanced line, such as, a coplanar waveguide (CPW). In this section the design considerations for three types of uniplanar baluns are presented.

#### 10.7.1 Coplanar Stripline-to-Coplanar Waveguide Balun

Figure 10.33 shows a CPS to a CPW balun [46]. In this balun at the balanced end currents of equal magnitude but opposite in direction flow along the two
strip conductors. At the unbalanced end currents of equal magnitude but opposite in direction flow along the center strip conductor and the ground planes on either side. A short circuit placed between conductors 1 and 2 at the balanced end results in an open circuit quarter wavelength away at the unbalanced end, forcing all the currents to flow between conductors 2 and 3. Further conductors 1 and 3 are short circuited at the unbalanced end by a bond wire. This short circuit appears as an open circuit quarter wavelength away at the balanced end, and therefore conductor 1 is isolated from the balanced end.

This transition in addition to serving as a balun also provides impedance transformation. Since RF energy propagates between conductors 2 and 3, the characteristic impedance between these conductors determine the impedance transformation over the quarter wavelength section. In [47] the application of this transition to a CPW feed network for a dipole antenna array is demonstrated.

10.7.2 Coplanar Stripline-to-Coplanar Waveguide Balun with Slotline Radial Stub

Figure 10.34 shows a coplanar stripline (CPS)-to-coplanar waveguide (CPW) balun. In this balun one of the slots of the CPW is terminated in a broadband slotline radial open stub, while the other slot extends further to meet the CPS. In [37] the characteristics of an experimental balun are reported. The measured insertion loss and return loss of the balun are typically 1.0 dB and less than −13.0 dB, respectively, over the frequency range of 1.6 to 7.0 GHz. The balun has a bandwidth greater than two octaves.
10.7.3 Coplanar Stripline-to-Coplanar Waveguide Double-Y Balun

The double-Y junction in this balun [48] is formed by placing alternatively three coplanar striplines (CPS) and three coplanar waveguides with finite width ground planes (FW-CPW) as shown in Figure 10.35. The advantage of FW-CPW over CPW in this design is the greatly reduced parasitics. Because of small parasitics the FW-CPW terminations behave almost like ideal open and short circuits resulting in wider bandwidth. This balun is modeled as a six port network as explained in Section 10.6.3 and Eqs. (10.48) and (10.50) are also valid here. In [41] the characteristics of an experimental balun are
The geometry as well as typical measured characteristics are summarized in Table 10.8. These characteristics show that the balun has a bandwidth of several decades.

### 10.8 COPLANAR STRIPLINE-TO-MICROSTRIP TRANSITION

#### 10.8.1 Coplanar Stripline-to-Microstrip Transition with an Electromagnetically Coupled Radial Stub

Coplanar stripline (CPS)-to-microstrip transitions [49] in a back-to-back arrangement are shown in Figure 10.36. In each transition one of the CPS strip conductor is terminated in a microstrip radial stub of radius $R$ and angle $\phi$, while the other strip conductor is extended forward to form the microstrip line. The CPS strip conductor width and separation are $W$ and $S$, respectively. The width of the microstrip line is $W_m$. The resonance frequency of the radial stub
depends on the radius $R$ and angle $\phi$. At resonance, the microstrip radial stub provides a virtual RF short circuit between the CPS strip conductor and the microstrip ground plane on the opposite side of the substrate. In the CPS the electric-field lines are across the strip conductors and parallel to the substrate. In the microstrip line, the electric-field lines are normal to the substrate. Hence, to gradually rotate the electric field lines by 90°, the microstrip ground plane edge is tapered at an angle $\theta$. The electric-field lines at various cross sections along the transition are illustrated in Figure 10.37.

FIGURE 10.36 Two back-to-back coplanar stripline-to-microstrip transition. Top side circuit pattern: $W = 0.69$ mm, $S = 0.19$ mm, $R = 5.08$ mm, $\phi = 60^\circ$, $W_m = 0.19$ mm, $L_{CPS} = 6.9$ mm. Bottom side circuit pattern: $L = 7.1$ mm, $L_m = 12.7$ mm, $\theta \approx 7^\circ$. Substrate parameters: $h = 0.254$ mm, $\varepsilon_r = 10.5$.

FIGURE 10.37 Electric-field lines at various cross-sections along the transition.
In [49] the characteristics of an experimental transition fabricated on a RT/Duroid 6010 substrate are reported. The measured insertion loss and return loss for two back-to-back transitions over the frequency range of 5.1 to 6.1 GHz is 2.4 dB (max) and less than −10.0 dB, respectively. The −10.0 dB return loss bandwidth of both transitions is about 18 percent centered at 5.55 GHz. The numerical simulation of the transition carried out using FDTD technique shows good agreement between measured and modeled results [49]. In [5] and in [50] a transition from an asymmetric CPS (ACPS)-to-microstrip with radial stubs and with metal vias, respectively, is demonstrated.

**10.8.2 Uniplanar Coplanar Stripline-to-Microstrip Transition**

A uniplanar coplanar stripline (CPS) -to-microstrip back-to-back transition [51] in a balanced arrangement is shown in Figure 10.38. In this transition, a microstrip line of characteristic impedance 50 Ω is coupled to two orthogonal microstrip lines of characteristic impedance 70 Ω through a quarter-wave stepped impedance-matching transformer. The characteristic impedance of 70 Ω is chosen for ease of fabrication. In an ideal transition, the mean path length of the folded loop “a-through-b” is equal to \( 0.5 \lambda_{g(\text{microstrip})} \), where \( \lambda_{g(\text{microstrip})} \) is the guide wavelength in the microstrip of characteristic impedance 70 Ω at the center frequency \( f_0 \). In a practical transition for wideband

![Diagram of a uniplanar coplanar stripline-to-microstrip transition](image)

**FIGURE 10.38** Two back-to-back balanced uniplanar coplanar stripline-to-microstrip transition: \( W_m = 0.23 \text{ mm}, W_1 = 0.33 \text{ mm}, W_2 = W = S_2 = S = 0.1 \text{ mm}, l_1 = 4.9 \text{ mm}, l_2 = 2.8 \text{ mm}, S_1 = 2.1 \text{ mm}, h_1 = 0.54 \text{ mm}, h_2 = 1.34 \text{ mm}.\) Substrate thickness: \( h = 0.254 \text{ mm}, \varepsilon_r = 10.5.\)
operation, the right angle bend parasitic elements have to be compensated. A simple solution to this problem is to increase the mean path length of the microstrip. Hence the mean path length is chosen as $0.638\lambda_{\text{microstrip}}$. This design ensures that the phase of the signals at the input locations $a$ and $b$ to the coupled microstrip line are $180^\circ$ out of phase. The coupled microstrip lines are excited in the odd mode with the electric-field lines predominantly across the gap $S_2$. The dimensions of the gap $S_2$ is chosen such that the odd-mode characteristic impedance is $50\,\Omega$. The horizontal orientation of the electric-field lines in the coupled microstrip makes the transition to a CPS simple. The width $W$ and separation $S$ of the CPS in the experimental transition is the same as the coupled microstrip width and separation.

In [51] the measured characteristics of the transition shown in Figure 10.38 are reported. The transition is designed for operation at a center frequency $f_0 = 10.0\,\text{GHz}$. However, the measurements show that $f_0$ has shifted to $9.6\,\text{GHz}$. The measured insertion loss and return loss is about $2.0\,\text{dB}$ and less than $-10.0\,\text{dB}$, respectively, over 42 percent bandwidth centered at $9.6\,\text{GHz}$. The numerical simulation of the transition carried out using FDTD technique shows that the measured and modeled results are in good agreement [51].

### 10.8.3 Coplanar Stripline-to-Microstrip Transition

Figure 10.39 shows a coplanar stripline (CPS)-to-microstrip transition [52] in a stacked configuration. In this transition the microstrip ground plane is attached using electrically conducting epoxy to one of the strip conductors of the CPS. The connection between the remaining strip conductors is by a gold ribbon. In [52] the characteristics of an experimental transition are reported. The geometry as well as the measured characteristics of the transition are summarized in Table 10.9. The transition has a wide bandwidth.

![FIGURE 10.39 Coplanar stripline-to-microstrip transition using ribbon bond.](image)
### 10.8.4 Micro-coplanar Stripline-to-Microstrip Transition

Figure 10.40 shows a micro-coplanar stripline (MCPS)-to-microstrip transition [53] in a back-to-back arrangement. In this transition the width of the microstrip ground plane is abruptly reduced to form a symmetric parallel-plate line. The parallel-plate conductors are next flared out to form the MCPS. The cross section at three locations along the transition are shown in the inset in Figure 10.40. Section A–A, B–B, and C–C show the microstrip, the parallel-plate, and the MCPS regions, respectively. The relevant parameters of the transition are as follows: \( h_1 = 254 \mu m, \epsilon_{r1} = 10.5, \epsilon_{r2} \approx 1.0, W = 889 \mu m, W_m = 254 \mu m, \) and the characteristic impedance \( Z_{0(microstrip)} = 50 \Omega. \) In [53] the characteristics of an experimental transition are reported. The measured insertion loss and return loss are 1.0 dB and less than \(-16.0\) dB, respectively, for two back-to-back transitions over the frequency range of 0.045 to 14.0 GHz. These losses also include the loss of the test fixture. The measurements show that the transition has a broad bandwidth.

#### Table 10.9 Coplanar Stripline-to-Microstrip Transition

<table>
<thead>
<tr>
<th>Dimensions and Characteristics</th>
<th>Reference [52]</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Coplanar stripline</strong></td>
<td></td>
</tr>
<tr>
<td>Substrate thickness (( \mu m ))</td>
<td>3000</td>
</tr>
<tr>
<td>( \epsilon_r )</td>
<td>10.0</td>
</tr>
<tr>
<td>( W (\mu m) )</td>
<td>490</td>
</tr>
<tr>
<td>( S (\mu m) )</td>
<td>58</td>
</tr>
<tr>
<td>( Z_{0(CPS)} (\Omega) )</td>
<td>50</td>
</tr>
<tr>
<td><strong>Microstrip line</strong></td>
<td></td>
</tr>
<tr>
<td>Substrate thickness (( \mu m ))</td>
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</tr>
<tr>
<td>( \epsilon_r )</td>
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<tr>
<td>( W_m (\mu m) )</td>
<td>385</td>
</tr>
<tr>
<td>( Z_{0(m)} (\Omega) )</td>
<td>50</td>
</tr>
<tr>
<td><strong>Gold ribbon</strong></td>
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</tr>
<tr>
<td>Width (( \mu m ))</td>
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</tr>
<tr>
<td>Length (( \mu m ))</td>
<td>250</td>
</tr>
<tr>
<td><strong>Measured characteristics</strong></td>
<td></td>
</tr>
<tr>
<td>Frequency range (GHz)</td>
<td>dc – 18.0</td>
</tr>
<tr>
<td>( S_{11} (\text{dB}) )</td>
<td>( ^a \leq -13.0 )</td>
</tr>
</tbody>
</table>

\(^a\)For two back-to-back transitions.
FIGURE 10.40 Two back-to-back micro-coplanar stripline-to-microstrip transition.

10.9 COPLANAR STRIPLINE-TO-SLOTLINE TRANSITION

An electromagnetically coupled coplanar stripline (CPS)-to-slotline transitions [54] in a back-to-back arrangement is shown in Figure 10.41. The CPS and the slotline are on opposite sides of a dielectric substrate. To elucidate the design of the transition, the cross sections at four locations along the length are shown in Figure 10.42. The input port at section A–A is a CPS with strip

FIGURE 10.41 Two back-to-back electromagnetically coupled coplanar stripline-to-slotline transition.
FIGURE 10.42 Cross-sectional view of the transition.

FIGURE 10.43 Coplanar waveguide-to-balanced stripline transition: $S = 1.397$ mm, $W = 0.254$ mm, $W_s = 2.54$ mm, $D_1 = 1.27$ mm, $D_2 = 2.54$ mm, $h_1 = 3.175$ mm, $\varepsilon_{r1} = 2.2$, $h_2 = 1.5748$ mm, $\varepsilon_{r2} = 2.1$, $R_1 = 1.397$ mm, $R_2 = 1.651$ mm, $L = 5.969$ mm.
TABLE 10.10 Coplanar Stripline-to-Slotline Transition

<table>
<thead>
<tr>
<th>Dimensions and Characteristics</th>
<th>Reference [54]</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>SUBSTRATE</strong></td>
<td><strong>HIGH-RESISTIVITY SILICON</strong></td>
</tr>
<tr>
<td></td>
<td>( \rho \approx 2500–3300 \Omega \cdot \text{cm} )</td>
</tr>
<tr>
<td>Thickness ( D ) (mm)</td>
<td>0.295</td>
</tr>
<tr>
<td>( \varepsilon_r )</td>
<td>11.7</td>
</tr>
<tr>
<td>( t ) (( \mu \text{m} ))</td>
<td>( \approx 2.5 )</td>
</tr>
</tbody>
</table>

**Coplanar stripline**

\( W_1 \) (mm) | 0.28 |
\( S_1 \) (mm) | 0.254 |
\( W_2 \) (mm) | 0.24 |
\( S_2 \) (mm) | 0.254 |
\( L_1 \) (mm) | 6.35 |
\( L_2 \) (mm) | 3.94 |
\( R \) (mm) | 1.27 |

**Slot line**

\( W_s \) (mm) | 0.1143 |
\( L_s \) (mm) | 7.13 |
\( L_3 \) (mm) | 3.8 |

**Measured characteristics per transition**

\( f_0 \) (GHz) | 10.0 |
\( S_{11} \) (dB) | \( \leq -10.0 \) |
\( S_{21} \) (dB) | 1.45 |
Bandwidth (\%) at \( f_0 \) | 30.0 |

Conductor width \( W_1 \) and separation \( S_1 \). At section \( B–B \) the CPS overlaps the ground plane of the slotline and transforms to coupled microstrip lines of width \( W_2 \) with odd-mode excitation. The separation \( S_2 \) between the coupled microstrip lines gradually diverges beyond \( B–B \) to \( C–C \), but the strip width remains fixed at \( W_2 \). At section \( C–C \) the coupled microstrip lines are totally decoupled and behave as two independent lines. Beyond this plane the CPS is terminated in a short circuit arc of radius \( R \). Coupling between the CPS and the slotline takes place at the location where the short circuit arc crosses the slotline at right angles. The slotline has a slot of width \( W_s \). Further the slotline is terminated in a short circuit at a distance \( L_3 \), which is approximately \( \lambda_{g(slotline)}/4 \) where \( \lambda_{g(slotline)} \) is the guide wavelength in the slotline at the design frequency \( f_0 \). In \([54]\) the characteristics of an experimental transition are reported. Table 10.10 summarizes the transition performance.
10.10 COPLANAR WAVEGUIDE-TO-BALANCED STRIPLINE TRANSITION

A coplanar waveguide (CPW)-to-balanced stripline transition [55] is shown in Figure 10.43. In this transition the center strip conduction of the CPW and the stripline are electrically connected by a metal port through an aperture in the ground plane. The diameters of the aperture and the metal post are experimentally optimized to obtain the best insertion loss characteristics. The ground planes of the stripline are connected together by shorting pins to ensure both surfaces are at equipotential. Electrical continuity between the CPW and the stripline ground planes is maintained by bond wires. In [55] the characteristics of an experimental transition are reported. The measured insertion loss and return loss of the transition are less than 0.5 dB and −10.0 dB, respectively, over the frequency range of 0.045 to 3.0 GHz. This transition has applications in the feed network of patch antennas.

REFERENCES


CHAPTER 11

Directional Couplers, Hybrids, and Magic-Ts

11.1 INTRODUCTION

The design and construction of coupled line directional coupler is presented in Section 11.2 of this chapter. These couplers are realized using edge coupled coplanar waveguides (CPWs) or broadside coupled CPWs. The conventional edge coupled CPW coupler is suited for weak coupling, typically 10 or 20 dB. The broadside coupled CPW coupler is suited for tight coupling, typically, 3 dB.

The design and construction of CPW quadrature (90°) hybrid or branch-line directional coupler is presented in Section 11.3. Both the standard as well as the reduced size branch-line coupler design are discussed. The advantage of the reduced size design is that it facilitates lowering the cost of monolithic integrated circuit (MMIC) based subsystems. In addition applications involving multistage balanced MMIC amplifiers require impedance transforming branch-line couplers. The design of these couplers are also discussed.

The design and construction of a CPW 180° ring hybrid or rat race is presented in Section 11.4. The 180° ring hybrid has application in balanced mixers. The design and construction of CPW passive and active magic-T circuits are described in Sections 11.5 and 11.6, respectively. The magic-T circuits are commonly used in monopulse receivers.

11.2 COUPLED-LINE DIRECTIONAL COUPLERS

When two CPWs are brought in close proximity their electromagnetic fields interact and power is coupled from one CPW to the other. Figure 11.1 shows three examples of coupled CPW structures, the edge coupled CPW, the edge coupled grounded CPW, and the broadside coupled CPW. The propagation
FIGURE 11.1 Coupled-line configurations: (a) Edge coupled CPW; (b) edge coupled grounded CPW.

along these CPW structures is described by two normal modes, namely the even and the odd modes. In Chapter 7 the normal modes of coupled CPW were explained in detail, and wherever possible in this book analytical expressions were presented to compute the even-mode and odd-mode effective dielectric constants and characteristic impedances. These characteristics are essential for designing directional couplers.

In weakly coupled lines, the distance of separation between the two lines is large, and hence the wave propagates with a velocity approximately the same as that on a single line. In this situation the even-mode and odd-mode phase velocities are assumed to be equal \[ v_{\text{ph(even)}} = v_{\text{ph(odd)}} = v_{\text{ph}} = \frac{c}{\sqrt{\varepsilon_{\text{eff}}}}, \] (11.1)
FIGURE 11.1 Coupled-line configurations: (c) edge coupled grounded CPW with metal underpass; (d) broadside coupled CPW.
and

\[ \lambda_g = \frac{v_p}{f}, \]  

(11.2)

where

\( c = \) velocity of light in free space
\( \varepsilon_{\text{eff}} = \) effective dielectric constant
\( \lambda_g = \) guide wavelength
\( f = \) frequency.

In addition, for maximum coupling the length \( L \) of the coupled section is \( \lambda_g/4 \) [2]. The following two relations [2] also hold good:

\[ Z_0^2 = Z_{0,e}Z_{0,o} \]  

(11.3)

and

\[ K = \frac{Z_{0,e} - Z_{0,o}}{Z_{0,e} + Z_{0,o}}, \]  

(11.4)

where

\( Z_0 = \) characteristic impedance of the feed line
\( Z_{0,e} \) and \( Z_{0,o} = \) even-mode and odd-mode characteristic impedance
\( K = \) voltage coupling coefficient.

Last, it is worth mentioning that under the preceding conditions there will be no reflection at the input port of the coupler and also the coupler will have infinite directivity [2].

In the case of tightly coupled lines, the even-mode and odd-mode phase velocities are unequal [3], and so the length \( L \) of the coupled section is determined from the expression

\[ L = \frac{\pi}{\beta_e + \beta_o}, \]  

(11.5)

where \( \beta_e \) and \( \beta_o \) are the even-mode and odd-mode propagation constants. For this case the coupler will not have infinite directivity.

### 11.2.1 Edge Coupled CPW Directional Couplers

A 10 dB edge coupled CPW directional coupler for operation at 3.0 GHz is demonstrated in [1]. The schematic of the coupler is shown in Figure 11.2.
Briefly, the design of the coupler is as follows: First, from the coupling requirement of 10 dB the even-mode and odd-mode characteristic impedances are determined from Eqs. (11.3) and (11.4). These impedances turn out to be $Z_{0,e} = 69.5 \Omega$ and $Z_{0,o} = 36.0 \Omega$ [1]. The graph of the computed even-mode and odd-mode characteristic impedances as a function of the geometry suggest the following choice: the strip width $S = 0.014$ in., the slot width $W = 0.009$ in., and the distance of separation $D = 0.013$ in. [1]. The computed $v_{ph}$ for this weakly coupled lines is about 0.34 times $c$. Hence $\lambda_0$ is 1.3385 in., and the length $L$ of the coupled section is 0.334 in. [1].

The measured coupling ($P_3/P_1$) is on the order of 10.3 ± 0.7 dB over the frequency range of 1.7 to 2.5 GHz [1]. It is observed that the center frequency has shifter from 3.0 to 2.1 GHz due to discontinuity capacitance that cause a significant increase in the effective coupler length $L$. The measured return loss at any port and directivity ($P_4/P_3$) are $-28.0$ and $17.0$ dB, respectively, over this frequency range. The departure from zero reflection and infinite directivity is because of the difference in the even-mode and odd-mode phase velocities.

### 11.2.2 Edge Coupled Grounded CPW Directional Couplers

In this section the design and performance of directional couplers with weak and tight coupling are examined. An edge coupled grounded CPW directional coupler for a coupling of about 8.0 dB at a center frequency of 3.1 GHz is
TABLE 11.1  Edge Coupled Grounded CPW Directional Coupler

<table>
<thead>
<tr>
<th>Circuit parameters and measured characteristics</th>
</tr>
</thead>
<tbody>
<tr>
<td>Substrate (alumina), $\varepsilon_r$</td>
</tr>
<tr>
<td>Thickness, mm</td>
</tr>
<tr>
<td>Metalization (gold) thickness, $t$, $\mu$m</td>
</tr>
<tr>
<td>Coupled section</td>
</tr>
<tr>
<td>GCPW center strip width, $S$, mm</td>
</tr>
<tr>
<td>GCPW slot width, $W$, mm</td>
</tr>
<tr>
<td>GCPW distance of separation, $D$, mm</td>
</tr>
<tr>
<td>Feed line</td>
</tr>
<tr>
<td>GCPW center strip width, mm</td>
</tr>
<tr>
<td>GCPW slot width, mm</td>
</tr>
<tr>
<td>Measured characteristics</td>
</tr>
<tr>
<td>Center frequency, GHz</td>
</tr>
<tr>
<td>Bandwidth, GHz</td>
</tr>
<tr>
<td>Coupling, dB</td>
</tr>
<tr>
<td>Directivity, dB</td>
</tr>
</tbody>
</table>

The design makes use of Eqs. (11.1) to (11.4) to address the requirements. In Table 11.1 the coupler geometrical parameters as well as the measured performance are summarized. It is observed that the measured coupling of $8.45 \pm 0.2$ dB is in good agreement with the design value of $8.2$ dB.

To achieve tight coupling on the order of $3.0$ dB, the separation $D$ between the strip conductors has to be very small. A small gap concentrates the electric fields and increases the conductor loss. Hence a better approach is to use a metal underpass as shown in the cross-sectional view in Figure 11.1(c). A $3.0$ dB coupler with an underpass designed for operation at $24.0$ GHz is reported in [5]. The geometry of the coupler is rather complicated, and hence simple design equations are not available. Therefore the coupler is designed with the help of computer simulation tools, such as em [6]. To facilitate characterization using on-wafer RF probing techniques the four ports are terminated in $50\ \Omega$ grounded CPW. The measured performance of the coupler shows that the coupling is about $4.0 \pm 1.0$ dB, the isolation greater than $15.0$ dB and the input return loss less than $-12.0$ dB.

11.2.3  Broadside Coupled CPW Directional Coupler

A schematic of a broadside coupled CPW directional coupler is shown in Figure 11.3. The coupler is designed for a special application which requires a
coupling of 3.0 dB at closely spaced frequencies of 0.9 and 1.5 GHz [3]. To meet this requirement, the coupler is designed for a more tighter coupling of 2.65 dB at an in between frequency of 1.2 GHz. The rational behind this design is that the coupling tends to become weaker and approach the target value of 3.0 dB at frequencies on either side of 1.2 GHz. The dimensions of the coupler are determined from (11.3) to (11.5). Table 11.2 summarizes the coupler geometrical parameters and the measured performance over the frequency range of 0.7 to 1.7 GHz. The design and measured coupling values are in good agreement.

11.3 QUADRATURE (90°) HYBRID

A typical quadrature 90° hybrid constructed with CPW and slotline [7] is shown in Figure 11.4. This hybrid is also known as a branch-line hybrid or coupler. The branch-line coupler shown in Figure 11.4 has a rectangular shape, but the coupler may be reformed into a ring shape. To understand the operating principle of the branch-line coupler, consider the equivalent circuit model shown in Figure 11.5. In this model the input, direct, coupled, and isolated ports are designated as ports 1, 2, 3, and 4, respectively. All of these ports are terminated in feed lines of characteristic impedance $Z_0$, which normally is 50 Ω. The characteristic impedance of the branch- and
TABLE 11.2 Broadside Coupled CPW Directional Coupler

<table>
<thead>
<tr>
<th>Circuit parameters and measured characteristics</th>
</tr>
</thead>
<tbody>
<tr>
<td>Substrate, $\varepsilon_r$</td>
</tr>
<tr>
<td>Thickness, mm</td>
</tr>
</tbody>
</table>

**Coupled section**

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>CPW center strip width, $S$, mm</td>
<td>6.5</td>
</tr>
<tr>
<td>CPW slot width, $W$, mm</td>
<td>3.5</td>
</tr>
<tr>
<td>Length of coupled section, $L$, mm</td>
<td>38.5</td>
</tr>
</tbody>
</table>

**Computed data**

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>$Z_{0,e}$, $\Omega$</td>
<td>128.96</td>
</tr>
<tr>
<td>$Z_{0,o}$, $\Omega$</td>
<td>19.54</td>
</tr>
<tr>
<td>$\varepsilon_{eff,e}$</td>
<td>2.28</td>
</tr>
<tr>
<td>$\varepsilon_{eff,o}$</td>
<td>3.06</td>
</tr>
</tbody>
</table>

**Measured characteristics**

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Coupling, $S_{31}$, $S_{41}$, dB</td>
<td></td>
</tr>
<tr>
<td>at 0.88 GHz</td>
<td>-3.2</td>
</tr>
<tr>
<td>at 1.55 GHz</td>
<td>-3.3</td>
</tr>
<tr>
<td>Input return loss, $S_{11}$, dB</td>
<td>$&lt;-15.0$</td>
</tr>
<tr>
<td>Isolation, $S_{21}$, dB</td>
<td>$&lt;-15.0$</td>
</tr>
</tbody>
</table>

**FIGURE 11.4** Schematic of a quadrature 90° hybrid or a branch-line coupler realized using a combination of coplanar waveguide and slotline. (From Reference [7], © 1993 IEEE.)
through-lines are $Z_0$ and $Z_0/\sqrt{2}$, respectively. The length of both the branch- and through-lines are quarter guide wavelength at the center frequency of operation. A signal entering port 1 is equally divided between the direct port 2 and the coupled port 3, with $90^\circ$ phase difference. Port 1 is perfectly matched. Port 4 is the isolated port, and hence no power is coupled to this port. The scattering matrix for an ideal 3-dB quadrature hybrid or branch-line hybrid or coupler has the following form [8]:

$$
[S] = \begin{bmatrix}
0 & j & 1 & 0 \\
j & 0 & 0 & 1 \\
1 & 0 & 0 & j \\
0 & 1 & j & 0
\end{bmatrix}.
$$

(11.6)

### 11.3.1 Standard 3-dB Branch-Line Hybrid

The coupler shown in Figure 11.4 is a good example of a standard 3-dB branch-line hybrid. The hybrid is fabricated on a 1.27 mm thick RT/Duroid 6010.8 ($\varepsilon_r = 10.8$) substrate [7]. In this circuit as a precaution bond wires are placed at the four corners of the rectangular loop to prevent the even mode of the coupled slotline from propagating on the CPW. The measured performance characteristics of the hybrid is summarized in Table 11.3. The hybrid has a bandwidth of 40 percent. A branch-line hybrid can be realized using a combination of CPW and asymmetric coplanar stripline (ACPS) also with similar characteristics as demonstrated in [9].
TABLE 11.3 Standard 3-dB Branch-Line Hybrid

<table>
<thead>
<tr>
<th>Circuit parameters and measured characteristics</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>CPW center strip width, $S$, mm</td>
<td>0.71</td>
</tr>
<tr>
<td>CPW slot width, $W$, mm</td>
<td>0.1</td>
</tr>
<tr>
<td>Length of CPW through-line, $L_{\text{CPW}}$, mm</td>
<td>10.39</td>
</tr>
<tr>
<td>Slotline slot width, $W_{\text{s}}$, mm</td>
<td>0.1</td>
</tr>
<tr>
<td>Length of slot branch-line, $L_{\text{s}}$, mm</td>
<td>7.77</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Measured characteristics</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Center frequency, GHz</td>
<td>3.0</td>
</tr>
<tr>
<td>Insertion loss (includes fixture losses), dB</td>
<td>$-3.75 \pm 0.25$</td>
</tr>
<tr>
<td>Phase quadrature, deg</td>
<td>$83 \pm 3$</td>
</tr>
<tr>
<td>Input and output return loss, dB</td>
<td>$&lt;-19.0$</td>
</tr>
<tr>
<td>Isolation, $S_{\text{r}}$, dB</td>
<td>$&lt;-20.0$</td>
</tr>
<tr>
<td>Bandwidth, %</td>
<td>40</td>
</tr>
</tbody>
</table>

11.3.2 Size Reduction Procedure for Branch-Line Hybrid

Consider the quarter wavelength transmission line shown in Figure 11.6(a). This line constitutes the through-line and the branch-line of a standard branch-line hybrid. The line itself consists of distributed series inductance and shunt capacitance. The goal here is to replace this quarter wavelength long line by a physically shorter but electrically equivalent line. Normally, if a line is arbitrarily shortened, the inductance and capacitance reduce. However, the reductions in the inductance and the capacitance can be overcome by increasing the characteristic impedance and by adding lumped capacitors as shown in Figure 11.6(b).

Let $[Y_a]$ and $[Y_b]$ denote the admittance matrices of the lines in Figures 11.6(a) and (b). Then [10]

$$
[Y_a] = \frac{1}{jZ_0} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}
$$

$$
[Y_b] = \begin{bmatrix}
\frac{\cos \theta}{jZ \sin \theta} + j\omega C & 1 \\
\frac{1}{jZ \sin \theta} & \frac{\cos \theta}{jZ \sin \theta} + j\omega C \\
\end{bmatrix},
$$

where $Z_0$, $Z$, $\theta$, $\omega$, and $C$ are the characteristic impedance of the quarter wavelength line, the characteristic impedance of the shortened line, the electrical length of the shortened line, the angular frequency, and the lumped
capacitance, respectively. Since these two lines are electrically equivalent, their admittance matrices should be identical. Hence equating (11.7) and (11.8), we obtain

\[ Z = \frac{Z_0}{\sin \theta}, \quad (11.9) \]

\[ \omega C = \frac{\cos \theta}{Z_0}. \quad (11.10) \]

These equations suggest that the line length can be made shorter, for example, from 1/4 to 1/8 of the wavelength, by increasing the characteristic impedance of the line by a factor of \(\sqrt{2}\). The lumped capacitance \(C\) can be easily incorporated in a CPW, since all the conductors are on the top side of the substrate.

### 11.3.3 Reduced Size 3-dB Branch-Line Hybrid

An equivalent circuit of standard and reduced size branch-line hybrid are shown in Figures 11.7(a) and (b). In a standard hybrid the characteristic impedance of the branch-line and the through-line are \(Z_0\) and \(Z_0/\sqrt{2}\), respectively. If in the reduced size hybrid the characteristic impedance of the both the branch-line and the through-line are \(Z\) and \(Z\) is greater than \(Z_0\), then
FIGURE 11.7  (a) Standard branch-line hybrid; (b) reduced size branch-line hybrid. The guide wavelength on the line is denoted as $\lambda_g$. 

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the electrical length of the branch-line $\theta_1$, the electrical length of the through-line $\theta_2$, and the lumped capacitance $C$ are given by [10]

$$\theta_1 = \arcsin \left( \frac{Z_0}{Z} \right),$$

(11.11)

$$\theta_2 = \arcsin \left( \frac{Z_0}{\sqrt{2} Z} \right),$$

(11.12)

$$\omega CZ_0 = \sqrt{1 - \left( \frac{Z_0}{Z} \right)^2} + \sqrt{2 - \left( \frac{Z_0}{Z} \right)^2}.$$  

(11.13)

For example, when $Z_0 = 50$ $\Omega$ and $Z = 70.7$ $\Omega$, the equations above give $\theta_1 = 45^\circ$ and $\theta_2 = 30^\circ$. This implies that the branch-line and the through-line lengths $\theta_1$ and $\theta_2$ are $\lambda_g/8$ and $\lambda_g/12$, where $\lambda_g$ is the guide wavelength.

The phase difference between the power to the direct port and the power to the coupled port, that is, the phase ($S_{21}/S_{34}$), is computed in [10] for the reduced size hybrid and the standard quarter wavelength hybrid. The results show that the bandwidth over which the phase difference is $90^\circ$ is narrower in the case of the reduced size hybrid. In a CPW, if the center strip conductor width is held fixed and the slot width is increased, the characteristic impedance increases and the conductor loss reduces. Hence the insertion loss of the reduced size hybrid that has a higher impedance than the standard hybrid is not degraded by size reduction.

An experimental reduced size hybrid fabricated on a semi-insulating GaAs is reported in [10]. The constant impedance transmission line is a CPW with a center strip width of 10 $\mu$m and characteristic impedance of 70.0 $\Omega$. The length of the branch-line and the through-line are $\lambda_{g(\text{CPW})}/8$ and $\lambda_{g(\text{CPW})}/12$, respectively, at 25 GHz. Air-bridges are used at the CPW junctions to tie the ground planes at equal potential and suppress the coupled slotline even mode. Metal-insulator-metal (MIM) shunt capacitors ($\approx 40 \times 40 \mu$m) are located at the corners of inner ground metal. The insulator film is $\text{Si}_3\text{N}_4$. The capacitance $C \approx 0.25$ pF. The size of the fabricated hybrid is 500 $\times$ 500 $\mu$m. This is more than 80 percent smaller than a standard branch-line hybrid.

The measured performance of the hybrid [10] over the frequency band of 24.0 to 26.0 GHz shows that the power coupled from port 1 to ports 2 and 3 are within 5.0 $\pm$ 0.5 dB, return loss at port 1 better than $-10.0$ dB, and the isolation between ports 1 and 4 is better than $-12.0$ dB. As a concluding remark, it may be noted that in [23] a small 90$^\circ$ hybrid coupler based on the Wheatstone bridge principle is demonstrated at a center frequency of 4.0 GHz.

11.3.4 Reduced Size Impedance Transforming Branch-Line Hybrid

The standard impedance transforming hybrid using quarter wavelength long lines with different characteristic impedances is shown in Figure 11.8(a). The
FIGURE 11.8  (a) Standard impedance transforming branch-line hybrid: (b) reduced size impedance transforming branch-line hybrid.

coupling constant $C_0$ is defined as [11]

$$C_0 = \frac{\text{coupling coefficient}}{\text{transmission coefficient}} = \left| \frac{S_{31}}{S_{21}} \right|. \quad (11.14)$$

The corresponding line characteristic impedances, in terms of $C_0$ and the
termination impedances of the hybrid ports, $Z_{\text{in}}$ and $Z_{\text{out}}$, can be expressed as [11]

$$Z_1 = \frac{Z_{\text{in}}}{C_0},$$  \hspace{1cm} (11.15)

$$Z_2 = \sqrt{\frac{Z_{\text{in}}Z_{\text{out}}}{1 + C_0^2}},$$  \hspace{1cm} (11.16)

$$Z_3 = \frac{Z_{\text{out}}}{C_0}.$$  \hspace{1cm} (11.17)

Notice that for 3 dB, coupling $C_0 = 1$. Further, for $Z_{\text{in}} = Z_{\text{out}} = 50 \, \Omega$, the impedance transforming hybrid reduces to a standard hybrid as discussed in Section 11.3.

The reduced size impedance transforming hybrid using lines of single characteristic impedance $Z_0$ but different lengths is shown in Figure 11.8(b). For an equivalent performance, the electrical lengths of the transmission lines are given by [11]

$$\theta_1 = \arcsin \left( \frac{Z_{\text{in}}}{Z_0C_0} \right),$$  \hspace{1cm} (11.18)

$$\theta_2 = \arcsin \left( \frac{\sqrt{Z_{\text{in}}Z_{\text{out}}/(1 + C_0^2)}}{Z_0} \right),$$  \hspace{1cm} (11.19)

$$\theta_3 = \arcsin \left( \frac{Z_{\text{out}}}{Z_0C_0} \right).$$  \hspace{1cm} (11.20)

The shunt capacitor values are obtained from the expression [11]

$$\omega C_1 = \sqrt{\frac{C_0^2 - 1}{Z_{\text{in}}^2 - Z_0^2} + \frac{1 + C_0^2}{Z_{\text{in}}Z_{\text{out}} - Z_0^2}},$$  \hspace{1cm} (11.21)

$$\omega C_2 = \sqrt{\frac{C_0^2 - 1}{Z_{\text{out}}^2 - Z_0^2} + \frac{1 + C_0^2}{Z_{\text{in}}Z_{\text{out}} - Z_0^2}}.$$  \hspace{1cm} (11.22)

For a 3 dB hybrid, $C_0 = 1$, and the equations above reduce to those in [12].

An experimental reduced size impedance matching hybrid using constant impedance CPW transmission lines and fabricated on a semi-insulating GaAs substrate is reported in [12]. Usually, the center frequency $f_0$, transforming impedances $Z_{\text{in}}$ and $Z_{\text{out}}$, and CPW characteristic impedance $Z_0$ are known. Therefore the design involves determining $\theta_1$, $\theta_2$, $\theta_3$, and the lumped capacitances $C_1$ and $C_2$ using Eqs. (11.18) to (11.22). The CPW circuit parameters, chip size, and the measured characteristics are summarized in Table 11.4.
### TABLE 11.4 Reduced Size Impedance Transforming 3-dB Branch-Line Hybrid

<table>
<thead>
<tr>
<th>Circuit parameters, measured characteristics and chip size</th>
</tr>
</thead>
<tbody>
<tr>
<td>Substrate, GaAs, $\varepsilon_r$</td>
</tr>
<tr>
<td>Thickness, $\mu$m</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Given circuit parameters</th>
</tr>
</thead>
<tbody>
<tr>
<td>$Z_{\text{in}}$, $\Omega$</td>
</tr>
<tr>
<td>$Z_{\text{out}}$, $\Omega$</td>
</tr>
<tr>
<td>$Z_0$, $\Omega$</td>
</tr>
<tr>
<td>CPW center strip width, $\mu$m</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Computed parameters</th>
</tr>
</thead>
<tbody>
<tr>
<td>$\theta_1$, deg</td>
</tr>
<tr>
<td>$\theta_2$, deg</td>
</tr>
<tr>
<td>$\theta_3$, deg</td>
</tr>
<tr>
<td>$C_1$, pF</td>
</tr>
<tr>
<td>$C_2$, pF</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Measured characteristics</th>
</tr>
</thead>
<tbody>
<tr>
<td>Center frequency, $f_0$, GHz</td>
</tr>
<tr>
<td>Power coupled to the output ports, dB (coupled port and direct port)</td>
</tr>
<tr>
<td>Return loss, dB</td>
</tr>
<tr>
<td>at input port</td>
</tr>
<tr>
<td>at output port</td>
</tr>
<tr>
<td>Isolation, $S_{41}$, dB</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Size</th>
</tr>
</thead>
<tbody>
<tr>
<td>Chip, $\mu$m$^2$</td>
</tr>
<tr>
<td>Circuit size compared to standard impedance transforming hybrid</td>
</tr>
</tbody>
</table>

#### 11.4 180° HYBRID

The 180° hybrid is in general a four-port network as represented in Figure 11.9(a). A signal incident at port 1 is evenly divided in-phase between the two output ports 2 and 3. Port 4 is the isolated port and hence no power is coupled to this port. On the other hand, if the signal is incident at port 4, it is evenly divided between the two output ports 2 and 3, and in addition the output signals are 180° out of phase as represented in Figure 11.9(b). In this case port 1 is the isolated port.

The 180° hybrid is also a signal combiner as represented in Figure 11.9(c). When signals are incident at ports 2 and 3, their sum and difference emerge from port 1 and port 4, respectively. Hence ports 1 and 4 are also referred to
FIGURE 11.9 Representation of a 180° hybrid: (a) As a power divider with port 1 as input; (b) as a power divider with port 4 as input; (c) as a power combiner with ports 2 and 3 as input.

as the sum and difference ports, respectively. The scattering matrix for an ideal 3-dB 180° hybrid has the following form [8]:

$$\begin{bmatrix}
0 & 1 & 1 & 0 \\
1 & 0 & 0 & -1 \\
1 & 0 & 0 & 1 \\
0 & -1 & 1 & 0
\end{bmatrix}. \quad (11.23)$$

The reason for the $1/\sqrt{2}$ factor is that with all impedances equal an equal power split reduces voltages (and currents) by $1/\sqrt{2}$. The factor $\mp j$ depends on whether the path length from the input port to the output ports are $\lambda_g/4$ or $3\lambda_g/4$, respectively. This will be evident when a practical circuit is considered in the next section. The 180° hybrid is constructed either as a ring hybrid or as a magic-T. The ring hybrid is also known as the rat race.
11.4.1 Standard 180° Ring Hybrid

A standard 180° ring hybrid realized using a combination of CPW and asymmetric coplanar stripline (ACPS) [9] is shown in Figure 11.10. The circuit consists of four CPW-to-ACPS T-junctions and an ACPS ring. The circumference of the ACPS ring is \(1.5\lambda_{g\text{ACPS}}\) where \(\lambda_{g\text{ACPS}}\) is the guide wavelength in the ACPS. The ACPS ring is divided into three \(\lambda_{g\text{ACPS}}/4\) sections and one \(3\lambda_{g\text{ACPS}}/4\) section. The characteristic impedance of the ACPS and CPW are

\[
Z_{\text{ACPS}} = \sqrt{2} Z_{\text{CPW}} \tag{11.24}
\]

and

\[
Z_{\text{CPW}} = Z_0, \tag{11.25}
\]

where \(Z_0\) is the terminating impedance or the source impedance.

An experimental hybrid built on a 0.635 mm thick RT/Duroid 6010.8 (\(\varepsilon_r = 10.8\)) substrate is reported in [9]. To prevent the coupled slotline mode from

![FIGURE 11.10  Standard 180° ring hybrid with coplanar waveguide terminations and asymmetric coplanar stripline ring. (From Reference [9], © 1997 IEEE.)](image)
TABLE 11.5 Standard 180° Ring Hybrid

Circuit parameters and measured characteristics

<table>
<thead>
<tr>
<th>CIRCUIT PARAMETERS</th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>CPW center strip width, $S$, mm</td>
<td>0.60</td>
<td></td>
<td></td>
</tr>
<tr>
<td>CPW slot width, $W$, mm</td>
<td>0.29</td>
<td></td>
<td></td>
</tr>
<tr>
<td>$Z_{CPW}$, $\Omega$</td>
<td>50</td>
<td></td>
<td></td>
</tr>
<tr>
<td>ACPS strip width, $S_{ACPS}$, mm</td>
<td>0.40</td>
<td></td>
<td></td>
</tr>
<tr>
<td>ACPS slot width, $W_{ACPS}$, mm</td>
<td>0.27</td>
<td></td>
<td></td>
</tr>
<tr>
<td>$Z_{ACPS}$, $\Omega$</td>
<td>71</td>
<td></td>
<td></td>
</tr>
<tr>
<td>$\lambda_{ACPS}/4$, mm</td>
<td>10.73</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>MEASURED CHARACTERISTICS</th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Center frequency, GHz</td>
<td>30</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Coupling (includes fixture losses) $(</td>
<td>S_{24}</td>
<td>$ or $</td>
<td>S_{44}</td>
</tr>
<tr>
<td>Input return loss $(</td>
<td>S_{44}</td>
<td>)$, dB</td>
<td>$&lt;-23.0$</td>
</tr>
<tr>
<td>Isolation $(</td>
<td>S_{14}</td>
<td>)$, dB</td>
<td>$&lt;-21.0$</td>
</tr>
<tr>
<td>Bandwidth, MHz, %</td>
<td>750 (25%)</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

interfering with the circuit performance, bond wires or air-bridges are located at the CPW-to-ACPS T-junctions. This circuit operates as explained in Section 11.4. The CPW and ACPS circuit parameters as well as the measured characteristics are summarized in Table 11.5. The ring hybrid has a bandwidth of about 25 percent.

11.4.2 Size Reduction Procedure for 180° Ring Hybrid

The standard 180° ring hybrid or rat race shown in Figure 11.10 consists of three $\lambda_g/4$ and a $3\lambda_g/4$ transmission lines, where $\lambda_g$ is the guide wavelength. The quarter wavelength lines can be shortened to one-eighth of a wavelength by increasing their characteristic impedance by a factor of $\sqrt{2}$ and adding lumped capacitances at the ends as discussed in Section 11.3.2. The three-quarter wavelength line can be replaced by an equivalent lumped element Pi-network as shown in Figure 11.11. The elements of the Pi-network are determined by equating the Pi-network $ABCD$ matrix to the line $ABCD$ matrix.

11.4.3 Reduced Size 180° Ring Hybrid

The equivalent circuit representation of a standard 180° ring hybrid is shown in Figure 11.12(a). To reduce the size of the hybrid, first, the quarter wavelength lines of 70 $\Omega$ characteristic impedance are replaced by one-eighth wavelength lines of 100 $\Omega$ characteristic impedance with lumped capacitances at the ends. Second, the three-quarter wavelength line of 70 $\Omega$ characteristic
impedance is replaced by a Pi-network consisting of lumped series capacitance and shunt inductances. The lumped shunt inductances and capacitances almost cancel each other, resulting in the equivalent circuit [10] shown in Figure 11.12(b).

Besides size reduction the reduced size ring hybrid has the advantage of being able to interchange ports at the location of the series metal-insulator-metal (MIM) capacitor [10] as illustrated in Figure 11.13. In Figure 11.13(a) the output ports 2 and 3 are located on opposite sides of port 4. By interchanging the location of port 2 and 4, the output ports 2 and 3 are located side by side as shown in Figure 11.13(b). Further, if port 4 is used as the input port then, the output at ports 2 and 3 are 180° out of phase as discussed in Section 11.4. This feature greatly simplifies balanced mixer construction using a ring hybrid [24].

A experimental reduced size ring hybrid fabricated on a semi-insulating GaAs substrate with elevated CPW as the transmission line is reported in [13]. The elevated CPW has the advantage of reducing both the insertion loss as well as the chip area as discussed in Chapter 2. The hybrid consists of three one-eighth wavelength 100 Ω elevated CPW, a series and two shunt capacitors in place of the three $\lambda_g/4$, and a $3\lambda_g/4$ 70 Ω transmission lines as in a standard ring hybrid. In the experimental hybrid the elevated CPW is meandered to further reduce the overall size. The ring hybrid is schematically shown in Figure 11.14.

**FIGURE 11.11** (a) Three-quarter wavelength transmission line. The wavelength on the line is denoted as $\lambda_g$; (b) equivalent lumped element Pi-network.
FIGURE 11.12 Representation of (a) standard 180° ring hybrid or rate race with transmission lines and (b) equivalent reduced size 180° ring hybrid or rat race with transmission lines and lumped elements. The wavelength on the line is denoted as $\lambda_e$. 
FIGURE 11.13 (a) Normal port layout; (b) port layout convenient for balanced mixer applications.
FIGURE 11.14 Reduced size 180° ring hybrid with meandered elevated CPW.

The measurements show that the coupling loss \(|S_{12}|, |S_{42}|\) of the hybrid is on the order of 4.2 ± 0.8 dB, return loss \(|S_{22}|\) better than 17.0 dB and isolation \(|S_{32}|\) better than 18.0 dB over the frequency range 15.0 ± 2.0 GHz. The chip size is on the order of 0.50 × 0.55 mm.

11.4.4 Reverse-Phase 180° Ring Hybrid

In the hybrid circuits shown in Figure 11.15, the three-quarter wavelength long phase delay section of the standard 180° ring hybrid is replaced by a quarter wavelength long line and a 180° phase shifter. The quarter wavelength line and the 180° phase shifter are implemented either by using a CPW-to-slotline T-junction [14] as shown in Figure 11.15(a) or by a phase-reversing asymmetric coplanar stripline (ACPS) section [9] as shown in Figure 11.15(b). The advantage gained in using either of the two approaches is that the phase shift is independent of frequency and hence the reverse-phase hybrid has a wider bandwidth. In addition, the reverse-phase hybrid is smaller in size since the circumference of the ring is one wavelength. Figure 11.15(c) shows the transmission line model for the circuit in Figure 11.15(b). The circuit parameters as well as the measured performance of the ACPS reverse-phase 180° ring hybrid shown in Figure 11.15(b) are summarized in Table 11.6. The reverse-phase 180° ring hybrid has a bandwidth of one octave.
### TABLE 11.6 ACPS Reverse-Phase 180° Ring Hybrid

<table>
<thead>
<tr>
<th>Circuit Parameters and Measured Characteristics</th>
<th>Standard Circuit</th>
<th>Reduced Size Circuit</th>
</tr>
</thead>
<tbody>
<tr>
<td>RT/Duroid 6010.8 (εr = 10.8) thickness, mm</td>
<td>0.635</td>
<td>0.635</td>
</tr>
</tbody>
</table>

#### CPW feed line

<p>| | | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Strip width, S, mm</td>
<td>0.6</td>
<td>0.6</td>
</tr>
<tr>
<td>Slot width, W, mm</td>
<td>0.29</td>
<td>0.29</td>
</tr>
<tr>
<td>Characteristic impedance, Z&lt;sub&gt;CPW&lt;/sub&gt;, Ω</td>
<td>50</td>
<td>50</td>
</tr>
</tbody>
</table>

#### Slotline stub

<p>| | | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Radial stub radius, mm</td>
<td>6.0</td>
<td>—</td>
</tr>
<tr>
<td>Radial stub angle, deg</td>
<td>90</td>
<td>—</td>
</tr>
</tbody>
</table>

#### ACPS ring

<p>| | | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Strip width, S&lt;sub&gt;ACPS&lt;/sub&gt;, mm</td>
<td>0.4</td>
<td>—</td>
</tr>
<tr>
<td>Slot width, W&lt;sub&gt;ACPS&lt;/sub&gt;, mm</td>
<td>0.27</td>
<td>—</td>
</tr>
<tr>
<td>Length of each arm, deg</td>
<td>90</td>
<td>7.2</td>
</tr>
<tr>
<td>Characteristic impedance, Z&lt;sub&gt;ACPS&lt;/sub&gt;, Ω</td>
<td>70.7</td>
<td>66.9</td>
</tr>
</tbody>
</table>

#### Measured characteristics

<p>| | | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Center frequency, GHz</td>
<td>3.0</td>
<td>3.0</td>
</tr>
<tr>
<td>Bandwidth, GHz</td>
<td>2.0–4.0</td>
<td>2.0–4.0</td>
</tr>
<tr>
<td>Coupling (S&lt;sub&gt;12&lt;/sub&gt; or S&lt;sub&gt;42&lt;/sub&gt;), dB (includes fixture losses)</td>
<td>−3.95 ± 0.45</td>
<td>−3.5 ± 0.4</td>
</tr>
<tr>
<td>Amplitude balance, dB</td>
<td>±0.4</td>
<td>±0.3</td>
</tr>
<tr>
<td>Phase balance, deg</td>
<td>±4.0</td>
<td>±3.1</td>
</tr>
<tr>
<td>Input return loss, S&lt;sub&gt;22&lt;/sub&gt;, dB</td>
<td>&lt; −13.5</td>
<td>&lt; −12.0</td>
</tr>
<tr>
<td>Isolation, S&lt;sub&gt;32&lt;/sub&gt;, dB</td>
<td>&lt; −23.0</td>
<td>&lt; −29.8</td>
</tr>
</tbody>
</table>

### 11.4.5 Reduced Size Reverse-Phase 180° Ring Hybrid

The reverse-phase 180° ring hybrid discussed in the previous section has a circumference that is one wavelength. This circumference can be further reduced and the overall size of the circuit made smaller if the characteristics impedance of the feed line and the ring line are chosen according to the following relation [15]:

\[
Z_{\text{ring}} = Z_{\text{feed}}\sqrt{2(1 - \cot^2 \theta)},
\]  

(11.26)

where \(Z_{\text{ring}}\) and \(Z_{\text{feed}}\) are the characteristic impedance of the ring line and feed line, respectively and \(\theta\) is the electrical length of one quarter of the ring.

1. **RT/Duroid 6010.8 (εr = 10.8) thickness, mm**: 0.635, 0.635
2. **CPW feed line**: Strip width, S = 0.6 mm, Slot width, W = 0.29 mm, Characteristic impedance, \(Z_{\text{CPW}}\) = 50 Ω
3. **Slotline stub**: Radial stub radius = 6.0 mm, Radial stub angle = 90 deg
4. **ACPS ring**: Strip width, \(S_{\text{ACPS}}\) = 0.4 mm, Slot width, \(W_{\text{ACPS}}\) = 0.27 mm, Length of each arm = 90 deg, Characteristic impedance, \(Z_{\text{ACPS}}\) = 70.7 Ω, 66.9 Ω
5. **Measured characteristics**: Center frequency = 3.0 GHz, Bandwidth = 2.0–4.0 GHz, Coupling = −3.95 ± 0.45 dB, Amplitude balance = ±0.4 dB, Phase balance = ±4.0 deg, Input return loss, \(S_{22}\) = < −13.5 dB, Isolation, \(S_{32}\) = < −23.0 dB
FIGURE 11.15 Reverse-phase 180° ring hybrid: (a) With CPW-to-slotline 180° reverse-phase section (from Reference [14], © 1994 IEEE); (b) with ACPS 180° reverse-phase section (from Reference [9], © 1997 IEEE); (c) equivalent transmission line model for the ACPS ring hybrid.

circumference. In this equation, $\theta$ can take any value between 45° and 90° [15]. By choosing $\theta$ equal to 72°, the four arm lengths reduce from one-quarter of a wavelength to one-fifth of a wavelength, and therefore the circumference reduces from one wavelength to 0.8 wavelength [9], [16]. The $Z_{\text{feed}}$ is normally 50 $\Omega$, and hence the characteristic impedance of the ring line also reduces from 70.7 to 66.9 $\Omega$. The circuit layouts of reduced size reverse-phase 180° ring
hybrid are identical to those of the standard reverse phase 180° ring hybrid shown in Figures 11.15(a) and (b). Except that the reduced size ring hybrid has arm lengths and characteristic impedances which are shorter and smaller, respectively. The measured performance of a CPS reduced size reverse-phase 180° ring hybrid [9] is also summarized in Table 11.6.

11.5 STANDARD 3-dB MAGIC-T

As explained in Section 11.4, the magic-T is also a 180° hybrid and can be completely described by the scattering matrix given in (11.23). In Figure 11.16(a) a magic-T [14] formed with three CPW T-junctions and a 180°
FIGURE 11.16 Standard 3-dB magic-T: (a) circuit configuration (from Reference [14], © 1994 IEEE); (b) equivalent transmission line model. The wavelength on the line is denoted as $\lambda_g$. 
reverse-phase CPW-slotline T-junction is shown. In Figure 11.16(a) port 1 and port 4 correspond to the H-arm and E-arm of a conventional waveguide magic-T. In addition the ports 1 and 4 are known as the sum (Σ) and difference (Δ) ports, respectively, as explained in Section 11.4. Ports 2 and 3 are the power dividing balanced-arms. Figure 11.16(b) shows the transmission line model of the above magic-T. In this figure the twisted transmission line represents the 180° phase reversal of the CPW-slotline T-junction. The characteristic impedance of the feed line, the CPW line and the slotline are indicated as \( Z_{feed}, Z_{CPW}, \) and \( Z_{slot} \), respectively. The guide wavelength on these lines are indicated as \( \lambda_g \).

To obtain a relation between the various characteristic impedances consider a signal feed to port 1 (H-arm) of the magic-T as shown in Figure 11.17(a). The arrows indicate the direction of the electric field lines in the CPW and the slotline. The signal divides into two components and arrive in phase at ports 2 and 3. The two components arrive at port 4 (E-arm) 180° out of phase and cancel each other. In this case the plane of symmetry at the H-arm and the E-arm correspond to an open circuit (magnetic wall) and a short circuit (electric wall), respectively. The equivalent circuit of the magic-T for this excitation is shown in Figure 11.17(b).

Next consider a signal fed to port 4 (E-arm) of the magic-T as shown in Figure 11.18(a). Once again, the signal divides into two components and arrive at ports 2 and 3 but with a 180° phase difference. The phase difference is because of the 180° reverse-phase CPW-slotline T-junction. Two components arrive at port 1 (H-arm) 180° out of phase and cancel each other. In this case the plane of symmetry at the H-arm and the E-arm correspond to a short circuit (electric wall) and an open circuit (magnetic wall), respectively. The equivalent circuit of the magic-T for this excitation is shown in Figure 11.18(b).

By superimposing the above two cases, the total reflection coefficient at the balanced-arm, port 2 is obtained as follows [14]:

\[
S_{22} = \frac{1}{2} \Gamma_{++} + \frac{1}{2} \Gamma_{+-},
\]

(11.27)

where \( \Gamma_{++} \) and \( \Gamma_{+-} \) are the voltage reflection coefficients at port 2. To achieve impedance matching at port 2, \( |S_{22}| \) must be equal to zero. For this to happen, the following conditions must be satisfied:

\[
Z_{slot} = Z_{CPW}
\]

(11.28)

and

\[
Z_{CPW} = \sqrt{2} Z_{feed}.
\]

(11.29)

A similar reasoning holds true for port 3 impedance match. The isolation between ports 1 (H-arm) and 4(E-arm) is perfect as long as the 180° reverse-phase CWP-slotline T-junction is ideal.

A magic-T [7] can also be constructed using a three CPW T-junctions and a slotline T-junction as shown in Figure 11.19. In this circuit, the slotline
FIGURE 11.17 In-phase excitation at ports 2 and 3 of the magic-T: (a) electric-field distribution. The arrows indicate the direction of the electric field. (b) Simplified equivalent circuit.

T-junction behaves as a phase inverter or as a 180° reverse-phase network. To achieve impedance matching at ports 2 and 3, $Z_{\text{slot}}$ is equal to $\sqrt{2}Z_{\text{feed}}$.

An experimental ring magic-T (Figure 11.19) fabricated on a 1.27 mm thicken RT/Duroid 6010.8 ($\varepsilon_r = 10.8$) substrate is reported in [7]. The CPW and the slotline circuit parameters as well as the measured characteristics are summarized in Table 11.7. The ring magic-T has an octave bandwidth.
11.5.1 Reduced Size 3-dB Magic-T

The circumference of the magic-T circuits discussed in the previous section is one guide wavelength. To reduce the circumference and thereby the overall size consider the hybrid ring topology [17] shown in Figure 11.20. In this circuit it is assumed that the transmission lines in opposite ring arms are identical and that the hybrid ring is matched at all ports. The phase shifter may be located anywhere in any of the four arms. In this hybrid a signal fed to port 1 (H-arm)
TABLE 11.7 Standard 3-dB Ring Magic-T

<table>
<thead>
<tr>
<th>Circuit parameters and measured characteristics</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>CPW FEED LINE</strong></td>
</tr>
<tr>
<td>Strip width, $S$, mm</td>
</tr>
<tr>
<td>Slot width, $W$, mm</td>
</tr>
<tr>
<td>Characteristic impedance, $Z_{\text{feed}}$, $\Omega$</td>
</tr>
</tbody>
</table>

**Slotline ring**

| Slot width, $W_s$, mm                               | 0.43 |
| Radius, mm                                          | 7.77 |
| Characteristic impedance, $Z_{\text{slot}}$, $\Omega$ | 70.7 |

**Slotline feed**

| Slot width, $W_f$, mm                               | 0.1  |
| Characteristic impedance, $Z_{\text{slot feed}}$, $\Omega$ | 50   |

**Slotline radial stub**

| Stub radius, mm                                     | 6.0  |
| Stub angle, deg                                     | 90   |

**MEASURED CHARACTERISTICS**

| Center frequency, $f_0$, GHz                        | 3.0  |
| Bandwidth, GHz                                      | 2.0–4.0 |
| E-arm power division                                |
| Amplitude, dB                                       | $\pm 0.4$ |
| Phase, deg                                          | $181.0 \pm 1.0$ |
| Insertion loss at $f_0$, dB                         | $< -0.6$ |
| H-arm power divisions                               |
| Amplitude, dB                                       | $\pm 0.3$ |
| Phase, deg                                          | $\pm 0.75$ |
| Insertion loss at $f_0$, dB                         | $< -0.5$ |
| Isolation between E- and H-arms, dB                 | $< -36.0$ |
| Isolation between the balanced arms 1 and 2, dB     | $< -12.0$ |

will be split equally and in-phase between the two output ports 2 and 3 (balanced-arms). Similarly a signal feed to port 4 (E-arm) will be split equally and out-of-phase between the two output ports 2 and 3. The following design equations hold good [17]:

\[
Z_{c1}^2 = Z_0^2 \frac{\sin^2 \theta_1 + \sin^2 \theta_2 - 2 \cos \theta_1 \cos \theta_2}{\sin^2 \theta_1}, \tag{11.30}
\]

\[
Z_{c2}^2 = Z_0^2 \frac{\sin^2 \theta_1 + \sin^2 \theta_2 - 2 \cos \theta_1 \cos \theta_2}{\sin^2 \theta_2}, \tag{11.31}
\]
FIGURE 11.19 Standard 3-dB ring magic-T. (From Reference [7], © 1993 IEEE.)

FIGURE 11.20 Generalized ring magic-T.
where \( \theta_i \) \((i = 1, 2)\) is the electrical length of arm \( i \) at the center frequency \( f_0 \). The impedances \( Z_{e1} \) and \( Z_{e2} \) are the characteristic impedances of the lines in the ring arms. The impedance \( Z_0 \) is the terminating impedance. To obtain real values for characteristic impedances, the following condition must be satisfied [17]:

\[
\cos \theta_1 + \cos \theta_2 < \sqrt{2}.
\]

(11.32)

In a symmetrical design all the four ring arms are identical. In such a case the equation above reduces to [15]

\[
Z_c = Z_0\sqrt{2}\sqrt{1 - \cot^2 \theta}.
\]

(11.33)

An experimental reduced size magic-T [15], [17] realized with symmetric coplanar striplines is shown in Figure 11.21(a). Coplanar striplines are chosen because they allow easy crossover of the two strips to realize the 180° phase shifter needed at the E-arm. The crossover may be placed at any position along the arm or at the T-junction as shown in Figure 11.21(b).

In this design [15] \( \theta \) is equal to 60° and for \( Z_0 \) equal to 50 \( \Omega \), \( Z_c \) from Eq. (11.33) is equal to 57.6 \( \Omega \). This design results in a ring circumference of 0.67 guide wavelength. The magic-T is fabricated on a 254 \( \mu \)m thick alumina substrate \( (\varepsilon_r = 9.9) \) and the conductor thickness is 4 \( \mu \)m. The geometrical parameters and the measured performance of the magic-T are summarized in Table 11.8. The magic-T has a bandwidth slightly larger than one octave.

As a concluding remark, it may be noted that there are other designs for magic-Ts that can be found in [16], [18], [19], [20].

### 11.6 ACTIVE MAGIC-T

The magic-T circuits discussed in earlier sections are based on short sections of transmission lines, which are interconnected, and hence are passive circuits. In this section an active magic-T [21] composed of a GaAs FET with two gate fingers, and very short sections of CPW and slotline is described. The schematic and equivalent circuit of the magic-T are shown in Figure 11.22(a) and (b). The GaAs FET source contact and gate fingers are extended to form the center strip conductor and the ground conductors of a CPW, respectively. The CPW is the H-arm as well as port 1 of the magic-T. The extended gate fingers and the two drain contacts form two slotlines that together with the CPW form an in-phase power divider. The two slotlines or the two output ports of the power divider are the two balanced-arms as well as ports 2 and 3 of the magic-T. In this arrangement the gate serves as the common or the ground conductor. The two drain contacts and the gate contact form a slotline series T-junction which is equivalent to an out-of-phase power divider. The input port of this power divider is the E-arm or port 4 of the magic-T. Having discussed the construction of the magic-T, expressions which relate the reflection coefficient at the four ports, the power division ratio between the input
FIGURE 11.21  (a) Reduced size ring magic-T (from Reference [15], © IEE); (b) alternate implementation with slotline feed for E-arm (from Reference [17], © IEE).

H-arm and E-arm and output ports 2 and 3, and the isolation between the input and output ports are presented next. The reflection coefficient at the four ports are given by [21]

\[
S_{11} = \frac{1 - 2g_m Z_H}{1 + 2g_m Z_H},
\]

\[
|S_{22}| = |S_{33}| = \frac{|\Gamma_{++} + \Gamma_{+-}|}{2},
\]

\[
|S_{44}| = |\Gamma_{+-}|,
\]
### TABLE 11.8 Reduced Size 3-dB Ring Magic-T

<table>
<thead>
<tr>
<th>Circuit parameters and measured characteristics</th>
</tr>
</thead>
<tbody>
<tr>
<td>Substrate (alumina), $\varepsilon_r$</td>
</tr>
<tr>
<td>Thickness, $\mu$m</td>
</tr>
<tr>
<td>Metalization thickness, $\mu$m</td>
</tr>
</tbody>
</table>

**Coplanar waveguide**

| Strip width, $S_1$, $\mu$m | 50 |
| Slot width, $W_1$, $\mu$m | 30 |
| $Z_0$, $\Omega$ | 50 |

**Coplanar stripline**

| Strip width, $W_2$, $\mu$m | 300 |
| Slot width, $S_2$, $\mu$m | 60 |
| $Z_c$, $\Omega$ | 57.6 |
| $\theta$, deg | 60 |
| Circumference, $\lambda_g$ | 0.67 |
| Ring radius, $\mu$m | 3478 |
| Crossover gap, $g$, $\mu$m | 100 |

**Measured performance**

| Center frequency, $f_0$, GHz | 6 |
| Frequency range, GHz | 4.5–9.2 |
| Transmission when fed at H-arm mag ($S_{21}$), mag ($S_{31}$) (dB) | 4.3 $\pm$ 0.3 |
| Transmission when fed at E-arm mag ($S_{24}$), mag ($S_{34}$) (dB) | 4.3 $\pm$ 0.3 |
| Output magnitude balance when fed at H-arm mag ($S_{21}/S_{31}$) (dB) | 0.3 $\pm$ 0.05 |
| Output phase balance when fed at H-arm phase ($S_{21}/S_{31}$) (deg) | 0 $\pm$ 4 |
| Output magnitude balance when fed at E-arm mag ($S_{24}/S_{34}$) (dB) | 0.4 $\pm$ 0.25 |
| Output phase balance when fed at E-arm phase ($S_{24}/S_{34}$) (deg) | 180 $\pm$ 4 |
| Return loss, mag ($S_{22}$) and mag ($S_{33}$), (dB) | $<-10.0$ |
| Isolation, mag ($S_{EH}$), mag ($S_{32}$), (dB) | $<-23.0$ |

where $g_m$ is the transconductance of the FET, $Z_H$ is the characteristic impedance of the CPW or the H-arm, and

\[
\Gamma_{++} = \frac{R_{dg} - Z_0}{R_{dg} + Z_0}, \tag{11.38}
\]

\[
\Gamma_{+-} = \frac{\left( \frac{2Z_E R_{dg}}{Z_E + 2R_{dg}} \right) - 2Z_0}{\left( \frac{2Z_E R_{dg}}{Z_E + 2R_{dg}} \right) + 2Z_0}, \tag{11.37}
\]
where $Z_e$ is the characteristic impedance of the input slotline or E-arm, $R_{dg}$ is the drain-to-gate resistance and $Z_0$ is the characteristic impedance of the output slot lines at ports 2 and 3.

The power division ratio between the input H-arm and E-arm and output ports 2 and 3 are [21]

$$|S_{21}| = |S_{31}| = \frac{2g_m \sqrt{Z_H Z_0}}{1 + 2g_m Z_H} \frac{R_{dg}}{R_{dg} + Z_0},$$

(11.39)
The isolation between the two output ports is given by \[ |S_{24}| = |S_{34}| = \frac{1 - |\Gamma _+|^2}{2} \cdot \frac{2R_{dg}}{2R_{dg} + Z_0} \quad (11.40) \]

The isolation between the output ports 2 and 3 and the input H-arm or port 1 is due to the unilateral characteristics of the FET. The isolation between the two input ports 1 and 4 or H-arm and E-arm is due to the orientation of the fields in the CPW and slotline.

An experimental active magic-T fabricated using 0.5 \( \mu \)m gate GaAs FET is reported in [21]. Each gate finger is 75 \( \mu \)m wide. The chip size is 1 \( \times \) 1 \( \times \) 0.6 mm. The measured coupling loss from the input ports 1 (H-arm) or 4 (E-arm) and the output ports 2 and 3 is within 5 \( \pm \) 1 dB. The measured return loss is better than 10 dB and isolation greater than 20 dB. These measurements are performed over the frequency range of 2 to 18 GHz. The active magic-T has a very wide bandwidth. The noise performance of active balun circuits is discussed in [22].

REFERENCES

[6] em is a registered trademark of Sonnet Software, Inc.


CHAPTER 12

Coplanar Waveguide Applications

12.1 INTRODUCTION

This chapter discusses several emerging applications of coplanar waveguides. These applications include microelectromechanical systems (MEMS) based switches and phase shifters, high-$T_c$ superconducting transmission lines, tunable devices using ferroelectric materials, photonic bandgap structures, and printed circuit antennas. These components and systems make possible several new applications involving the transmission, display, and processing of information at a very high data rate through satellites and wireless networks.

12.2 MEMS COPLANAR WAVEGUIDE CAPACITIVE METAL MEMBRANE SHUNT SWITCH

A coplanar waveguide (CPW) capacitive membrane shunt switch [1] is schematically illustrated in Figure 12.1. The switch consists of a thin metallic membrane, suspended across the CPW center strip conductor. The membrane is supported at either ends by metal posts attached to the CPW ground planes. The thickness, width, and length of the membrane are denoted as $t_m$, $W_m$, and $L_m$, respectively. In such an arrangement the membrane and the CPW center strip conductor behave as the top and bottom electrodes, respectively, of a parallel-plate capacitor. Since the membrane is free to move, the parallel-plate capacitance can be increased by decreasing the distance of separation. This is done by applying a dc voltage between the membrane and the center strip. The dc potential sets up an electrostatic force of attraction that pulls the membrane toward the center strip, thereby decreasing the distance of separation and increasing the capacitance. A dielectric film deposited over the bottom electrode prevents stiction when the metal surfaces come in contact.
12.2.1 OFF and ON Capacitances

The cross section of the switch when it is OFF, that is, when the membrane is in the up position, is shown in Figure 12.2(a). The OFF capacitance of the switch is given by [2].

\[
C_{OFF} = \frac{1}{(t_d/A\varepsilon_0\varepsilon_{rd}) + (h_a/A\varepsilon_0)},
\]

where

- \(A\) = overlap area between the membrane and the bottom electrode
- \(h_a\) = height of the air gap between the membrane and the dielectric layer
- \(t_d\) = thickness of the dielectric film
- \(\varepsilon_{rd}\) = dielectric constant of the film

When the switch is ON, the membrane is in the down position as shown in Figure 12.2(b). The ON capacitance of the switch is given by [2]

\[
C_{ON} = \frac{A\varepsilon_0\varepsilon_{rd}}{t_d}.
\]
FIGURE 12.2 Cross section of the switch: (a) Switch is OFF when the membrane is up; (b) switch is ON when the membrane is down.

For example, if $t_d$ is 2000 Å, $\varepsilon_{rd}$, is 6.7 (PECVD silicon nitride), contact area $A$ is 120 µm by 120 µm, and $h_a$ is 3.6 µm, then from Eqs. (12.1) and (12.2), the $C_{OFF}$ and $C_{ON}$ are 34 fF and 4.3 pF, respectively. This example clearly shows that $C_{OFF}$ is very small compared to $C_{ON}$ and the ratio $C_{ON}/C_{OFF}$ is about 123. For most applications it is sufficient if the ratio $C_{ON}/C_{OFF}$ is about 100.

12.2.2 Figure of Merit

The figure of merit of the switch in defined in terms of a cutoff frequency as follows [2]:

$$f_c = \frac{1}{2\pi R_{ON} C_{OFF}},$$

(12.3)

where

$R_{ON} =$ effective ON resistance or the parasitic resistance of the switch, which is on the order of 0.35 Ω to 0.4 Ω [2].
For the switch in the example in Section 12.2.1, the calculated $f_c$ using Eq. (12.3) is 9000 GHz. This value contrasts with the $f_c$ of 280 GHz and 730 GHz for a GaAs MESFET and a PIN diode, respectively, which operate at 20 GHz [2]. Thus the $f_c$ of a MEMS switch is greater than 12 times that of the best available electronic switches. The higher value of $f_c$ for MEMS based switches implies that these switches will operate with significantly lower loss and lower parasites than switches based on MESFETs and PIN diodes.

12.2.3 Pull Down Voltage

To obtain an expression for the pull down voltage, the MEMS switch discussed in Section 12.2.1 is represented by a simple lumped model. The model [3] consists of a parallel-plate capacitor with a fixed lower plate and a movable upper plate, which is attached to a linear spring as shown in Figure 12.3. The stiffness constant of the spring is $K$, the dc potential across the capacitor is $V$, and the gap between the capacitor plates is $h_a$. This model has single degree of freedom, that is, the gap between the movable and the fixed plates of the capacitor. The electrostatic force between the parallel plates of the capacitor when a voltage $V$ is applied is given by [4]

$$F_{\text{electrostatic}} = \frac{\varepsilon_0 SW_m V^2}{2(h_a - \Delta)^2} \text{ Newtons}, \quad (12.4)$$

where

$S = $ CPW center strip conductor width

$W_m = $ membrane width

$\Delta = $ deflection of the plate

**FIGURE 12.3** A simple lumped capacitor-spring model for the membrane switch.
The restoring spring force of the beam is given by [4]

\[ F_{\text{spring}} = K\Delta \text{ Newtons}. \] (12.5)

Since the system is in equilibrium, we can equate the electrostatic force between the parallel plates to the restoring spring force of the membrane:

\[ \frac{\varepsilon_0SW_mV^2}{2(h_a - \Delta)^2} = K\Delta. \] (12.6)

Solving for the voltage, we have

\[ V = (h_a - \Delta) \sqrt{\frac{2K\Delta}{\varepsilon_0SW_m}} \text{ Volts.} \] (12.7)

A generic plot of the voltage \( V \) as a function of the deflection [4] is shown in Figure 12.4. The figure shows that for deflection from zero to one-third of the initial gap height, \( h_a/3 \), the voltage required to hold the membrane in its deflected position increases monotonically with the deflection \( \Delta \). Further increases in deflection of the membrane result in the deflected position requiring a monotonically decreasing voltage to hold the beam. Therefore the system is unstable, and the membrane snaps down to turn ON the switch. This critical voltage is the pull down voltage. Substituting for \( \Delta = h_a/3 \) in Eq. (12.7) and simplifying obtains

\[ V_p = \left[ \frac{8K}{27\varepsilon_0SW_m} h_a^3 \right]^{1/2} \text{ Volts.} \] (12.8)
The spring constant $K$ is given by [3]

$$K = \frac{32E t_m^3 W_m}{L_m} + \frac{8\sigma(1 - \nu)t_m W_m}{L_m} \text{ Newtons/meter},$$  \hspace{1cm} (12.9)

where

$E =$ Young’s modulus of the membrane material

$\sigma =$ internal residual tensile stress in the membrane

$\nu =$ Poisson’s ratio for the membrane material

$t_m =$ membrane thickness

$L_m =$ membrane length.

For the switch in the example of Section 12.2.1, if $W_m = 120 \mu m$, $L_m = 280 \mu m$, $E = 70 \text{ MPa}$, $\sigma = 120 \text{ MPa}$, and $\nu = 0.33$, then $K = 138 \text{ MPa} \cdot \text{m}$. Further, if $S = 120 \mu m$ and $h_a = 3.6 \mu m$, then the calculated $V_p$ from Eq. (12.8) is $V_p \approx 122 \text{ V}$. This value is about 2.5 times higher than the actuation voltage of 50 V used in the practical switch [2]. Nevertheless, the model serves the purpose of providing a first-cut analysis to gain physical insight and understand of the actuation mechanism. To accurately predict $V_p$, a three-dimensional numerical simulation must be carried out.

### 12.2.4 Fabrication Process

Surface micromachining techniques are utilized to fabricate the switches. Typically the process requires about five mask layers. In [1] and [2] high-resistivity silicon ($\rho > 5 \text{ K} \Omega \cdot \text{cm}$) and aluminum are chosen as the materials for the substrate and the conductors, respectively. In addition silicon nitride ($\varepsilon_{rd} = 6.7$) is used as an insulator between the conductors. These materials allow the possibility of integrating CMOS devices with MEMS devices to construct multifunction assemblies [2]. The fabrication process steps are schematically illustrated in Figure 12.5, and briefly described below:

1. A 1 $\mu m$ thick layer of silicon dioxide is thermally grown over the silicon wafer and serves as a buffer layer.
2. A 0.5 $\mu m$ thick layer of refractory metal such as tungsten is sputtered and patterned to define the bottom electrode of the switch. Tungsten gives a smooth surface finish to the bottom electrode. The good surface finish minimizes the air gaps and ensures good electrical contact when the membrane is in the down position.
3. A 2000 Å thick layer of PECVD silicon nitride ($\varepsilon_{rd} = 6.7$) is deposited and patterned to insulate the bottom electrode. This film prevents the dc
FIGURE 12.5 Schematic illustration of process flow: (a) Silicon dioxide deposition; (b) tungsten bottom electrode deposition; (c) silicon nitride insulator deposition and patterning; (d) aluminum metal posts deposition and patterning; (e) photoresist sacrificial spacer layer spin coating and patterning; (f) Aluminum alloy metal membrane deposition and patterning; (g) sacrificial spacer layer removal by oxygen plasma etch.
control voltage, applied between the membrane and the bottom electrode, from shorting out when the membrane is pulled down. This film thickness is sufficient thin to allow RF signals to capacitively couple from the membrane to the bottom electrode.

4. A 4 \mu m thick aluminium layer is evaporated and wet-etched using a commercial etchant to define the CPW conductors and the post for the membrane. The attenuation of RF signals on aluminium CPWs is about 0.06 dB/mm at 10 GHz [1], which is considered to be small.

5. A photoresist sacrificial spacer layer is spin-coated and patterned.

6. An aluminum alloy membrane layer is sputtered and wet-etched. The thickness of the membrane is less than 0.5 \mu m.

7. The sacrificial spacer layer is removed by oxygen plasma etch to release the membrane. To accelerate the release rate 2 \mu m square openings are provided in the aluminum alloy membrane.

### 12.2.5 Switching Time and Switching Energy

The measured switching speed for the switch in the example in Section 12.2.1 shows that, the time taken for the switch to turn on and off is on the order of 5.3 and 3.5 \mu s, respectively [2], when the RF power is in the few mW range. The corresponding pull down voltage and the energy needed to turn on the switch are 50 V and about 10 nJ, respectively [2]. The switch is turned off by simply turning off the supply voltage. If we assume that this cycle can take place at a rate of 5 KHz, then the drive power that is expended is 50 \mu W. Finally, the switch lifetime test results reported in [2] shows that, the membranes structural integrity is maintained, even after subjecting it to 500 million switching cycles, as evident from the absence of mechanical failures.

In general, the MEMS switches operate at a slower speed than electronic switches. For example, the above switching time of few microseconds contrasts with the switching time of GaAs MESFET and PIN diodes which is about 150 ps and 1 ns, respectively [5], when the RF power is in the mW range. The drive power required in the case of a MESFET switch is higher than a MEMS switch. For example, the driver circuit power expended in turning on the above MESFET switch in 150 ps at a switching frequency of 5 MHz is about 114 mW [5].

### 12.2.6 Insertion Loss and Isolation

The measured insertion loss of the switch in the example in Section 12.2.1 when it is OFF, that is, when the membrane is in the up position, is shown as a function of the frequency in Figure 12.6 [2]. The insertion loss is observed to increase by a few tenths of a dB as the frequency is swept from 0 to 40 GHz. For example, at 20 GHz and 35 GHz the insertion loss is about 0.14 dB and 0.25 dB, respectively, which is considered to be very small. The measured
FIGURE 12.6 Measured insertion loss and return loss when the switch is OFF or the membrane is in the up position. (From Reference [2], © IEEE 1999.)

The insertion loss is better than 15 dB over the entire frequency range. This shows that the switch is well matched to the characteristic impedance of the CPW. Good impedance match is possible because of the low $C_{\text{off}}$, which is on the order of few tens of fF.

The measured isolation of the switch when it is ON, that is, when the membrane is in the down position, is shown as a function of the frequency in Figure 12.7 [2]. The isolation is observed to monotonically improve as the frequency is swept from 0 to 40 GHz. For example, at 10 GHz and 35 GHz

FIGURE 12.7 Measured isolation and return loss when the switch is ON or the membrane is in the down position. (From Reference [2], © IEEE 1999.)
the isolation is about 15 dB and 35 dB, respectively, which is considered to be acceptable for switching RF signals. The isolation below 10 GHz is mainly limited by $C_{\text{ON}}$, which is on the order of few pF. Higher isolation at lower frequencies can be obtained by increasing the size of the bottom electrode or cascading series and shunt versions of the switch.

There are several publications which report the insertion loss and isolation of GaAs MESFET [6] and PIN diode [7] switches. In [6] it is shown that the insertion loss and isolation of recessed-back GaAs MMIC FET switch is on the order of 0.5 dB and 70 dB, respectively over the frequency range of 8.4 to 12.0 GHz. In [7] it is shown that the insertion loss and isolation of vertical GaAs PIN diode switch is on the order of 1.0 dB and 45 dB, respectively, over the frequency range of 100 MHz to 20.0 GHz.

There are several other designs available in the literature for the construction of MEMS switches. For example, in [8] switches using serpentine and cantilever springs for low actuation voltage are reported. In [9] and [10] a cantilevered arm with electrical contacts is electrostatically actuated to close the gap in the signal line. These switches have an isolation $\geq 50$ dB and insertion loss $\leq 0.2$ dB at few GHz frequencies.

### 12.3 MEMS COPLANAR WAVEGUIDE DISTRIBUTED PHASE SHIFTER

A coplanar waveguide distributed true-time delay phase shifter [11], [12] is schematically shown in Figure 12.8. In this phase shifter, the CPW is periodically loaded with a MEMS air bridge to provide capacitance control. The capacitance control is brought about by the application of a dc voltage between the CPW center strip conductor and the air-bridge. The control voltage sets up an electrostatic force of attraction that lowers the height of the air-bridge and increases the parallel-plate capacitance, $C_{\text{MEMS}}$, formed by the air-bridge and the center strip conductor. If the distance of separation between the air-bridges is $d$. Then the distributed MEMS capacitance per unit length is $C_{\text{MEMS}}/d$. Assuming that the circuit is lossless and a TEM mode propagates on the CPW along the $z$-direction, the lumped element equivalent circuit model for an incremental length of the loaded CPW is as shown in Figure 12.9.

The phase velocity of the electromagnetic wave on the loaded CPW is given by the well-known relation

$$v_t = \frac{1}{\sqrt{L_u[C_u + (C_{\text{MEMS}}/d)]}},$$

where $L_u$ and $C_u$ are the inductance and capacitance per unit length, respectively, of the unloaded CPW. These quantities are related to the effective dielectric constant $\varepsilon_{\text{eff}}$, the unloaded characteristic impedance of the CPW $Z_{\text{op}}$, and the velocity of light in free space $c$, through the following well-known
The characteristic impedance of the loaded CPW is given by the well-known relation

\[ Z_l = \frac{L_u}{\sqrt{C_u + (C_{\text{MEMS}}/d)}}. \]  

(12.13)

Thus from Eq. (12.10) it is evident that by increasing \( C_{\text{MEMS}}/d \), the phase velocity \( v_l \) can be reduced. If \( v_{l1} \) and \( v_{l2} \) are the phase velocities for two
different settings of the control voltage, then the differential phase shift in degrees per meter assuming $v_{i1} > v_{i2}$ is

$$\Delta \phi = 360f \left( \frac{1}{v_{i2}} - \frac{1}{v_{i1}} \right) \text{deg/meter}, \quad (12.14)$$

where $f$ is the frequency of operation.

The periodic structure has an upper frequency limit due to the Bragg reflection occurring at [11]

$$f_{\text{Bragg}} = \frac{1}{\pi d \sqrt{L_u [C_u + (C_{\text{MEMS}}/d)]}}. \quad (12.15)$$

### 12.3.1 MEMS Air-Bridge Capacitance

The capacitance $C_{\text{MEMS}}$ can be controlled by either lowering the height of or by snapping down the air-bridge [11], [12]. Each of these options will be discussed below and expressions for the capacitances will be presented.

An isolated MEMS air-bridge capacitor, whose height can be varied through electrostatic actuation, is schematically illustrated in Figure 12.10. The capacitance of the air-bridge for a height $h_a$ is given by

$$C_{\text{MEMS}} = \frac{W_m \varepsilon_0}{h_a}, \quad (12.16)$$

![FIGURE 12.10 Schematic of a MEMS air-bridge capacitor with variable height. Inset shows the equivalent capacitance.](image-url)
FIGURE 12.11  Schematic of a MEMS air-bridge capacitor in the snap down position and the bridge post loaded with fixed thin film capacitors. Inset shows the equivalent series capacitance.

where $W_m$ and $S$ are the air-bridge and the CPW center strip conductor widths, respectively.

An isolated MEMS air bridge in the snap down position is schematically illustrated in Figure 12.11. In this circuit besides the variable air-bridge capacitance, $C_{\text{variable}}$, fixed capacitances, $C_{\text{fixed}}$, are added to the air-bridge posts to enhance the capacitive loading.

These two capacitances appear in series as shown in the inset in Figure 12.11, and therefore the total capacitance can be expressed as

$$C_{\text{MEMS}} = 2 \frac{C_{\text{variable}} C_{\text{fixed}}}{C_{\text{variable}} + 2C_{\text{fixed}}}, \quad (12.17)$$

where

$$C_{\text{variable}} = \frac{W_m S \varepsilon_0 \varepsilon_{\text{rd}}}{t_d}, \quad (12.18)$$

and $\varepsilon_{\text{rd}}$ and $t_d$ are the dielectric constant and thickness of the insulating film.
12.3.2 Fabrication and Measured Performance

The fabrication of the MEMS air bridge capacitors is similar to the MEMS metal membrane capacitors discussed in Section 12.2.4. The measured performance of two phase shifters with MEMS capacitors shown in Figures 12.10 and 12.11, respectively, are compared in Table 12.1.

**TABLE 12.1 Phase Shifter Parameters and Measured Characteristics**

<table>
<thead>
<tr>
<th></th>
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</tr>
</thead>
<tbody>
<tr>
<td><strong>CPW parameters</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Substrate</td>
<td>Quartz, $\varepsilon_r = 3.78$</td>
<td>Glass, $\varepsilon_r = 5.7$</td>
</tr>
<tr>
<td></td>
<td>$\tan \delta = 0.0001$</td>
<td>$\tan \delta = 0.001$</td>
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<tr>
<td></td>
<td>$h = 500 \mu m$</td>
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<td>Center conductor width, $\mu m$</td>
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<tr>
<td>Slot width, $\mu m$</td>
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<td>Characteristic impedance</td>
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<tr>
<td><strong>MEMS capacitors</strong></td>
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<tr>
<td>Bridge width, $\mu m$</td>
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<td>Bridge length or span, $\mu m$</td>
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<td>300</td>
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<tr>
<td>Spacing between bridges, $\mu m$</td>
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<td>780</td>
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<tr>
<td>Total number of bridges</td>
<td>38</td>
<td>11</td>
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<tr>
<td>Bridge height above the center strip conductor, $\mu m$</td>
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<tr>
<td>Capacitance in UP state or zero bias (fF)</td>
<td>34</td>
<td>10</td>
</tr>
<tr>
<td>Capacitance in DOWN state or with bias (fF)</td>
<td>—</td>
<td>75</td>
</tr>
<tr>
<td>$C_{max}/C_{min}$</td>
<td>1.17</td>
<td>7.5</td>
</tr>
<tr>
<td>Bias voltage, V</td>
<td>13</td>
<td>75</td>
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<td></td>
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<tr>
<td><strong>Conductor and dielectric thickness</strong></td>
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<td></td>
</tr>
<tr>
<td>Center conductor, $\mu m$</td>
<td>Au: 0.8</td>
<td>Ti/Au/Ti = 0.02/0.7/0.02</td>
</tr>
<tr>
<td>Ground planes, $\mu m$</td>
<td>Au: 2.5</td>
<td>Ti/Au/Ti = 0.02/0.7/0.02</td>
</tr>
<tr>
<td>Bridges, $\mu m$</td>
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<td>Ti/Au = 0.02/1</td>
</tr>
<tr>
<td>SiN layer, Å</td>
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<tr>
<td>Total length, mm</td>
<td>7.6</td>
<td>8.58</td>
</tr>
<tr>
<td>Measured insertion loss for 360° differential phase shift, dB</td>
<td>5.1 @ 40 GHz</td>
<td>2.34 @ 25 GHz</td>
</tr>
<tr>
<td></td>
<td>4.0 @ 60 GHz</td>
<td>2.25 @ 35 GHz</td>
</tr>
<tr>
<td>Measured return loss, dB</td>
<td>Better than 10 dB over 0–43 GHz</td>
<td>Better than 11 dB over 0–35 GHz</td>
</tr>
</tbody>
</table>
12.4 HIGH-TEMPERATURE SUPERCONDUCTING COPLANAR WAVEGUIDE CIRCUITS

The Nobel Prize winning discovery in 1986, of high-transition-temperature superconductivity in the Ba-La-Cu oxide system [13] renewed the interest in superconducting circuits for high-frequency applications. Since that time several other oxide superconductors such as YBa$_2$Cu$_{3-x}$O$_{7-x}$ with transition temperature above the boiling point of liquid nitrogen, 77 K, have been discovered [13] and their application in high-frequency circuits has been demonstrated [14], [15]. These new oxide superconductors have been called high-temperature superconductors (HTS) in order to distinguish this class of superconductors from those studied prior to 1986 which have a critical temperature, $T_c$, below 77 K.

Most high-frequency applications require epitaxial $c$-axis oriented thin films for good electrical properties. Such films are usually obtained either by laser ablation or by sputtering from stoichiometric targets. In this section we focus mainly on the characteristics and applications of YBa$_2$Cu$_3$O$_{7-x}$ thin films. The substrate materials that are most widely used with YBa$_2$Cu$_3$O$_{7-x}$ are MgO ($\varepsilon_r = 10$ at 77 K) and LaAlO$_3$ ($\varepsilon_r = 24$ at 77 K).

12.4.1 High-Frequency Electrical Properties of Normal Metal Films

Consider a plane wave incident normal to the surface of a good conductor. As the wave propagates inward it suffers rapid attenuation. The distance at which the wave is attenuated to $1/e$ (36.8 percent) of its initial value is called the skin depth. The skin depth is commonly denoted as $\delta$, and it is expressed as [16]

$$\delta = \sqrt{\frac{2}{\omega \mu \sigma(T)}}, \quad (12.19)$$

where

$\omega = $ angular frequency $= 2\pi f$

$\mu = \mu_0 = 4\pi \times 10^{-7}$ H/m

$\sigma(T) = $ the conductivity of the metal in Siemens/meter at a temperature $T$

One can easily observe from Eq. (12.19) that the skin depth varies inversely as the square root of the frequency.

The surface resistance of a sheet of conductor with thickness $\delta$ and conductivity $\sigma(T)$ is given by [16]

$$R_s = \frac{1}{\sigma(T)\delta} \Omega/\text{square}. \quad (12.20)$$

Equation (12.20) is valid as long as the conductor thickness is much greater
than the skin depth. The equation shows that the surface resistance varies as the square root of the frequency. Last, since $\sigma$ is a function of temperature, both $\delta$ and $R_s$ are temperature dependent. As an example, the conductivity of copper is $5.8 \times 10^7$ S/m at room temperature, and hence at 10 GHz, $\delta$ and $R_s$ are 0.66 $\mu$m and 26 m$\Omega$/square, respectively. As the frequency is increased to 20 GHz, $\delta$ decreases to 0.47 $\mu$m while $R_s$ increases to 36.9 m$\Omega$/square. On the other hand, as the temperature is reduced to 77 K, the conductivity of copper increases to $4.5 \times 10^8$ S/m, and at 10 GHz both $\delta$ and $R_s$ decrease to 0.33 $\mu$m and 13 m$\Omega$/square, respectively. It is important to note that the surface resistance $R_s$ is a measure of the time-average power dissipated per unit area of surface [16]. Hence the attenuation constant due to conductor losses $\alpha_c$ in any transmission line is proportional to $R_s$ [16]. In the next section, and in Section 12.4.6, the reduction in $\alpha_c$ through the use of superconductors is discussed.

### 12.4.2 High-Frequency Electrical Properties of Epitaxial High-$T_c$ Superconducting Films

The main advantage of using superconductors instead of normal conductors in high-frequency circuits, is the reduction of conductor losses. Therefore the most important electrical parameter is the surface resistance of the superconductor. The surface resistance is the real part of the surface impedance, $Z_s$, which is generally expressed as

$$Z_s = R_s + jX_s.$$  \hspace{1cm} (12.21)

The surface impedance, $Z_s$, of YBa$_2$Cu$_3$O$_{7-x}$ in the local London limit, that is, when the electronic mean free path is larger than the superconducting coherence length, can be described using the two-fluid model [17]. According to this model

$$Z_s = \frac{\omega^2 \mu_0^2 \lambda_T^3(T) \sigma_1}{2} + j\omega \mu_0 \lambda_T(T),$$  \hspace{1cm} (12.22)

where $\lambda_T(T)$ is the London or the magnetic penetration depth which is a function of the temperature $T$, $\sigma_1$ is the real part of the complex conductivity.

Comparing Eqs. (12.21) and (12.22), we obtain the surface resistance and surface inductance

$$R_s = \frac{\omega^2 \mu_0^2 \lambda_T^3(T) \sigma_1}{2}$$  \hspace{1cm} (12.23)

and

$$L_s = \omega \mu_0 \lambda_T(T),$$  \hspace{1cm} (12.24)
The penetration depth \( \lambda_\ell \) is dependent on the temperature. A mathematical relation for the exact temperature dependence for high-\( T_c \) superconductors has not yet been established. However, based on experimental observations, the temperature dependence can be described by [17]

\[
\lambda_\ell(T) = \frac{\lambda_\ell(0)}{\sqrt{1 - 0.1(T/T_c) - 0.9(T/T_c)^2}},
\]

where

- \( T \) = temperature
- \( T_c \) = critical temperature
- \( \lambda_\ell(0) \) = penetration depth at the reference temperature \( T = 0 \) K

In the equation above the material constant \( \lambda_\ell(0) \) is experimentally determined for several high-\( T_c \) \( \text{YBa}_2\text{Cu}_3\text{O}_7-x \) thin film samples [17] and are listed in Table 12.2. Notice that \( \lambda_\ell(0) \) increases with the transition width \( \Delta T_c \). Where as there is no significant dependence of \( \lambda_\ell(0) \) on the critical current density \( J_c \). Thus, for high-quality films, \( \lambda_\ell(0) \) are in the range of 160 to 200 nm. Last, unlike the skin depth \( \delta \) for normal conductors, the penetration depth \( \lambda_\ell(0) \) for supercon-

### TABLE 12.2 Measured Magnetic Penetration Depth for Epitaxial c-Axis Oriented \( \text{YBa}_2\text{Cu}_3\text{O}_7-x \) Thin Film Samples Deposited by dc-Magnetron Sputtering

<table>
<thead>
<tr>
<th>Sample Number</th>
<th>Circuit Number</th>
<th>( J_c ) (( \times 10^6 ) A/cm(^2))</th>
<th>( T_c ) (K)</th>
<th>( \Delta T_c ) (K)</th>
<th>( \lambda_\ell(0) ) (nm)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>1</td>
<td>1.7</td>
<td>90.0</td>
<td>0.5</td>
<td>160</td>
</tr>
<tr>
<td></td>
<td>2</td>
<td></td>
<td></td>
<td></td>
<td>175</td>
</tr>
<tr>
<td>2</td>
<td>1</td>
<td>3.0</td>
<td>90.5</td>
<td>0.8</td>
<td>200</td>
</tr>
<tr>
<td></td>
<td>2</td>
<td></td>
<td></td>
<td></td>
<td>185</td>
</tr>
<tr>
<td>3</td>
<td>1</td>
<td>4.2</td>
<td>91.0</td>
<td>0.5</td>
<td>155</td>
</tr>
<tr>
<td></td>
<td>2</td>
<td></td>
<td></td>
<td></td>
<td>165</td>
</tr>
<tr>
<td></td>
<td>3</td>
<td></td>
<td></td>
<td></td>
<td>170</td>
</tr>
<tr>
<td>4</td>
<td>1</td>
<td>1.0</td>
<td>86.5</td>
<td>2.5</td>
<td>240</td>
</tr>
<tr>
<td></td>
<td>2</td>
<td></td>
<td></td>
<td></td>
<td>270</td>
</tr>
<tr>
<td></td>
<td>3</td>
<td></td>
<td></td>
<td></td>
<td>250</td>
</tr>
</tbody>
</table>

*Accuracy \( \pm 30 \) nm.

Note: Film thickness = 200 nm.

Source: From Reference [17], © 1993 American Institute of Physics.
ductors is an intrinsic property of the material, and it is independent of the frequency.

### 12.4.3 Kinetic and External Inductances of a Superconducting Coplanar Waveguide

A high-$T_c$ superconducting CPW and its lumped element equivalent circuit model for an incremental section are shown in Figures 12.12 and 12.13. In this model the total series inductance per unit length, $L$, consists of two parts, namely the internal inductance or the kinetic inductance per unit length, which accounts for magnetic energy storage within the conductor, and the external inductance per unit length, which accounts for magnetic energy storage external to the conductor [17]. That is,

$$ L = L_{\text{kinetic}} + L_{\text{external}}. \quad (12.26) $$

The kinetic inductance originates from the inertia of the paired carriers in the superconductor [17], while the external inductance arises from flux linkages [16].

The kinetic inductance per unit length, $L_{\text{kinetic}}$, is given by [17]

$$ L_{\text{kinetic}} = \mu_0 \lambda_k(T) \frac{C}{4ADK(k)} \left\{ \frac{1.7}{\sinh(t/2\lambda_k)} + \frac{0.4}{\sqrt{[(B/A)^2 - 1][1 - (B/D)^2]}} \right\}. \quad (12.27) $$
where
\[
A = -\frac{t}{\pi} + \frac{1}{2} \sqrt{\left(\frac{2t}{\pi}\right)^2 + S^2},
\]
\[
B = \frac{S^2}{4A},
\]
\[
C = B - \frac{t}{\pi} + \sqrt{\left(\frac{t}{\pi}\right)^2 + W^2},
\]
\[
D = \frac{2t}{\pi} + C,
\]
\[
t = \text{superconductor thickness}
\]
\[
S = \text{CPW center strip conductor width}
\]
\[
W = \text{CPW slot width}
\]
\[
\mu_0 = 4\pi \times 10^{-7}\text{H/m}
\]
\[
(12.32)
\]
Notice that \( L_{\text{kinetic}} \) is a function of the penetration depth \( \lambda_0(T) \).

The external inductance per unit length, \( L_{\text{external}} \), is given by [17]
\[
L_{\text{external}} = \frac{\mu_0}{4} \frac{K(k')}{K(k)},
\]
\[
(12.33)
\]
where \( K(k) \) and \( K(k') \) are the complete elliptic integrals of the first kind with their modules given by
\[
k = \frac{S}{S + 2W}
\]
\[
k' = \sqrt{1 - k^2}.
\]
\[
(12.34)
\]
\[
(12.35)
\]
As examples, the calculated external and kinetic inductances per unit length for three CPW structures [18] are tabulated in Table 12.3 and graphically illustrated in Figure 12.14. The results in Table 12.3 and Figure 12.14 show that the external and kinetics inductances per unit length increases as the aspect ratio \( S/(S + 2W) \) of the CPW decreases. In addition for a fixed aspect ratio, the kinetic inductance increases as the penetration depth increases.

### 12.4.4 Resonant Frequency and Unloaded Quality Factor

Typical geometry of a linear and meander high-\( T_c \) superconducting coplanar waveguide series capacitively coupled resonators [19] are shown in Figure 12.15. A schematic showing the flip-chip assembly of the resonator within a microwave package for characterization [19] is shown in Figure 12.16. The measured normalized resonant frequency as a function of the normalized temperature for a CPW resonator is shown in Figure 12.17. In this figure \( T_0 \)
TABLE 12.3  Calculated External Inductance per Unit Length for CPW Lines on a 0.5 mm Thick LaAlO₃ Substrate ($\varepsilon_r = 24$)

<table>
<thead>
<tr>
<th>CPW Structure</th>
<th>Center Strip Conductor Width, $S$ (μm)</th>
<th>Slot Width, $W$ (μm)</th>
<th>Aspect Ratio $S/(S + 2W)$</th>
<th>Conductor Thickness (μm)</th>
<th>External Inductance per Unit Length (nH/m)</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>74</td>
<td>46</td>
<td>0.446</td>
<td>0.3</td>
<td>427.6</td>
</tr>
<tr>
<td>2</td>
<td>34</td>
<td>26</td>
<td>0.395</td>
<td>0.3</td>
<td>454.0</td>
</tr>
<tr>
<td>3</td>
<td>8</td>
<td>13</td>
<td>0.235</td>
<td>0.3</td>
<td>562.7</td>
</tr>
</tbody>
</table>

Source: From Reference [18], © 1993 Trans Tech Publications.

is a fixed low temperature that is normally, the lowest attainable temperature of the measuring system. Notice that the resonant frequency decreases as the temperature increases. The decrease in resonance frequency occurs because the penetration depth increases with temperature, as given by Eq. (12.25).

The unloaded quality factor of a series resonator, assuming that $G$ in the equivalent circuit model of Figure 12.13 is negligible, is given by [20]

$$Q_0 = \frac{\omega_0 L}{R}, \quad (12.36)$$

FIGURE 12.14  Computed kinetic inductance per unit length as a function of the London penetration depth for coplanar waveguide with aspect ratio as parameter. (From Reference [18], © 1993 Trans Tech Publications.)
FIGURE 12.15 Typical geometry of a linear and meander high-$T_c$ superconducting coplanar waveguide series capacitively coupled resonators. The shaded areas at the end of each ground plane represents the silver contact pads. (From Reference [19], © 1995 IEEE.)
FIGURE 12.16  Schematic showing the flip chip assembly of the superconducting resonator within a microwave package mounted inside a closed-cycle cryo-cooler. (From Reference [19], © 1995 IEEE.)

FIGURE 12.17  Measured normalized resonance frequency as a function of the temperature for a YBa$_2$Cu$_3$O$_{7-x}$ coplanar waveguide resonator. For material characteristics and resonator dimensions refer to data for sample 3/circuit 1 in Tables 12.2 and 12.4. (From Reference [17], © 1993 American Institute of Physics.)
FIGURE 12.18 Measured unloaded quality factor as a function of the temperature for a YBa$_2$C$_3$O$_{7-x}$ coplanar waveguide resonator on a LaAlO$_3$ substrate. For material characteristics and resonator dimensions refer to data for sample 3/circuit 3 in Tables 12.2 and 12.4. The $f_0$ is 6.2 GHz. (From Reference [17], © 1993 American Institute of Physics.)

where

\[ L = \text{total series inductance per unit length} \]
\[ R = \text{series resistance per unit length} \]
\[ \omega_0 = \text{angular frequency at resonance equal to } 2\pi f_0. \]

The quality factor as determined from a practical CPW resonator, is usually the loaded quality factor $Q_L$. At resonance the unloaded quality factor $Q_U$ is related to the loaded quality factor $Q_L$ and the insertion loss $L_0$ in dB through the relation [21]

\[ Q_0 = \frac{Q_L}{1 - 10^{-L_0/20}}. \]  

(12.37)

The measured unloaded quality factor, $Q_0$, for a CPW resonator as a function of the temperature is shown in Figure 12.18. Notice that $Q_0$ decreases as the temperature increases. The reason for the decrease will be evident from the equations in the next section.
12.4.5 Surface resistance of High-\(T_c\) Superconducting Coplanar Waveguide

**Temperature Dependence** The two-fluid model is used in explaining the current flow in high-\(T_c\) superconductors. The model assumes that the total conduction current density \(\vec{J}\) consists of the superconducting current density \(\vec{J}_s\) and the normal electron current density \(\vec{J}_n\). That is,

\[
\vec{J} = \vec{J}_s + \vec{J}_n. \tag{12.38}
\]

The current density \(\vec{J}\) is related to the electric field \(\vec{E}\) through the relation

\[
\vec{J} = \sigma \vec{E}, \tag{12.39}
\]

where \(\sigma\) is the complex conductivity expressed as

\[
\sigma = \sigma_1 - j\sigma_2. \tag{12.40}
\]

The real part of the complex conductivity \(\sigma_1\) is the normal state conductivity of the high-\(T_c\) superconductor determined at \(T = T_c\). The imaginary part of the complex conductivity \(\sigma_2\) is equal to [17].

\[
\sigma_2 = \frac{1}{\omega \mu_0 \lambda^2_{\text{t}}(T)}, \tag{12.41}
\]

where \(\lambda_{\text{t}}(T)\) is the temperature dependent penetration depth given by Eq. (12.25).

From the two-fluid model, the series resistance per unit length, \(R\), of the high-\(T_c\) superconducting CPW is given by [22]

\[
R = \frac{\sigma_1 \omega L_{\text{kinetic}}}{\sigma_2}, \tag{12.42}
\]

where \(L_{\text{kinetic}}\) is the penetration depth dependent kinetic inductance given by Eq. (12.27).

By substituting for \(R\) and \(\sigma_2\) from Eqs. (12.36) and (12.41) into Eq. (12.42) and rearranging the terms, the real part of the complex conductivity \(\sigma_1\) at \(\omega = \omega_0\) is obtained:

\[
\sigma_1 = \frac{L}{\omega_0 \mu_0 Q_0 L_{\text{kinetic}} \lambda^2_{\text{t}}(T)}. \tag{12.43}
\]
Finally, by substituting for $\sigma_1$ from Eq. (12.43) into Eq. (12.23), the surface resistance $R_s$ at $\omega = \omega_0$ is obtained:

$$R_s = \frac{\omega_0 \mu_0 L \lambda_1(T)}{2Q_0 L_{\text{kinetic}}}. \quad (12.44)$$

For our example, the surface resistance obtained from the measurements of the quality factor and the resonance frequency of CPW resonators [17], fabricated on YBa$_2$Cu$_3$O$_{7-x}$ samples of Table 12.2, is summarized in Table 12.4. The results in Table 12.4 show that the lowest achieved value of $R_s$ is about 38 $\mu$Ω/square and 105 $\mu$Ω/square at the temperatures of 10 K and 77 K, respectively, when the frequency is 6.2 GHz. When the $R_s$ values in Table 12.4 are compared with the $J_c$ and $\Delta T_c$ values in Table 12.2, it is observed that $R_s$ increases significantly when $J_c$ is less than 10$^6$ A/cm$^2$ at 77 K and $\Delta T_c$ is greater than 2 K.

**Frequency Dependence** The experimentally determined surface resistance $R_s$ for YBa$_2$Cu$_3$O$_{7-x}$ at 77 K over the frequency range of 5 to 20 GHz [17] is shown in Figure 12.19. For comparison the surface resistance $R_s$ for copper at 77 K is also included. It is observed that at 77 K and 10 GHz, the $R_s$ of YBa$_2$Cu$_3$O$_{7-x}$ is about 60 times lower than that of cooled copper. Furthermore the experimental data points appear to lie on a line that has a quadratic frequency dependence, consistent with Eq. (12.23).
FIGURE 12.19  Measured surface resistance of YBa$_2$Cu$_3$O$_{7-x}$ as a function of frequency at 77 K. (From Reference [17], © 1993 American Institute of Physics.)

12.4.6 Attenuation Constant

The unloaded quality factor $Q_o$ for any transmission line resonator can be expressed as [23]

$$\frac{1}{Q_o} = \frac{1}{Q_c} + \frac{1}{Q_d} + \frac{1}{Q_r},$$

(12.45)

where

$Q_c =$ quality factor due to conductor losses

$Q_d =$ quality factor due to dielectric losses

$Q_r =$ quality factor due to radiation losses

The radiation losses can be minimized by providing a metal shield all round the CPW resonator. The quality factor due to dielectric losses is

$$\frac{1}{Q_d} \approx \tan \delta,$$

(12.46)
where \( \tan \delta \) is the loss tangent of the substrate material. The loss tangent for both MgO and LaAlO\(_3\) at 77 K is on the order of \(10^{-4}\). Hence the dielectric losses are negligible. Therefore the unloaded quality factor is

\[
Q_0 \approx Q_c.
\]

(12.47)

The quality factor due to conductor losses is related to the attenuation constant due to conductor losses, \( \alpha_c \), through the relation [23]

\[
Q_c = \frac{\pi}{\alpha_c \lambda_g},
\]

(12.48)

where \( \lambda_g \) is the guide wavelength and is equal to twice the resonator length for the fundamental mode. For example, the experimentally determined unloaded quality factor of the CPW resonator, indicated as sample 3/circuit 3 in Table 12.4, is about 1200 at 77 K [24]. The corresponding attenuation constant \( \alpha_c \) from Eq. (12.48) is about 1.8 dB/m at 6.2 GHz. This film has a surface resistance of about 105 \( \mu \Omega/\text{square}\). Closed-form equations to compute the attenuation constant of superconducting CPWs are given in Section 8.6.

12.5 FERROELECTRIC COPLANAR WAVEGUIDE CIRCUITS

Recently there has been renewed interest in tunable microwave components based on thin film ferroelectric materials for applications at room as well as cryogenic temperatures. The materials that are commonly used at these temperatures are barium strontium titanate and strontium titanate, respectively. In this section we focus on the dielectric characteristics of these materials and their applications in microwave phase shifters for phased array antennas.

12.5.1 Characteristics of Barium Strontium Titanate Thin Films

**Dielectric Characteristics as a Function of Temperature and Voltage** Thin films of barium strontium titanate, \( \text{Ba}_{1-x}\text{Sr}_x\text{TiO}_3 \), are experimentally observed to have complex permittivity, \( \hat{\varepsilon} \), which is a function of both temperature and voltage [25]. The complex permittivity can be expressed as [26]

\[
\hat{\varepsilon} = \varepsilon' - j\varepsilon'',
\]

(12.49)

where \( \varepsilon' \) and \( \varepsilon'' \) are the real and imaginary parts, respectively. The loss tangent of the material is defined as [26]

\[
\tan \delta = \frac{\omega \varepsilon'' + \sigma}{\omega \varepsilon'},
\]

(12.50)
where $\omega$ and $\sigma$ are the angular frequency and conductivity, respectively. The conductivity is usually considered to be negligibly small. Hence $\tan \delta$ can be approximated as

$$\tan \delta \approx \frac{\varepsilon''}{\varepsilon'}.$$  \hspace{1cm} (12.51)

It is a common practice to specify, at microwave frequencies, the dielectric property of materials by the real part of the permittivity, $\varepsilon' = \varepsilon_r \varepsilon_0$, where $\varepsilon_r$ is the relative permittivity or dielectric constant, and by the loss tangent, $\tan \delta$. Often it is preferable to choose a material with low $\tan \delta$ in order to minimize power dissipation.

The $\varepsilon_r$ and $\tan \delta$ values of $\text{Ba}_{1-x}\text{Sr}_x\text{TiO}_3$ are extracted from capacitance measurements. For example, in [25] an interdigital capacitor fabricated over a 0.5 $\mu$m thick $c$-axis oriented $\text{Ba}_{0.5}\text{Sr}_{0.5}\text{TiO}_3$ film on a single crystal (001) $\text{LaAlO}_3$ substrate is used to estimate these values. Room temperature (300 K) measurements resulted in $\varepsilon_r$ and $\tan \delta$ values of 1430 and 0.007 with no externally applied electric field, and 960 and 0.001 with an externally applied electric field intensity of 2.33 V/$\mu$m, respectively. The single crystal (001) $\text{LaAlO}_3$ ($\varepsilon_r = 24$) is selected as the substrate material, first, to ensure good lattice match with the $\text{Ba}_{0.5}\text{Sr}_{0.5}\text{TiO}_3$ thin film and thus minimize interfacial strain, and second, for its low loss tangent, $\tan \delta$, which is typically $<10^{-5}$. The $\varepsilon_r$ and $\tan \delta$ characteristics of this film are illustrated in Figure 12.20a and b over a wide range of temperature and voltage values.

**Dependence of Dielectric Constant on Film Thickness** The $\varepsilon_r$ value of $\text{Ba}_{1-x}\text{Sr}_x\text{TiO}_3$ thin films usually depends on the film thickness, $t$. For $t < 0.2$ $\mu$m, the thinner the film, the smaller is the $\varepsilon_r$ value. However, the $\varepsilon_r$ value becomes less thickness dependent when $t > 0.5$ $\mu$m [25].

**Dielectric Tunability** The dielectric tunability (%) at a fixed temperature is defined as [27]

$$\text{Tunability} = \left(\frac{\varepsilon_{r,0V} - \varepsilon_{r,V\text{-applied}}}{\varepsilon_{r,0V}}\right) \times 100,$$  \hspace{1cm} (12.52)

where $\varepsilon_{r,0V}$ and $\varepsilon_{r,V\text{-applied}}$ are the dielectric constant at zero-bias voltage and at the applied bias voltage, respectively. For the $\text{Ba}_{0.5}\text{Sr}_{0.5}\text{TiO}_3$ thin film with characteristics as discussed in the previous section, the calculated tunability at room temperature is 33 percent when an electric field intensity of 2.33 V/$\mu$m is applied across the sample [25].

**Curie Temperature** The Curie temperature, $T_c$, that is, the temperature below which a material is ferroelectric and above which the material is paraelectric,
is an important parameter. The $T_c$ for $\text{Ba}_{1-x}\text{Sr}_x\text{TiO}_3$ thin films with $x = 0.4$ is about 275 K for a typical film thickness of 0.5 $\mu$m deposited on a single-crystal $\text{LaAlO}_3$ [27]. Often tunable microwave components that utilize this material for tunability operate above the Curie temperature, typically at room temperature. It is therefore worthwhile to mention that although at room temperature, the $\text{Ba}_{0.6}\text{Sr}_{0.4}\text{TiO}_3$ material operates in the paraelectric regime, it is customary for researchers in this field to refer to the material as ferroelectric.
12.5.2 Characteristics of Strontium Titanate Thin Films

Dielectric Characteristics as a Function of Temperature and Voltage

The \( \varepsilon_r \) and \( \tan\delta \) values of strontium titanate (SrTiO\(_3\)) thin film are extracted from capacitance measurements [28]. The capacitor used in these experiments consists of a SrTiO\(_3\) thin film sandwiched between two parallel metal plates. The capacitor is fabricated on a single-crystal LaAlO\(_3\). The top and bottom plates of the capacitor are made from gold and strontium ruthenium oxide (SrRuO\(_3\)), respectively. It has been experimentally observed that the interfacial effects between the film and the electrodes become small when the film thickness is large [28]. Hence the thickness of the SrTiO\(_3\) film is chosen as 2.5 \( \mu \)m [28]. Further, if the lattice constants of the film and the bottom plate are matched, the lattice mismatch-induced stress is reduced. Hence, the bottom plate is fabricated from SrRuO\(_3\) [28], since the lattice constant of SrRuO\(_3\) and SrTiO\(_3\) are very well matched. The small interfacial effects and the reduced stress contribute to enhancing the dielectric properties of the film so that they approach those of a bulk single crystal material.

The \( \varepsilon_r \) and \( \tan\delta \) extracted from the measured capacitance of the parallel plate structure above [28] are presented as a function of the temperature in Figure 12.21a and b. These results corresponds to the case where the externally applied dc electric field intensity in zero. It is observed from Figure 12.21a that \( \varepsilon_r \) increases from about 300 at room temperature to about 930 at 4 K. On the other hand, it is observed from Figure 12.21b that \( \tan\delta \) is on the order of \( 1 \times 10^{-3} \) and lower across the temperature range of 150 to 300 K. Below 150 K, \( \tan\delta \) increases and approaches \( 6 \times 10^{-3} \) at 4 K. Further, two relaxation peaks occur in the \( \tan\delta \) characteristics at about 25 and 65 K, respectively.

The \( \varepsilon_r \) and \( \tan\delta \) as a function of the externally applied dc electric field intensity, with the temperature held constant, is shown in Figure 12.22. The figure indicates the presence of hysteresis in both \( \varepsilon_r \) and \( \tan\delta \), which is due to either ferroelectric ordering or interfacial space charge [28].

Dielectric Tunability and Figure of Merit

The dielectric tunability of the film is given by Eq. (12.52). The measured tunability of SrTiO\(_3\) film of thickness 2.5 \( \mu \)m over the temperature range of 4 to 100 K is about 70 percent when the applied electric field intensity is in the range of 40 to 50 V/\( \mu \)m.

The figure of merit is the ratio of the tunability to the loss and is expressed as [28]

\[
K = \frac{(\varepsilon_{r,0V} - \varepsilon_{r,V\text{-applied}})}{\varepsilon_{r,0V}} \cdot \frac{1}{(\tan\delta)_{\text{max}}},
\]

(12.53)

where \((\tan\delta)_{\text{max}}\) is the maximum loss under all the applied electric field intensities.

The measured figure-of-merit for the SrTiO\(_3\) film of thickness 2.5 \( \mu \)m is close to 200 up to a temperature of 70 K and then increases to 400 at a temperature of 120 K. The figure-of-merit remains at this value until the temperature
FIGURE 12.21 Measured dielectric characteristics of 2.5 μm thick SrTiO₃ film on a single crystal (001) LaAlO₃ substrate at 1 KHz as a function of temperature: (a) Dielectric constant; (b) loss tangent. (From reference [28], © 1998 American Institute of Physics.)

exceeds 200 K and then rapidly decreases. Hence SrTiO₃ thin films are useful for tunable microwave devices operating at temperatures above 70 K.

12.5.3 Grounded Coplanar Waveguide Phase Shifter

The layout of a (Ba,Sr)TiO₃ coplanar waveguide Ka-band phase shifter [29] is shown in Figure 12.23. The phase shifter consists of a uniform grounded
FIGURE 12.22  Measured dielectric characteristics of 2.5 μm thick SrTiO$_3$ film as a function of the applied dc electric field intensity at a fixed temperature of 190 K. (From reference [28], © 1998 American Institute of Physics.)

coplanar waveguide of length $L$ with tapered impedance matching transformers of length $L_1$ at either ends. The circuit is fabricated on a multilayer dielectric that consists of a (Ba,Sr)TiO$_3$ thin film deposited over a MgO substrate. The cross section of the phase shifter is shown in Figure 12.24.

The principle of operation of the phase shifter is based on a change in the propagation constant of the grounded coplanar waveguide because of a change

FIGURE 12.23  Schematic showing the layout of the Ka-band phase-shifter: $L = 6$ mm, $L_1 = 3$ mm.
in the dielectric constant of the (Ba,Sr)TiO$_3$ film with an externally applied dc bias voltage. The measured phase characteristics, at a fixed frequency of 31.34 GHz, as a function of the bias voltage [29] is shown in Figure 12.25. It is observed that the phase shift increases almost linearly from 0 to 370° as the bias voltage is varied from 0 to 350 Volts. The measured insertion loss is in the range of 4.0 to 6.0 dB over the whole range of bias voltages.

**FIGURE 12.24** Schematic showing the cross-section of the phase-shifter: $h = 500$ $\mu$m, $h_1 = 8$ $\mu$m, $S = 60$ $\mu$m, $W = 40$ $\mu$m, $\varepsilon_r = 9.7$, $\varepsilon_{r_1}$ is bias dependent.

**FIGURE 12.25** Measured phase characteristics as a function of the bias voltage at a fixed frequency of 31.34 GHz. (From reference [29], © 2000 Gordon and Breach Science Publishers.)
12.6 COPLANAR PHOTONIC-BANDGAP STRUCTURE

Photonic-bandgap structures are artificial electromagnetic crystals having a spatially periodic dielectric constant with a lattice parameter comparable to the wavelength of the electromagnetic wave. When suitably designed, a photonic-bandgap structure is capable of suppressing the propagation of electromagnetic wave along certain directions over a band of frequencies. The first experimental demonstration of a three-dimensional photonic-bandgap was by Yablonovitch et al. [30]. Since that time several other photonic-bandgap structures have been investigated [31, 32], and applications such as high-impedance ground plane structures for antennas have been demonstrated [31]. This section is devoted to a two-dimensional photonic-bandgap structure that is compatible with coplanar waveguides.

12.6.1 Nonleaky Conductor-Backed Coplanar Waveguide

A conductor-backed coplanar waveguide (CBCPW) can support, besides the dominant CPW mode, two other parasitic modes, namely the parallel plate mode and the microstrip mode as discussed in Sections 3.4 and 4.3, respectively. These parasitic modes, when excited, couple power from the dominant coplanar waveguide mode to a leaky mode. When compared to a conventional coplanar waveguide (CPW), the loss of power through leakage is responsible for the higher transmission loss in a CBCPW.

A nonleaky conductor backed coplanar waveguide [33] is schematically illustrated in Figure 12.26. In this transmission line the top ground planes on either side of the center strip conductor are replaced by two-dimensional photonic-bandgap lattice. The lattice consists of a periodic array of square metal pads with recess and interconnected by narrow lines. An unit cell of the lattice is shown in the inset in Figure 12.26. Over a predetermined frequency band, the photonic-bandgap lattice behaves as a perfect magnetic conductor (PMC), and has a band-stop-type characteristic, as will be shown in the sections that follow.

**Effective Surface Impedance Model** The unit cell is modeled [34] along the x-direction as a transmission line of length equal to the substrate thickness $h$. The propagation constant on this line is denoted as $\beta$. Furthermore, to take into account the presence of a lower ground plane, the line is terminated at the bottom by a perfect electric conductor (PEC). In the lattice the gaps between adjacent pads and the interconnecting lines between the pads give rise to a capacitance $C$ and an inductance $L$ [34]. Hence the transmission line is terminated at the top by a parallel equivalent circuit consisting of a capacitor $C$ and an inductor $L$. The equivalent circuit model is shown in Figure 12.27. Based on this model the surface of a photonic-bandgap lattice is assigned a sheet impedance that is equal to the impedance of the parallel equivalent
FIGURE 12.26 Schematic of nonleaky conductor backed coplanar waveguide with two-dimensional photonic bandgap structure in the top ground planes: \( h = 0.635 \) mm, \( \varepsilon_r = 10.2 \), \( S = 2.032 \) mm, \( W = 0.508 \) mm, \( a = 3.048 \) mm, \( b = 2.7432 \) mm, \( d = 0.3048 \) mm, \( g = 0.3048 \) mm, \( e = 0.762 \) mm.

circuit, and is expressed as

\[
Z = \frac{j\omega L}{1 - \omega^2 LC} \tag{12.54}
\]

This equation suggests that the surface impedance is very high at the resonant frequency \( \omega_0 \) given by

\[
\omega_0 = \frac{1}{\sqrt{LC}} \tag{12.55}
\]

Consequently at \( \omega_0 \) the surface behaves as a perfect magnetic conductor (PMC). This type of impedance characteristic makes the photonic-bandgap
structure reject a predetermined band of frequencies. Over this high-impedance surface or ground plane, the tangential electric and magnetic fields have an antinode and a node, respectively. Furthermore, from Eq. (12.54), the surface impedance below and above $\omega_0$ is inductive and capacitive, respectively. This feature is exploited in the experimental characterization of a photonic-bandgap structure as explained in the next section.

**Photonic-Bandgap Structure Phase Characteristics** The perfect magnetic conductor (PMC) behavior of the photonic bandgap structure can be verified, by illuminating the surface with an uniform plane wave and observing the phase of the reflected wave [34]. When the frequency of the incident wave is far below or above $\omega_0$, the surface according to Eq. (12.54) has either an inductive or a capacitive impedance. Consequently the phase of the reflected wave from this surface, depending on frequency being greater than or less than $\omega_0$, is either $\pi$ or $-\pi$. At $\omega_0$ the surface has a very high impedance, and therefore the phase of the reflected wave is zero. The phase falls within $+\pi/2$ and $-\pi/2$ when the magnitude of the surface impedance exceeds the impedance of free space.

**Measured Phase Characteristics of Photonic-Bandgap Structure** The experimental setup shown in Figure 12.28 is used to measure the phase of the reflected signal from the surface of the photonic-bandgap structure. The phase of the reflection coefficient is initially measured with a perfect electric conductor (PEC) in place of the photonic-bandgap structure. Next the measurement
FIGURE 12.28 Experimental setup for measuring the phase of the reflection coefficient of a surface.

is repeated with the photonic-bandgap structure in place of the PEC. The difference in the phase for the two settings is now calculated as a function of the frequency. A typical phase characteristic is graphically illustrated in Figure 12.29 for the photonic-bandgap structure shown in Figure 12.26. The photonic-bandgap structure in this experiment [34] is a $40 \times 60$ array with a period $a$ equal to 3.048 mm. The resonant frequency of the photonic-bandgap structure is about 14.5 GHz [34].

**Measured Transmission Loss of Nonleaky Conductor-Backed Coplanar Waveguide** The measured transmission losses [33] as a function of the frequency for nonleaky CBCPW, conventional coplanar waveguide (CPW), and CBCPW are presented in Figure 12.30. It is observed that because of the absence of parasitic parallel plate modes, the transmission loss in the case of CPW is the lowest. In the case of CBCPW, significant amount of power is lost in the form of leakage, and hence the transmission loss is very high. On the other hand, the photonic-bandgap structure from which the nonleaky CBCPW ground planes are constructed has a band-stop characteristic over the frequency range of 9 to 14 GHz [33]. Consequently over this frequency range the propagation of the parasitic parallel plate mode is suppressed, and the transmission loss of the nonleaky CBCPW approaches that of the CPW.
FIGURE 12.29 Measured phase difference between the reflection coefficients of a photonic-bandgap surface and a perfect electrically conducting surface. (From reference [34], © IEEE 1999.)

FIGURE 12.30 Comparison of measured transmission coefficient $S_{21}$ of nonleaky conductor-backed coplanar waveguide with conventional CPW and CBCPW. (From reference [33], © IEEE 1999.)
12.7 COPLANAR WAVEGUIDE PATCH ANTENNAS

In this section the characteristics of patch antennas with coplanar waveguide feed are presented. The feed system in these antennas is directly coupled, electromagnetically coupled, or aperture coupled to the patch. The advantages of using coplanar waveguide in the feed are as follows: First, it allows series as well as shunt mounting of components without the use of via holes. Second, it allows mounting of MMIC circuits such as phase shifters using solder bumps and flip chip techniques.

12.7.1 Grounded Coplanar Waveguide Patch Antenna

A grounded coplanar waveguide (GCPW) patch antenna and feed [35] are shown in Figure 12.31. The patch is formed by widening the center strip conductor of the GCPW. The feed is a short length of GCPW. The GCPW is excited at the end opposite the patch by a surface launch connector. The center conductor of the connector passes through the dielectric substrate and is attached to the GCPW center strip conductor. The outer conductor of the connector is attached to the GCPW lower ground plane. This type of launcher efficiently transitions the coaxial TEM mode to the GCPW quasi-TEM mode. The upper and lower ground planes of the GCPW are electrically connected by a series of shorting pins. These pins suppress the excitation of the parasitic parallel plate mode between the upper and lower ground planes. The upper ground planes are electrically connected by a bond wire to suppress the excitation of the parasitic coupled slotline mode.

The patch operates in the fundamental mode, when the periphery is approximately one wavelength, that is, when the distance $A-B-C-D$ in Figure 12.31 is half a wavelength or 180°. The fundamental mode produces a linearly polarized radiation pattern directed normal to the upper ground planes. The polarization is parallel to the line $AD$. The electric field lines in the slot region between the patch and the ground planes are also shown in the figure. The radiation from the patch takes place mainly from sides $CE$ and $FB$. Sides $BC$ and $EF$ contribute very little to the radiation, since the fields go to zero and reverse direction at the midpoints of these sides.

The measured characteristics [35] for a linearly polarized single patch show that the $E$- and $H$-plane 3 dB beamwidths are typically about 110° and 80°, respectively. The gain of the antenna is about 3.5 dBi, and the 3:1 VSWR bandwidth is about 6.5 percent at 2.3 GHz.

When the periphery of the patch is two wavelengths, the next higher-order mode is excited. This mode gives rise to a linearly polarized pattern with a null normal to the patch [35]. This mode can be useful in generating high-gain patterns with tilted beams [35]. A circular polarization is produced by feeding a square patch on two adjacent sides through a 90° hybrid as explained in [35] and [36].
FIGURE 12.31 Grounded coplanar waveguide patch antenna operating in the fundamental mode.
12.7.2 Patch Antenna with Electromagnetically Coupled Coplanar Waveguide Feed

In this type of feed, the coplanar waveguide (CPW) and the patch antenna are located on opposite sides of a dielectric substrate [37, 38]. The RF power from the CPW feed is electromagnetically coupled to the patch antenna. The coupling takes place from the terminated end of the CPW feed. The termination can either be a modified short circuit or an open circuit as illustrated in Figure 12.32a and b. The short circuit gives rise to excess inductance at the termination as discussed in Section 9.3, and therefore the coupling is termed as inductive. Through similar reasoning, the coupling from an open circuit is
**TABLE 12.5** Measured Performance of Patch Antenna with Electromagnetically Coupled Coplanar Waveguide Feeds

<table>
<thead>
<tr>
<th>Parameters</th>
<th>Inductively Coupled</th>
<th>Capacitively Coupled</th>
</tr>
</thead>
<tbody>
<tr>
<td>Center frequency, GHz</td>
<td>4.67</td>
<td>4.3</td>
</tr>
<tr>
<td>Slot length, $L_s$ (mm)</td>
<td>16.0</td>
<td>14.0</td>
</tr>
<tr>
<td>$-10.0$ dB return loss bandwidth, percent</td>
<td>3.5</td>
<td>2.8</td>
</tr>
<tr>
<td>$3$ dB beamwidth, degrees</td>
<td></td>
<td></td>
</tr>
<tr>
<td>$H$-Plane</td>
<td>70</td>
<td>80</td>
</tr>
<tr>
<td>$E$-Plane</td>
<td>67</td>
<td>--</td>
</tr>
<tr>
<td>Front-to-Back Ratio, dB</td>
<td>10</td>
<td>9.5</td>
</tr>
</tbody>
</table>

Note: $S = 3.0$ mm, $W = 0.06$ mm, $h = 1.58$ mm, $e_r = 2.22$, $L_1 = 18.3$ mm, $W_1 = 22.0$ mm, $W_c = 1.0$ mm.

termed capacitive. In the antennas discussed in [37], the short-circuit and the open-circuit terminations are located symmetrically above the center of the patch. The mode that is excited in the cavity formed by the patch is the TM$_{10}$ mode. The circuit dimensions and the measured performance [37] of the patch antenna with inductive and capacitive coupling are presented in Table 12.5. The radiation from the patch is linearly polarized and parallel to side of length $L_1$.

### 12.7.3 Coplanar Waveguide Aperture-Coupled Patch Antenna

Aperture-coupled feeding is attractive because of certain advantages, such as no physical contact between the feed and radiator, wider bandwidth, and better isolation between antennas and the feed network. Furthermore, aperture-coupled feeding allows independent optimization of antennas and feed networks by using substrates of different thickness or permittivity. In this section aperture-coupled patch antennas with coplanar waveguide feed are described.

**Grounded Coplanar Waveguide Aperture-Coupled Patch Antenna** A grounded coplanar waveguide (GCPW) aperture-coupled patch antenna is schematically illustrated in Figure 12.33. In the experimental antenna [39], the patch and the GCPW feed structure, with a series gap $L_s$ in the center conductor, are fabricated on separate substrates, and the aperture is etched in the common ground plane. The aperture is located directly above the series gap. Thus microwave power is coupled from the GCPW feed line to the patch through the aperture. In the experimental antenna, the patch is displaced by about 0.32 cm from the center of the aperture and also, the GCPW stub length $L$ is adjusted to provide the best impedance match to the feed line. The radiation from the antenna is linearly polarized with the plane of polarization parallel to the patch side of dimension $a$. 
The measured return loss [39] is shown in Figure 12.34. The return loss is about $-16.9\, \text{dB}$ at $12.65\, \text{GHz}$. Typical measured $E$- and $H$-plane radiation patterns [39] for the GCPW aperture-coupled patch antenna is shown in Figure 12.35\textit{a} and \textit{b}. The patterns look fairly symmetrical and exhibit a 3-dB beamwidth of about $60^\circ$ and $50^\circ$ in the $E$- and $H$-plane, respectively. The measured front-to-back ratio is about $14.0\, \text{dB}$, which is typical for an aperture coupled patch antenna. Last, in [40] an aperture-coupled patch antenna with series slotline stubs in the top ground planes, instead of a series gap in the center strip conductor, is demonstrated. The characteristics of this antenna is similar to that presented above.

**Finite Width Coplanar Waveguide Aperture-Coupled Micromachined Patch Antenna** Printed antennas fabricated on high dielectric constant substrates suffer from excess surface wave losses and lower radiation efficiency [41]. The
surface wave losses can be reduced by decreasing the substrate thickness, typically the substrate thickness should be less than $\lambda_d/10$, where $\lambda_d$ is the wavelength in the dielectric. For example, in silicon ($\varepsilon_r = 11.7$) at 94.0 GHz this thickness corresponds to about 100 $\mu$m. The radiation efficiency can be improved by locally removing the substrate using micromachining technique and synthesizing in a low dielectric constant region around the antenna.

**FIGURE 12.34** Measured return loss as a function of the frequency for feed structure with series gap and a dumbbell-shaped aperture.

**FIGURE 12.35** Measured radiation patterns for the grounded coplanar waveguide aperture-coupled patch antenna: (a) $E$-plane; (b) $H$-plane.
FIGURE 12.36 A W-band finite width coplanar waveguide aperture-coupled micromachined patch antenna: (a) Schematic $h_1 = 200\ \mu m$, $h_2 = 100\ \mu m$, $h_a = 150\ \mu m$, $L = 800\ \mu m$, $W = 800\ \mu m$; (b) cross-section, $L_m = 160\ \mu m$, $W_s = 50\ \mu m$, $\varepsilon_r = 11.7$. 
FIGURE 12.37  Schematic of coplanar waveguide with finite-width ground plane-to-microstrip transition: \( S_1 = 30 \, \mu m, \, W_1 = 29 \, \mu m, \, G_1 = 45 \, \mu m, \, S_2 = 40 \, \mu m, \, W_2 = 24 \, \mu m, \, G_2 = 106 \, \mu m, \, W_m = 74 \, \mu m, \, L = 280 \, \mu m. \)

In Figure 12.36a and b an aperture-coupled micromachined microstrip antenna [41] is schematically illustrated. The feed network and the antenna are fabricated on two separate silicon wafers and stacked vertically. The feed network is a coplanar waveguide with finite width ground planes (FW-CPW). The antenna is a metal patch suspended over a cavity and micromachined in the silicon wafer. Depending on the cavity depth, the quasi-static effective dielectric constant in the region of the patch is in the range of 2.8 to 3.9 [41].

The feed line transitions from a FW-CPW to a microstrip line and couples power to the patch through an \( H \)-shaped aperture in the common ground plane located between the two wafers. The transition is shown in Figure 12.37. The microstrip line is orthogonal and symmetrically located with respect to the aperture as shown in Figure 12.38. It is observed in [41] that a \( H \)-shaped aperture couples power more efficiently than a conventional rectangular aperture. The real and the imaginary parts of the antenna input impedance are dependent on the slot length \( L_s \) and the microstrip line extension \( L_m \) [41].

The measured return loss of the antenna is about \(-18.0\, \text{dB} \) at 94 GHz with a 2:1 VSWR bandwidth of 1 percent. The radiation from the antenna is linearly polarized with the plane of polarization parallel to the patch side of dimension \( L \). The antenna has a radiation efficiency of \( 58 \pm 5 \) percent, as determined from radiometric measurements. The measured crosspolarization level is below \(-20.0\, \text{dB} \) and the front-to-back ratio is below \(-10.0\, \text{dB} \) in both \( E \)- and \( H \)-planes [41].
FIGURE 12.38  Schematic illustrating the integration of the microstrip line with the patch antenna: $L_h = 250 \, \mu m$, $W_s = 50 \, \mu m$, $L_m = 160 \, \mu m$, $L_s = 500 \, \mu m$, $L = 800 \, \mu m$, $W = 800 \, \mu m$.

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